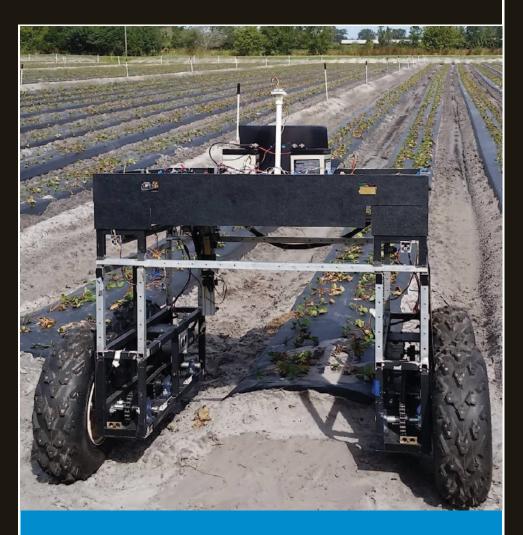
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Cover Image: An Approximated, Control Affine Model for a Strawberry Field Scouting Robot Considering Wheel–Terrain Interaction by Pablo Menendez-Aponte, Xiangling Kong and Yunjun Xu. Figure 5 'DDAGR in front of a strawberry bed in a commercial strawberry orchard.'