Delineation of a catchment boundary using velocity and elevation measurements

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ABSTRACT. The determination of catchment boundaries is a major source of uncertainty in net balance studies on large ice sheets. Here, a method for defining a catchment boundary is developed using new measurements of ice-surface velocity and elevation near the Ice Stream B/C boundary in West Antarctica. An objective method for estimating confidence in the catchment boundary is proposed. Using elevation data, the resulting mean standard deviation in boundary location is 13 km in position or 6000 km² in area. Applying a similar uncertainty to both sides of the Ice Stream B catchment results in a catchment-area uncertainty of 9%. Much larger uncertainties arise when the method is applied to velocity data. The uncertainty in both cases is primarily determined by the density of field measurements and is proportionally similar for larger catchment basins. Differences in the position of the velocity-determined boundary and the elevation-determined boundary probably result from data sampling. The boundary positions determined here do not support the hypothesis that Ice Stream B captured parts of the Ice Stream C catchment.

INTRODUCTION

The location of catchment boundaries is a major uncertainty in many mass-balance studies. In the case of Ice Stream B, West Antarctica, the poor definition of lateral boundaries contributes largely to the weak confidence in the mass-balance estimate (Whillans and Bindschadler, 1988). Catchment boundaries may be determined from measurements of surface elevation, surface velocity or a combination of both. Until now, there has been no objective assessment of the confidence that can be placed on boundaries so determined or the best strategy of locating a catchment boundary using field measurements.

Fieldwork was conducted in West Antarctica in an effort to locate precisely the boundary between ice ultimately flowing into Ice Stream B and that flowing into Ice Stream C (Fig. 1). Measurements of surface elevation and surface velocity were collected near the boundary between the catchments of Ice Streams B and C.

Particular interest in this region arises because past migration of this boundary has been suggested as a means by which Ice Stream B "captured" part of the Ice Stream C catchment (Rose, 1979; Shabtaic and Bentley, 1987). Determination of the present boundary position would be an important test of the capture hypothesis.

This contribution determines the catchment boundary using field measurements of surface velocity and surface elevation. The major innovation is the development of an objective method for tracking of uncertainties, leading to estimates of confidence in the calculated boundary positions.

DATA COLLECTION

During field campaigns between 1984 and 1991, sites on Ice Streams B and C and in their catchments were surveyed https://doi.org/10.3189/1998AoG27-1-140-144 Published online by Cambridge University Press 140 using Transit ("Doppler") and global positioning system (GPS) satellite tracking receivers (Fig. 1). Tracking data are post-processed to obtain precise measurements of position and elevation. Details on Transit survey methods and data reduction are described by McDonald and Whillans (1988). Similar methods were employed in the GPS work. Most sites were visited at least twice, in order to determine the motion of a surface marker. For sites visited more than twice, velocities are calculated from positions that yield the best



Fig. 1. Topographic map and measured surface velocities in the upstream and catchment regions of Ice Streams B and C. Inset shows study area. Stippled regions are major shear margins according to Shabtaie and others (1987). Contour interval is 100 m.

precision in velocity. The standard error in horizontal and vertical position at most field sites is $\leq 1 \text{ m}$. The average time interval between surveys is 3.0 years. This leads to a mean uncertainty in measured velocities of about 0.4 m a⁻¹.

CATCHMENT-BOUNDARY DETERMINATION

A catchment boundary is defined by the flowline that passes into neither drainage outlet (Ice Stream B or C) but instead terminates at its down-glacier end in the nearly stagnant region between outlets (inter-stream ridge B/C). This special flowline may be calculated using measurements of surface elevation or surface velocity. First, we use measured surface velocities, and second elevations.

There are several principles involved in the use of discrete data to define a catchment boundary. First, data sampling is taken to be adequate such that the direction of ice flow varies in a smooth and continuous manner between measurement sites. Faults, such as those that occur at ice-stream shear margins, are not considered important in the catchment area. Secondly, flow is taken to be parallel to present-day velocity vectors or perpendicular to elevation contours. The last contention is attested to by the Byrd Station Strain Network (BSSN), West Antarctica (Whillans, 1979), where mean flow directions are perpendicular to elevation contours. Thirdly, in the use of velocity measurements, the direction of ice flow measured at the surface is considered to represent the depthaveraged flow direction. Support for this contention is also provided by the BSSN (Whillans, 1977, 1979). Calculated balance speeds along the BSSN vary consistently with measured surface speeds. This indicates little or no divergence between the flow direction at the surface and the flow direction at depth. These are the concepts adopted here for the purpose of catchment-boundary determination.

In the present work, calculations begin at a stagnant point between two catchment outlets. Directions ofice motion interpolated from field measurements are used to progressively calculate a flowline up-glacier. Uncertainties and a correlation distance in these uncertainties are taken into account. Multiple flowlines are calculated in which interpolated quantities are randomly varied according to their uncertainties. The result is a suite of possible flowlines. The distribution of this suite of flowlines determines a most probable boundary location and an estimate of confidence in that location.

MEASUREMENT UNCERTAINTIES

The standard error of measurement in the horizontal component of velocity, σ_u , is linked to the standard errors in horizontal position from the first and second surveys and the time interval between surveys, Δt :

$$\sigma_{\rm u} = \sqrt{\frac{\sigma_{\rm h1}^2 + \sigma_{\rm h2}^2}{\Delta t}}.$$
 (1)

Standard errors σ_{h1} and σ_{h2} are formal errors in the calculation of position and are primarily due to uncertainties in the satellite orbits. The uncertainty in the direction of ice motion at measured sites is

$$\arctan \frac{\sigma_u}{u}$$
 (2)

where u is the measured speed. The mean value of this uncertainty is 1.4° for the present dataset.

Formal measurement uncertainties in elevation are about 2 m for Transit work and 1 m for GPS work.

SHORT-SCALE FLUCTUATIONS

Point measurements of ice-flow direction may not represent the regional value due to ice flow around basal obstacles and over resistive sites. Such fluctuations in flow direction are observed along the 160 km long BSSN (Fig. 2). Whillans and Johnsen (1983) attribute these small-scale fluctuations to variations in basal relief and basal friction. There are directional fluctuations on a scale of 10–20 km as well as on a larger scale of 20 to > 50 km. The large-scale trend is described by a third-order polynomial fit. Fluctuations from this trend indicate a standard deviation in ice-flow direction of 1.0°. This last value is an estimate for the "noise" in flow direction due to localized subglacial effects.



Fig. 2. Ice-flow direction along the BSSN, West Antarctica. Zero degrees is roughly parallel to the strain network axis, oriented in a northeast-southwest direction.

Similarly, point measurements of elevation are influenced by where on a surface undulation the measurement is made. Along the BSSN, deviations from the mean surface are near 0 at the ice divide and as much as 65 m 160 km downslope. The mean fluctuation from the surface is 7.0 m.

Added quadratically, uncertainties due to measurement and local-scale fluctuations contribute a net standard deviation in flow direction of 1.7° for velocity measurements and 3.5° for elevation measurements. These combined uncertainties are negligible relative to the uncertainty associated with large-scale effects, and are neglected henceforth.

LARGE-SCALE FLUCTUATIONS

In the current work, the uncertainty due to large-scale fluctuations is dominant. The large-scale (20 to >50 km) uncertainty at any location depends on how well the regional flow direction is sampled by the data and approximated during data interpolation. The long-distance fluctuation in flow direction along the BSSN, due to velocity and elevation changes, is about 7°. However, the BSSN is too restrictive a sample to provide a meaningful measure in the current work.

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A simple model is that the uncertainty in the large-scale flow direction, designated $\Delta \theta$, increases as data "sparsity", designated *D*, increases. More specifically, the distribution of possible $\Delta \theta$ values for any *D* is random, but with a standard deviation that increases as a linear function of *D*.

The "cross-correlation" or "jackknife" technique (Swan and Sandilands, 1995) is used to estimate how well largescale variations in ice-flow direction are sampled by field measurements and modeled by the interpolator. For a set of n data values, the interpolator's ability to accurately predict the value at a new location (n + 1), is considered the same as its ability to predict the value at location n from a set of (n - 1) data values. For a test location, k, the data value is withheld during interpolation of the full dataset. After interpolation, the value predicted by the interpolator at the test location is compared with the true, withheld value at that location. The difference between the two is

$$\Delta \theta_k = |\theta_{k \text{ actual}} - \theta_{k \text{ interpolated}}| \tag{3}$$

in which θ_{k_actual} is the direction of ice flow obtained from field measurements at location k, and $\theta_{k_interpolated}$ is the interpolated value at k when the true value has been withheld from the dataset. The distribution of $\Delta \theta_k$ values for locations having a similar degree of data sparsity is taken as a measure of uncertainty in flow direction for that degree of data sparsity.

A measure of data sparsity at a location is given by

$$D_{k} = \left[\frac{1}{n-1}\sum_{i=1}^{n} \left(\frac{1}{D_{ki}^{m}}\right)\right]^{-\frac{1}{m}} \quad (i \neq k, \ m \ge 1) \qquad (4)$$

where D_{ki} is distance from the test location, k, to the *i*th measurement site, and n is the number of values in the dataset. D_k is small in regions of closely spaced data and large in regions of widely spaced data. Tests were conducted for m in the range 1–3. The results are similar to one another. For further analysis, a value of m = 1 is used.

No direct physical significance can be attached to the scale of D_k . While distant values contribute very little to the summation in Equation (4), they affect the value of D_k through the factor $[1/(n-1)]^{-1/m}$. In this case *n* is fixed, so D_k is a relative measure of data sparsity.

For each measurement of velocity and elevation, values of $\Delta \theta_k$ and D_k are calculated. For the case of velocity measurements, the distribution is presented in Figure 3. As in the proposed model, the variance of $\Delta \theta_k$ is larger at greater data sparsity. Moreover, small values of $\Delta \theta_k$ are more



Fig. 3. Distribution of $\Delta \theta_k$ vs D_k for velocity measurements. Spacing of field data is such that no values exist below $D_k \approx 70 \text{ km}$ or above $D_k \approx 300 \text{ km}$.





Fig. 4. Distribution of $\Delta \theta_k$ vs D_k for elevation measurements.

numerous than large values, consistent with a normal frequency distribution. The data are consistent with many models, including the one proposed here, $\sigma = AD_k$, in which the standard deviation increases with data sparsity. The parameter A is chosen such that 68% (1 σ) of $\Delta \theta_k$ values lie beneath the line.

There must be an upper limit to the standard deviation in $\Delta \theta_k$. One estimate of this limit is the standard deviation in flow direction of all catchment-area velocities. This value is 35° and occurs near $D_k = 239$.

The uncertainty model is then

$$\sigma = AD_k(D_k < D_{k-\max})$$

and $\sigma = \sigma_{\max}$ for $(D_k \ge D_{k-\max})$. (5)

A similar procedure is used to analyze the variance in flow directions deduced from elevation data (Fig. 4). Flow direction is taken to be perpendicular to elevation contours calculated from the data. Different interpolation algorithms were tested for data contouring (e.g. kriging, radial basis functions, inverse distance, minimum curvature). All yielded similar results. The standard deviation in elevation-measurement-based flow directions is also chosen as the upper limit for $\Delta \theta_k$.

Parameters determined for the uncertainty model are listed in Table 1.

AUTOCORRELATION LENGTH

The model developed so far describes the magnitude of uncertainty in flow direction. Also needed is a measure of the distance over which directional fluctuations act. Data from the BSSN (Fig. 2) show large-scale directional changes over lengths of 20–50 km. A similar scale of variation occurs in velocity measurements in the Jakobshavns drainage basin of West Greenland (Fastook and others, 1995). This distance is termed the autocorrelation length. In the model work here, the autocorrelation length is randomly varied between values of 20 and 50 km. The autocorrelation length can be

Table 1. Empirically determined parameters for the uncertainty model presented in Equation (5)

Parameter	Velocity data	Elevation data
$\sigma_{\max}(^{\circ})$	35	34
D_{k-max} (km)	239	960
$A (^{\circ} \mathrm{km}^{-1})$	0.142	0.035



Fig. 5. Topographic map of the Ice Stream B/C catchment region, indicating boundary position determined using velocity measurements (solid line) and 1σ uncertainty limits (dashed line). Solid circles mark elevation-measurement sites. The starting point for calculations is labeled \times . Contour interval is 100 m.

interpreted as the distance scale over which estimated directional fluctuations apply.

STARTING POINT

The starting point for calculations is defined using the most recent, detailed topographic map of the inter-stream ridge B/C area (Retzlaff and others, 1993). Surface slope in the region is such that this point is known with a precision of about 10 km. Because interpolated ice-flow directions vary slowly with position within the catchment, a small change in the starting position results in a nearly simple translation of the calculated boundary. This 10 km uncertainty in the boundary starting position is combined quadratically with the large-scale uncertainty described above.

BOUNDARY CALCULATION

Beginning at the starting point (labeled \times in Figs 5 and 6), a flowline is calculated up-glacier using interpolated directions of ice flow. Interpolated ice-flow directions fluctuate according to the product of the angular uncertainty (Equation (5)) and a random number selected from a normal distribution about zero. As the calculation proceeds up-glacier, the flow direction and the uncertainty estimate (Equation (5)) vary continuously along the flowline. However, the random number is held constant over a distance corresponding to the selected autocorrelation length. Once calculations are complete along this length, a new random number and autocorrelation length are chosen. Flowline calculation continues upglacier until the north-south trending ice divide is intersected.

Multiple flowlines are calculated from the same starting point, but differ because of randomly fluctuated uncertainties. The distribution of the resulting suite of flowlines determines a mean boundary position and an estimate of confidence in that position.



Fig. 6. Topographic map of the Ice Stream B/C catchment region, indicating boundary position determined using elevation measurements (solid line) and 1σ uncertainty limits (dashed line).

RESULTS

The calculated catchment boundary between Ice Streams B and C, based on velocity measurements and 5000 flowline calculations, is displayed in Figure 5. The standard deviation in the boundary position increases nearly linearly with distance as 0.15L, in which L is distance along the boundary from the starting position. This steady increase in standard deviation is a consequence of the nearly constant data sparsity along the boundary. The mean standard deviation in boundary position is 36 km. The standard deviation in catchment area along this boundary is $15\,000 \text{ km}^2$. This is approximately three times the value of the previous estimate made by Whillans and Bindschadler (1988), based on older elevation data.

The corresponding calculation based on elevation measurements and 5000 calculations is shown in Figure 6. Here also, standard deviation increases with distance from the starting point, but as 0.058L. The mean standard deviation in boundary position is 13 km. The standard deviation in catchment area along this boundary is 6000 km^2 . This value agrees to within 25% of the uncertainty estimate made by Whillans and Bindschadler (1988).

Applying similar levels of uncertainty to the Ice Stream A/B boundary allows for an estimate of uncertainty in the size of the entire Ice Stream B catchment area (values used for the A/B boundary position and catchment-area size are those determined by Whillans and Bindschadler (1988)). For velocity data, the area is $147(32) \times 10^3$ km². The standard deviation in area is 22%. Using elevation data, the catchment area works out to be $147(14) \times 10^3$ km². The standard deviation in area is 9%.

DISCUSSION

The uncertainty estimate determined from elevation measurements is about 40% of that determined from velocity measurements. In part, this could be because there are

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25% more elevation measurements in the catchment area than velocity measurements. As the uncertainty is modeled to be proportional to the number and nearness of field measurements, more elevation data lead to narrower confidence limits. However, the discrepancy is much too large to be due to data density alone. The main reason for the discrepancy is that flowlines determined from velocities are much more variable than flowlines determined from elevation contours. In terms of the factor A in Table l, the variability in velocitydetermined flow directions is four times that for elevationdetermined flow directions.

The reduced variability in flow directions given by elevations may be inherent. While one velocity measurement is needed to indicate the flow direction at a point, at least three elevation measurements are needed to infer the flow direction. This means that flow directions from elevations are averages over a large area, whereas velocity measurements apply at a specific point. As a result, flowlines based on elevation measurements are smoother than flowlines based on velocities. The larger variance observed in velocity-determined flow directions may be due to complex flow conditions that are not adequately sampled by the velocity data. Hodge and Doppelhammer (1996) report on ice-stream segments that extend into the catchments of Ice Streams C and D. There may be other such segments near the Ice Stream B/C boundary. The large variability in velocity-measurement-based flow directions relative to elevation-measurement-based flow directions may be evidence of this.

There is also a small difference in the positions of the boundary determined by the two methods. For the most part, these differences fall within the ranges of uncertainty. The largest difference occurs in the upper part of the catchment area, where the velocity-determined boundary lies to the south of the elevation-determined boundary (Figs 5 and 6). The difference is due to measured velocities that are not parallel to the regional surface slope, but are consistently more clockwise (Fig. 1). The offset is larger than subglacial effects measured along the BSSN allow for (the short-scale uncertainty described above).

This raises the intriguing possibility that the difference in boundary positions may be real, possibly due to migration and evolution of the B/C boundary with time. However, it is difficult to devise a physical process that could account for such a difference. The momentum of the ice is so small that large-scale ice motion should follow the mean surface slope. We therefore discount the proposition that the two sets of flow directions are different in reality, and propose that the calculated differences are due to problems in the sampling of velocities.

CONCLUSIONS

The largest contributor to uncertainty in the boundary position is the sparsity of field measurements. Increasing the level of confidence significantly would require a substantial increase in the number of measurements, and thus a much more ambitious field program. High-density datasets, such as those obtained through radar interferometry and radar and laser altimetry, may be expected to yield more precise results.

Using velocity data, the method results in a very large uncertainty, presumably because velocity directions are locally complex. The boundary position and confidence given by elevation data provide better estimates.

Other catchment areas on polar ice sheets may be defined by a similar level of precision. Applying the elevation-measurement-based formula of $\sigma = 0.058L$ (applied to the lateral boundaries), the standard deviation in the "East Antarctica into the Ross Ice Shelf" catchment area (defined by Bentley and Giovinetto, 1991) works out to be 7% (168(13) × 10⁴ km²). For this much larger catchment area, the uncertainty is proportionally similar to that given for the Ice Stream B catchment.

These new results bring into question the "capture" hypothesis, in which Ice Stream B caused the stagnation of Ice Stream C by stealing parts of its catchment area (Rose, 1979; Shabtaie and Bentley, 1987). The boundary determined here (Fig. 6) does not restrict the supply of ice flowing into the head of Ice Stream C. Moreover, velocities in the upper part of Ice Stream B. It is only the middle to lower regions of Ice Stream C that are nearly stopped. There is no evidence for ongoing capture of the Ice Stream C drainage.

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