# EXTRACTION OF TRACE COMPONENTS FROM LARGE QUANTITIES OF ICE IN BORE HOLES

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ABSTRACT. A melting probe system has been developed which can be lowered down to 400 m in an ice bore hole of 135–165 mm diameter. At the desired depth, a section of the bore hole is isolated and evacuated. Afterwards several tons of ice are melted under vacuum with an electrical heater. The inclusions which are principally gaseous, may be collected both during or after the melting procedure. The application of this system is mainly in the field of dating polar ice by radio-active isotope analysis.

Résumé. Extraction des traces dans les carrotages à partir de quantités importantes de glace. On a développé un système de sonde à fusion, qui peut être descendu jusqu'à une profondeur de 400 m, dans un forage effectué dans une couche de glace. Le diamètre du forage étant de 135-165 mm. À la profondeur désirée, il est possible d'étanchéfier la sonde avec la paroi du trou et d'évacuer la section concernée. On peut ensuite fondre plusieurs tonnes de glace, sous vide, à l'aide d'un chauffage électrique. Pendant ou après la fusion, on peut recueillir les inclusions, principalement des gazes. Les applications de ce système se trouvent surtout dans la datation des glaces polaires, à l'aide d'analyse radioisotopique.

ZUSAMMENFASSUNG. Entnahme von Spurenkomponenten aus grossen Eismengen in Bohrlöchern. Ein Schmelzsondensystem wurde entwickelt, das in ein Eisbohrloch von 135–165 mm Durchmesser bis auf eine Tiefe von 400 m hinuntergelassen werden kann. In der gewünschten Tiefe wird ein Abschnitt des Bohrlochs abgedichtet und evakuiert, anschliessend werden mit einer elektrischen Heizung mehrere Tonnen Eis unter Vakuum geschmolzen. Verschiedene Einschlüsse, vor allem jedoch Gase, werden laufend oder nach dem Schmelzprozess extrahiert und gesammelt. Die Anwendungen liegen, wenigstens bis heute, hauptsächlich auf dem Gebiet der Datierung von polarem Eis mit Hilfe von Radioisotopenanalysen.

# I. INTRODUCTION

The successful development of ice-core drilling techniques has allowed the recovery of ice cores from polar ice sheets and glaciers, which cover (in a continuous sequence) the last few hundred to a hundred thousand years (Ueda and Garfield, 1969[a]). Both detailed 18O/16O profiles which provide a high resolution record of climatic history (Dansgaard and others, 1973) and depth profiles of dissolved and particulate matter (Langway, 1970) are impressive examples of ice-core investigations. The time resolution obtained is such that even seasonal effects can be observed for certain parameters. Although the amount of ice available from ice cores is sufficient for these studies, samples of much larger size (tons) are required for studies on isotopes produced by cosmic rays, cosmic dust, daughter products of U- and Th-decay, pollen, and other constituents. To obtain such large quantities of ice from depth by present core drilling techniques, more than one hundred meters of core would be required. Therefore, satisfactory time resolution (corresponding to a few meters) could only be achieved if the core diameter were increased by a factor of ten. This has not yet been undertaken because of the great technical effort involved. This need for large samples from a relatively narrow depth range motivated us to develop an "in situ" extraction technique for gases and particulate and dissolved matter from large amounts of ice in bore holes.

We performed our first tests in the TUTO ice tunnel near Thule (Greenland) in 1966. (Oeschger and others, 1966, 1967). There an electrical heater of 7 kW power consumption was inserted in a 5 m deep hole bored with a SIPRE-auger. The hole was sealed vacuum tight on top of the heater and several tons of ice were melted under vacuum conditions. The gases released by the melting ice were collected; the  $CO_2$  was separated and used for <sup>14</sup>C-dating.

Encouraged by the promising results of this test we constructed a similar system for use in deeper bore holes. During the 1968/69 season at "Byrd" station (Antarctica) we carried out a test which failed because of a power breakdown that caused the probe to become permanently

frozen to the wall of the bore hole. In 1969/70, again at "Byrd" station, we tested an improved extraction probe and were able to sample CO<sub>2</sub> from three tons of ice at four different levels in a 340 m bore hole which had been drilled with a CRREL thermal core drill (Ueda and Garfield, 1969[b]). During the melting process the escaping gases were continuously pumped to the surface. There the CO<sub>2</sub> was extracted and the remaining gases were collected. The melt water was pumped to the surface and either filtered or used for Si sampling for later <sup>32</sup>Si dating (Clausen, 1973). <sup>14</sup>C measurements showed that the samples had been contaminated by fossil CO<sub>2</sub> that degassed from the hoses through which the gas had been pumped to the surface. We therefore decided to place the CO<sub>2</sub> extraction system directly on the top of the probe rather than at the surface to avoid this contamination. After successful tests of a system based on this new concept, we used it in bore holes at "Byrd" station in 1971/72, on the Devon Island ice cap (Canada) in 1973, and at Station Crête (Greenland) in summer 1974.

In this paper we give a technical description of the sampling equipment and the procedure. The resulting data will be published and discussed later.

#### 2. DRILLING IN ICE

During the last decade, core drilling in ice has become a dependable technique and several bore holes have been successfully drilled in Antarctica, Greenland, and smaller ice caps.

In the ablation zone, old ice is already exposed at the surface and the SIPRE hand auger can be used to drill to about 5 m, the depth required for placement of the *in situ* extraction probe. Recently developed mechanical drills allow drilling to depths of 100 m, both in the accumulation and in the ablation zone (Rand, in press; Ruffi, in press).

Since our extraction method only works in ice, in accumulation zones we need bore holes which reach a depth greater than that of the firn-ice transition zone, i.e. greater than about 70 m. To obtain such holes a CRREL thermal drill or a modification of it is used. The maximum depth which can be reached by this intermediate drilling depends on the rate of hole closure due to hydrostatic pressure and varies with temperature.

A mechanical rotary drilling method with cable suspension has allowed deep drilling to the bedrock at Camp Century (Greenland) and "Byrd" station (Antarctica) (Ueda and Garfield, 1969[a]). To compensate for the hydrostatic pressure, these deep bore holes were filled with a non-freezing fluid of a density equal to that of ice. In situ extraction in such bore holes does not seem to be impossible but new problems arise from the interference of the fluid.

#### 3. LOGIC OF EXTRACTION

In this section we describe briefly the principal steps of our extraction procedure. Technical details and experiments with the system will follow in later sections.

For extraction at the desired depth a portion of the bore hole has to be sealed vacuum tight around the probe. After tests to ensure that the sealing system is tight, the desired amount of ice is melted by an electrical heater probe, and the released gases are pumped off continuously during the melting process. In the upper part of the probe, the gases are dried and  $CO_2$  is extracted by an adsorbant. The remaining gases are pumped through a hose to the surface, where they are compressed and stored for later shipment to the laboratory.

When the desired amount of gases has been collected, pumping is stopped and sampling of particulate and dissolved matter starts. It can be performed either in the bore hole or at the surface. For extraction at the surface, the heater probe is pulled up, while the lower seal and the melt water remain in the bore hole. A submersible pump is lowered into the hole and the melt water is pumped to the surface for sampling, e.g. by filter or ion-exchange column.



Fig. 1. The melting probe. A: water intake. B: electrical heater for melting ice. C: water outlet. D: wiring cylinder. E: submersible electric motor. F: gear-wheel pump. G: millitube filter cartridge or ion-exchange column. H: gas drying column with 3A molecular sieve. I: gas inlet. J: rubber packer section. K: electromagnetic by-pass valve. L: CO<sub>2</sub> extraction column with 5A molecular sieve.

#### 4. EXTRACTION PROCEDURE

The following devices were used for the collection of our samples: the melting probe, the balloon probe, the submersible pump, the cable hose and the auxiliary hoses, the winches for cable hose and auxiliary hoses, the gas control system, and the electrical power system, and these are described in turn in this section.

# 4.1. The melting probe

The melting probe is schematically shown in Figure 1. The main parts are: electrical heater for ice melting B and auxiliary heaters, a water circulation section E-G, a gas drying section H-I, a rubber packer section J, and a CO<sub>2</sub> extraction-line section L. This probe is designed as a modular system: the different sections can be used or replaced by others as required by the special problem we want to solve.

4.1.a. *Heaters.* Two types of electrical heater have been constructed. The older one consists of four heating elements, which are mantled by stainless steel and wound around a stainless-steel tube 1.6 m long (Lükon, Täuffelen, Switzerland). Each element is wired separately in a three phase Y connection and rated for a three-phase 440 V input. The maximum total power consumption is 10 kW. We had frequent failures with this type of heater due to short circuits between the three heating wires caused by moisture penetrating through the insulation.

In the improved version the heater now consists of six U-shaped elements, which are mantled by stainless steel and 1.7 m long. Each element contains only one heating wire, rated for a one-phase 240 V input. The six elements can be connected to two three-phase or various one-phase circuits. The maximum total power consumption is 10.5 kW.

The heating elements of both versions end in a water-vapour-proof stainless-steel cylinder (wiring cylinder), where they are connected to the power supply. The electrical heaters are designed for operation in vacuum without overheating.

Auxiliary heaters are built into the wiring cylinder, the water circulation section, the gas drying section, and the rubber packer section. They consist of silicon rubber insulated heating wires (Dätwyler, Altdorf, Switzerland), pressed against the walls of these parts. The power rating is 700 W per metre of heated probe section. The auxiliary heaters are used to prevent the water circulation system from freezing during operation. At the end of operations they allow the loosening of the probe in case it should be frozen onto the wall of the bore hole.

4.1.b. The water circulation section. The water circulation section is mounted into the probe when we want to sample the melt water in the bore hole. The melt water is sucked from the bottom of the electrical heater (A in Fig. 1) through a stainless steel tube by a gear-wheel pump F (Maag, Zürich, Switzerland), which is driven by a 750 W, three-phase, submersible electrical motor E (Franklin Inc., Bluffton, Indiana). The pump forces the water either through a "Millitube" 0.8 µm filter cartridge (Millipore Comp., Bedford, Mass.) or through an ion-exchange column containing resin (Rohm & Haas, Philadelphia) G. The water flows back into the melted cavity. The pumping rate is about 15 l/min.

For technical reasons we placed the pump F on top of the heater B and the wiring cylinder D. This has the disadvantage that the water has to be sucked above the water level. Therefore the total gas pressure in the melting cavity must be higher than 500 mbar and it is not possible to start water circulation as long as vacuum gas extraction is going on. When gas extraction has been completed, we fill the cavity with purified  $N_2$  to a pressure of 500 mbar and start water circulation. If we assume that during the circulation the melt water is a well-mixed reservoir, then 95% of the water will have passed through the filter or ion-exchange column at least once when an amount of water has been circulated corresponding to three times the total quantity of melt water available.

4.1.c. Gas drying section. The gas which is extracted from the melting ice has to be dried before the  $CO_2$  can be separated by adsorption on a molecular sieve. The gas flows outside the probe along the cold wall of the bore hole, where a high percentage of the water vapour condenses. The remaining humidity is adsorbed by passing the gas through a stainless-steel column H with an active length of 1.7 m and filled with 300 g of molecular sieve pellets (Linde Type 3A, Union Carbide Corporation). After each run the column is dismounted so that the molecular sieve can be reactivated by vacuum drying at 300 to  $350^{\circ}C$ .



Fig. 2. The rubber packer section. M: top cover with electrical connector and gas inlet tube. N: string and metal-band sealing.
 O: neoprene rubber hose. P: auxiliary heater (silicon-rubber insulated heating wire). Q: nitrogen gas inlet. R: brass tube.
 s: inner aluminium body. T: double O-ring seal.

4.1.d. Rubber packer section. The rubber packer section J is schematically shown in Figure 2. A rubber hose 0, made of special low temperature Neoprene (Lonstroff, Aarau, Switzerland), is fixed on both ends with strings and metal bands N to a brass tube R. The brass tube is slid over an aluminium body s. Its vacuum-tight top cover M is provided with a ceramic-insulated electrical connector and three gas inlet tubes. To seal the portion of the bore hole below the rubber packer the rubber hose is inflated with 99.99% N<sub>2</sub> at a pressure of 3 bar (absolute), pressing it over its whole length against the wall of the bore hole. The N<sub>2</sub> is provided through a nylon hose from a tank at the surface. Pressure in the hose and in the packer is monitored during the whole operation.

To release the pressure in the packer the hose is disconnected from the  $N_2$  tank. If the packer hose becomes clogged, pressure in the packer can be released by pulling up the probe a few centimetres. This allows the brass tube R to slide partly from the aluminium body s. A rubber hose frozen to the bore hole wall can be melted out by operating the auxiliary heater in the aluminium body.

Since the drilling operation does not produce a very smooth bore-hole wall, the following sealing procedure has to be applied: The probe is lowered first to a temporary position, with the main heater facing the part of the bore-hole wall that will later be used for sealing. The heater is switched on for 15 min to smooth and wet the wall surface. Afterwards the probe is brought to the final position. We inflate the rubber packer immediately and start to evacuate the cavity.

4.1.e.  $CO_2$  extraction-line section. From the drying section the gases flow through the  $CO_2$  extraction column L in Figure 1 or through a by-pass K to the hose of the oceanographic cable. The column is a stainless-steel spiral at the top of the probe above the rubber packer where the temperature is almost as low as the bore-hole temperature. The column has an active length of 50 cm and is filled with 20 g of molecular sieve (Linde Type 5A, Union Carbide Corporation). During extraction the pressure in the gas line is kept at about 100 to 180 mbar. The partial pressure of the  $CO_2$  in the spiral is estimated to be only about  $5 \times 10^{-5}$  bar.

At a bore-hole temperature of about  $-20^{\circ}$ C the efficiency of our CO<sub>2</sub> extraction is estimated to be about 85%. Extraction of CO<sub>2</sub> at the surface, where it was easily possible to raise the efficiency to almost 100% by cooling down the CO<sub>2</sub> extraction column to about  $-50^{\circ}$ C, had to be abandoned because the samples were contaminated by CO<sub>2</sub> that degassed from the nylon hose. Until now we have not attempted to cool the spiral in the bore hole.

After the extraction process, the spiral is removed from the probe. On a vacuum system it is heated to  $250^{\circ}$ C to transfer the CO<sub>2</sub> sample to a stainless-steel transportation cylinder filled with molecular sieve 5A. The extraction column is reactivated by heating to  $350^{\circ}$ C and vacuum pumping down to  $3 \times 10^{-5}$  bar for 24 h before the next extraction run.

#### 4.2. The balloon probe

In the first two prototypes of our extraction probe we were using identical rubber packer systems both at the top and at the bottom of the probe. The lower packer froze in completely and in no case could it be retrieved, even after heating with the auxiliary heaters. Moreover pumping the melt water to the surface is impossible after removing a lower packer. To avoid such difficulties we are now using a special probe to place a lower seal before lowering down the extraction probe (Fig. 3). It consists of a plastic tank u, which is filled with 3.3 l of warm ( $40^{\circ}$ C) water. The probe is lowered to the desired depth, then a magnetic valve w is opened and the water flows into the balloon x. The water will melt the balloon slightly into the wall of the bore hole. A thermistor v in the water tank shows a rapid temperature decrease when the water has flowed through the magnetic valve. A second thermistor z in the balloon confirms that the balloon holds water. After 20 h the water v in the balloon is frozen, and we can pull



Fig. 3. The balloon probe. U: plastic water tank. V: upper thermistor. W: electromagnetic valve. X: rubber balloon (doublewalled). Y: lukewarm water, cooling down and freezing. Z: lower thermistor.

the water tank u to the surface. The balloon x with the lower thermistor z and a short piece of nylon hose, remains in the bore hole. This sealing system can be drilled through by mechanical drilling to reopen the bore hole. This has not yet been attempted.

# 4.3. The submersible pump

For pumping the melt water to the surface we use a commercial submersible water pump. It is a 75-stage centrifugal pump, driven by a 6.5 kW electrical motor at the bottom (Reda Pump Company, Bartlesville, Oklahoma). The total length is 2.96 m with the suction inlet 1.23 m above the bottom, the outer diameter is only 85 mm, the pressure is 50 bar. We have glued an electrical heating tape on the wall of the pump to avoid freezing during stand-still.

The submersible pump is suspended on the same cable hose as the extraction probe (see section 4.4). The water is pumped through an extra hose of 10 mm i.d., which is fixed to the cable hose and is heated along its whole length (see section 4.4). For a depth of 380 m the

pumping speed is 6 l/min, for a depth of 100 m the speed raises to 14 l/min. As the inlet of the pump is not at the bottom of the bore hole, about 35% of the melt water can be pumped to the surface.

# 4.4. Cables and hoses

To suspend the probe, to provide it with electrical and remote control signals, and to pump the gases to the surface, we use an oceanographic pump cable hose (U.S. Steel Corp., Pittsburg, Pa.). It consists of a nylon hose of  $\frac{3}{8}$  inch i.d. surrounded by 30 insulated electrical wires 20 A.W.G. and two braids of galvanized steel. The cable is one piece with a total length of 450 m. The power is transmitted through six wires for each phase to the main heater. With a load of 10 kW the voltage drops by 10 V per phase. The remaining 12 wires are used for the various sections of the auxiliary heater, the circulation pump motor, the magnetic valves of the CO<sub>2</sub> extraction line and for temperature and pressure gauges. The cable hose of the oceanographic pump is also used for suspension of and power transmission to the balloon probe and the submersible pump.

To fill the rubber packer with nitrogen an auxiliary nylon hose of 4 mm i.d. is clamped to the oceanographic cable. The melt water is pumped to the surface through a special



Fig. 4. Schematic diagram of the gas control system. B: weather balloon. C: gas compressor. E: entry from bore hole. I: integrated gas-flow meter. MI and M2: manometers. P: vacuum pump. S: storage cylinder. VI, V2, V3, V4 and V5: valves.

water hose. It is a high-pressure natural rubber hose with 10 mm i.d. in 5 pieces, each 100 m long, containing along the whole length a Nikrothal heating wire (Kanthal A. B., Hallstakammar, Sweden) with a power load of 11 W/m.

If logistic considerations do not allow the transport of the bulky oceanographic cable to the extraction site we shall use a special lightweight cable-hose (Huber & Suhner, Pfäffikon, Switzerland) with two nylon hoses and 12 insulated wires, but without braids. The probe is suspended on an extra steel cable, e.g. on the CRREL thermal drill cable, to which the lightweight cable-hose is fixed.

#### 4.5. Winches

The oceanographic cable and its cable reel have a total weight of 680 kg. A drive with an electrical motor is used to lower and to pull up the cable with the probes or with the submersible pump. For each run, the auxiliary hoses have to be attached to the oceanographic cable hose with cable clamps. They are reeled by hand.

# 4.6. Gas control system

The gas control system at the surface is schematically shown in Figure 4. Before gas extraction can start, the blocked portion of the bore hole is evacuated with a double-stage rotary vacuum pump P (Edwards Ltd., Crawley, England). For vacuum tests, valve v1 towards pump and compressor is closed and any possible pressure increase is monitored with manometer M1. When the tests are satisfactory, we start extraction by switching on the main heater. For the first few hours the escaping gases are not collected; they help to flush the system. Gas collection is started by closing valves v2 and v4 and by compressing the gas into the storage cylinder. The amount of gas collected is checked with manometer M2. The compressor c (A. Hofer GmbH, Mühlheim, Germany) is a two-stage stainless-steel diaphragm compressor. It maintains a pressure of 180 mbar at manometer M1 when the pressure in the storage cylinder s is lower than 10 bar. When the extraction is terminated, in a second step, the gas in the storage cylinder is transferred and compressed into a small gas-transportation cylinder.

When a metal diaphragm compressor is not available, the gases may be collected at the outlet of the vacuum pump in a weather balloon. An integrating gas-flow meter 1 between the vacuum pump and the balloon allows the amount of collected gas to be measured. In a second step, after terminating the extraction, the collected gas is transferred into a stainless-steel transportation cylinder with a small gas compressor.

# 4.7. Electrical power system

The power requirement during the extraction is almost 14 kW. To pump the water to the surface 15 kW from a three-phase power system is required.

To switch and control the different circuits and to read thermistors and manometers in the probes we have built a compact switch board. The power consumption of the main heater is continuously recorded in order to estimate the amount of ice melted. About 90 kg of ice per hour are melted. To obtain sufficient  $CO_2$  and Ar for <sup>14</sup>C- and <sup>39</sup>Ar-dating about 5 tonnes of ice have to be melted and about 700 kWh is consumed.

# 4.8. Extraction time-table

The time required to prepare the equipment in the field depends on local logistic support facilities and on the extraction program. In general, preparation in the field takes 4 to 7 days.

The following table shows a typical sequence for an extraction:

Lowering the balloon probe, filling the balloon probe with water and		
freezing the water		24 h
Pulling up the balloon probe, mounting the melting probe and lowering it		8 h
Evacuation of the cavity and vacuum tests		24 h
Melting of the ice and extraction of gases; time required depends on available power and gas content of the ice. If 10 kW are available and		
4 tonnes of ice have to be melted		48 h
Pulling up the melting probe, mounting and lowering the submersible		8 h
Pumping a tonnes of melt water to the surface		8 h
Pulling up the submersible pump and mounting the balloon probe		6 h
Total time	5 d	6 h

A similar time is required if, instead of pumping the melt water to the surface, the down-hole water circulation system is used after ice melting.

It is assumed that reactivation of the molecular sieves, preparing the filter or ion-exchange resin and minor repairs, e.g. of the melting probe, can be done during the first step.

### 5. DISCUSSION

# 5.1. Yields of the gas extraction

To minimize the fraction of the gases which will remain in the melt water, we keep the gas pressure in the melted cavity low and pump off the gases continuously during the melting process. <sup>14</sup>C- and <sup>39</sup>Ar-dating is based on the measurement of the ratios <sup>14</sup>C/total C and <sup>39</sup>Ar/total Ar. Incomplete extraction can produce errors due to isotope fractionation. In this case correction is possible by measuring the ratios of the stable isotopes in the sample, e.g. <sup>13</sup>C/<sup>12</sup>C.

To find out whether very rare and easily soluble gas components, e.g. Kr and  $CO_2$ , are lost to any great extent we have measured the composition of the extracted gases. The analysis showed only minor deviations from atmospheric composition. The extraction of  $CO_2$  by trapping it on a molecular sieve and the extraction of  $CO_2$  by ion exchange show similar efficiencies.

# 5.2. Contamination problems

The major contamination problems encountered are gas leakage and CO<sub>2</sub> degassing. A leak anywhere in the vacuum system causes severe contamination by atmospheric air, if the leakage rate is higher than about 60 cm<sup>3</sup> s.t.p. of air per hour. An indication of leakage during extraction is the presence of <sup>85</sup>Kr in the sample; <sup>85</sup>Kr has been only released into the atmosphere in measurable quantities since the beginning of nuclear energy production.

As mentioned in the introductory chapter, the contamination of  $CO_2$ -samples (for <sup>14</sup>Cdating) from degassing of hoses is avoided by collecting the  $CO_2$  down the hole in the probe. A major contamination source for  $CO_2$  could be the materials from which the probe is built. To keep  $CO_2$ -degassing of the probe to a minimum, stainless steel has been used for construction of its main parts wherever possible. For electrical insulators we used ceramics or silicon rubber. Special care has to be taken to clean the probe before each run. One drop of oil or an equivalent amount of organic material, i.e. about 1 mg, burning completely on the heater, would suffice to contaminate the  $CO_2$  sample seriously. The apparent <sup>14</sup>C-age of a contaminated sample is overestimated if the contaminant is of fossil origin.

#### Natural Amount of ice to concentration be treated to get Compounds extract required in to be extracted Search for recent ice for analysis Origin Main applications (dpm = decays) $(T_{\frac{1}{2}} = \text{half life},$ per minute, if if radioactive radioactive isotope) isotope) CO2 gas in air 14C 0.2 dpm/103 kg ice $(1-5) \times 10^3 \text{ kg}$ produced in the dating of ice bubbles atmosphere by variations in cosmic radiation cosmic ray (14N(n, p) 14C intensities reaction) $T_1 = 5730$ years Argon in air 39Ar 0.1 dpm/10<sup>3</sup> kg ice $5 \times 10^3$ kg produced in the dating of ice bubbles atmosphere by behaviour of gases cosmic radiation in the firn (various reactions) $T_1 = 270$ years Silicon dissolved 32Si 0.4 dpm/103 kg ice 103 kg produced in the dating of ice and adsorbed atmosphere by variations in on particulate cosmic radiation cosmic ray matter (spallation) intensities T about 300 years 3×10-3 dpm/ Manganese 53Mn 102 kg sufficient characteristic for identification of dissolved or 103 kg ice if analysed cosmic dust cosmic dust estimated for as a after neutron $T_{1} = 3.7 imes 10^{6}$ long term compound of low activation variations in years particulate accumulation cosmic ray matter areas intensities Chlorine 36Cl 10-2 dpm/103 kg 104 kg estimated produced in the dating of very old dissolved ice estimated atmosphere by ice for low cosmic radiation accumulation (spallation) areas $T_{1} = 3.1 \times 10^{5}$ years Inorganic cosmic dust ppb (10-9 g/g ice) 102 kg micrometeoritic total influx of particulate estimated for matter, mainly cosmic dust matter low from solar accumulation system areas pollen o-104 pollen/ 10-103 kg edge of ice cap or climatic variations 103 kg ice tundra influencing main wind direction and flora (Ritchie and Lichti-Federovich, Organic matter 1967) dissolved and aminoacids ? (10<sup>-10</sup> g as particulate terrestrial and dating of old ice matter detection extra-terrestrial by analysis of limit) racemiation origin possible influx of extraterrestrial organic matter (Bada, and Schroeder.

## TABLE I. MAIN APPLICATIONS OF THE EXTRACTION METHOD

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1972)

The melt water which is circulated through the probe or pumped to the surface may contain considerable amounts of pump wear-off and dissolved components from the extraction system and the hoses. However, for studies of pollen and isotopes produced by cosmic rays, they need not necessarily be of contaminating character.

# 6. Applications of the extraction method

We have developed our extraction technique mainly for extracting CO<sub>2</sub> for <sup>14</sup>C-dating. However the technique offers many other possibilities. In Table I we have compiled the main possible applications.

# 7. ACKNOWLEDGEMENTS

The development of the "in situ extraction technique" described, has been a continuous effort over the past 10 years in collaboration with L. B. Hansen and C. C. Langway from U.S. Army CRREL, who aided us in overcoming many of the difficulties we had during this time. The extraction for 32Si-dating was carried out in collaboration with H. B. Clausen from the University of Copenhagen. Many of the technical problems were solved by our collaborators W. Bernhard, T. Müller, H. Rufli, H. Steuri and L. Trenholm. They were all of great help, both regarding design and construction of equipment as well as providing assistance in field parties. The interest and the encouragement of all these mentioned above, both in periods of success and of difficulty, are highly appreciated. We thank R. C. Finkel for valuable discussions and comments on the paper. We are very grateful to the U.S. National Science Foundation and the Schweizerischer Nationalfonds zur Förderung der wissenschaftliche Forschung for their support.

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