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Theory of heat equations for sigma functions*

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Abstract

Let e and q be fixed co-prime integers satisfying 1 < e < q. Let $\mathscr C$ be a certain family of deformations of the curve $y^e = x^q$. That family is called the (e, q)-curve and is one of the types of curves called plane telescopic curves. Let Δ be the discriminant of $\mathscr C$. Following pioneering work by Buchstaber and Leykin (BL), we determine the canonical basis $\{L_j\}$ of the space of derivations tangent to the variety $\Delta = 0$ and describe their specific properties. Such a set $\{L_j\}$ gives rise to a system of linear partial differential equations (heat equations) satisfied by the function $\sigma(u)$ associated with $\mathscr C$, and eventually gives its explicit power series expansion. This is a natural generalisation of Weierstrass' result on his sigma function. We attempt to give an accessible description of various aspects of the BL theory. Especially, the text contains detailed proofs for several useful formulae and known facts since we know of no works which include their proofs.

Introduction

Classically, the Weierstrass function $\sigma(u)$ is defined through the Weierstrass elliptic function $\wp(u)$ as follows:

$$\sigma(u) = u \exp\left(\int_0^u \int_0^u \left(\frac{1}{u^2} - \wp(u)\right) du du\right).$$

The modern approach is to define the sigma function starting from a general elliptic curve. However, in this introduction, we treat only the curve defined by

$$y^2 = x^3 + \mu_4 x + \mu_6 \quad \text{(Weierstrass form)}. \tag{0.1}$$

(We refer the reader to [12] for the case of the most general elliptic curve.) For this curve, we define the function $\sigma(u)$ by

$$\sigma(u) = \left(\frac{2\pi}{\omega'}\right)^{1/2} \Delta^{-\frac{1}{8}} \exp\left(-\frac{1}{2}\omega'^{-1}\eta'u^{2}\right) \cdot \vartheta\left[\frac{\frac{1}{2}}{\frac{1}{2}}\right] (\omega'^{-1}u, \omega''/\omega'), \tag{0.2}$$

where $\Delta = -16(4\mu_4^3 + 27\mu_6^2)$ is the discriminant of the curve, and ω' , ω'' , η' , and η'' are the periods of the two differential forms

$$\frac{dx}{2y}, \frac{xdx}{2y}$$

with respect to a pair of fixed standard closed paths α_1 and β_1 which represents a symplectic basis of the first homology group, though η'' does not appear explicitly. The last part of (0.2) is Jacobi's theta series defined by



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$$\vartheta \begin{bmatrix} b \\ a \end{bmatrix} (z, \tau) = \sum_{n \in \mathbb{Z}} \exp 2\pi i \left(\frac{1}{2} \tau (n+b)^2 + (n+b)(z+a) \right) \quad (a, \ b \in \frac{1}{2} \mathbb{Z}). \tag{0.3}$$

From now on, we suppose the function $\sigma(u)$ is defined by (0.2). In using this definition, it is not clear that $\sigma(u)$ is independent of the choice of α_1 and β_1 . Indeed, both of the later part (Jacobi's theta series) of (0.2) and former part are not invariant when we choose another pair of α_1 and β_1 . However, these changes offset each other and $\sigma(u)$ itself is invariant.

Using the Dedekind eta function $\eta(\tau)$ (not to be confused with the periods η above and in Section 1.1), the discriminant Δ of the curve above is given by $\Delta = \left(\frac{2\pi}{\omega'}\right)^{12} \eta(\omega''/\omega')^{24}$, and the first terms in (0.2) can be explicitly written as

$$\left(\frac{2\pi}{\omega'}\right)^{1/2} \Delta^{-\frac{1}{8}} = -\frac{\omega'}{2\pi} \eta(\omega''/\omega')^{-3}.$$
 (0.4)

Although Δ is invariant with respect to a change of α_1 and β_1 , both sides of (0.4) and ω' are not invariant. The function $\sigma(u)$ has a power series expansion at the origin as follows:

$$\sigma(u) = u \sum_{n_4, n_6 \ge 0} b(n_4, n_6) \frac{(\mu_4 u^4)^{n_4} (\mu_6 u^6)^{n_6}}{(1 + 4n_4 + 6n_6)!}$$

$$= u + 2\mu_4 \frac{u^5}{5!} + 24\mu_6 \frac{u^7}{7!} - 36\mu_4^2 \frac{u^9}{9!} - 288\mu_4 \mu_6 \frac{u^{11}}{11!} + \cdots,$$
(0.5)

where $b(n_4, n_6) \in \mathbb{Z}$. (This expansion also shows the independence of $\sigma(u)$ with respect to the choice of α_1 and β_1).

In this work, we are interested in the *sigma function*, which is a multivariate entire function, associated with a curve which we call (n, s)-curves or plane telescopic curves (see Section 1.1 for definitions). One of the motivations of a theory of heat equations is to get a recurrence relation for the expansion coefficients of the sigma function, like that of the $b(n_4, n_6)$ s. But, there is another motivation as follows. For such a general non-singular curve, there is an intrinsic or axiomatic definition (see 4.1) of the sigma function. It would be useful if we have an expression, like (0.2), for the generalised sigma function. Indeed it is not so difficult to show that the natural generalisation of the right-hand side of (0.2), but dropping the factor corresponding to (0.4), satisfies some of the conditions in 4.1. Before [9], except for curves of genus one and two, the validity of the expression including the natural generalisation of the factor (0.4) was not yet proved completely. We shall discuss this motivation again at the end of this introduction.

It is well-known that the sigma function for a general non-singular algebraic curve is expressed by Riemann's theta series with a characteristic coming from the Riemann constant of the curve multiplied by some exponential factor and some constant factor. This constant factor might be a natural generalisation of (0.4). But, there seems to be no proof of the determination of this constant factor except in genus one and two (we mention this again later). To fix the last constant is another motivation of the theory, which is described around Lemma 4.17 of [8].

We now review the classical theory of the heat equations for $\sigma(u)$. Let z and τ be complex numbers with the imaginary part of τ positive. We define $L = 4\pi i \frac{\partial}{\partial \tau}$ and $H = \frac{\partial^2}{\partial z^2}$. Then Jacobi's theta function (0.3) satisfies the following equation, which is known as the heat equation,

$$(L-H)\,\vartheta \begin{bmatrix} b \\ a \end{bmatrix} (z,\tau) = 0. \tag{0.6}$$

Weierstrass' result in [31], which is displayed as (0.13) below, is regarded as an interpretation of (0.6) in the form attached to his function $\sigma(u)$. Strictly speaking, he did not derive it directly, but only by elementary and quite technical integrations from the well-known differential equation

 $\wp'(u)^2 = 4\wp(u)^3 - g_2\wp(u) - g_3$, where $g_2 = -4\mu_4$ and $g_3 = -4\mu_6$, satisfied by the $\wp(u) = -\frac{d^2}{du^2}\log\sigma(u)$. He eventually obtained the recurrence relation

$$b(n_4, n_6) = \frac{2}{3} (4n_4 + 6n_6 - 1)(2n_4 + 3n_6 - 1)b(n_4 - 1, n_6)$$

$$-\frac{8}{3} (n_6 + 1)b(n_4 - 2, n_6 + 1) + 12(n_4 + 1)b(n_4 + 1, n_6 - 1)$$
(0.7)

for the coefficients of the expansion (0.5) of $\sigma(u)$ (see also §6.3 and [25]).

Frobenius and Stickelberger approached (0.7) via a different method in their paper [14] which was published in the same year as [31]. Using the expansion

$$\wp(u) = \frac{1}{u^2} + \frac{g_2}{20}u^2 + \frac{g_3}{28}u^4 + \frac{g_2^2}{1200}u^6 + \cdots,$$
 (0.8)

and the corresponding expansion of the Weierstrass function

$$\zeta(u) = \frac{1}{u} - \int_0^u \left(\wp(u) - \frac{1}{u^2} \right) du$$

with

$$g_2 = 60 \sum_{(n',n'')\neq(0,0)} \frac{1}{(n'\omega' + n''\omega'')^4}, \quad g_3 = 140 \sum_{(n',n'')\neq(0,0)} \frac{1}{(n'\omega' + n''\omega'')^6}, \tag{0.9}$$

they obtained the formulae

$$\omega' \frac{\partial g_2}{\partial \omega'} + \omega'' \frac{\partial g_2}{\partial \omega''} = -4g_2, \quad \omega' \frac{\partial g_3}{\partial \omega'} + \omega'' \frac{\partial g_3}{\partial \omega''} = -6g_3,$$
$$\eta' \frac{\partial g_2}{\partial \omega'} + \eta'' \frac{\partial g_2}{\partial \omega''} = -6g_3, \quad \eta' \frac{\partial g_3}{\partial \omega'} + \eta'' \frac{\partial g_3}{\partial \omega''} = -\frac{1}{3}g_2^2,$$

where $\eta' = \zeta(u + \omega') - \zeta(u)$, $\eta'' = \zeta(u + \omega'') - \zeta(u)$ which are independent of u, and (see (6.4))

$$\omega' \frac{\partial}{\partial \omega'} + \omega'' \frac{\partial}{\partial \omega''} = -4g_2 \frac{\partial}{\partial g_2} - 6g_3 \frac{\partial}{\partial g_3},$$

$$\eta' \frac{\partial}{\partial \omega'} + \eta'' \frac{\partial}{\partial \omega''} = -6g_3 \frac{\partial}{\partial g_2} - \frac{1}{3}g_2^2 \frac{\partial}{\partial g_3}.$$
(0.10)

In our notation of the present paper, these operators (0.10) are denoted by $4L_0$ and $4L_2$, respectively. Moreover, they found (p.318 in [14])

$$\omega' \frac{\partial \eta'}{\partial \omega'} + \omega'' \frac{\partial \eta'}{\partial \omega''} = \eta', \quad \omega' \frac{\partial \eta''}{\partial \omega'} + \omega'' \frac{\partial \eta''}{\partial \omega''} = \eta''.$$

and gave, on p.326 of [14], exactly the same system of heat equations in [31]. Observing the work of Weierstrass from the viewpoint of the paper [9], the left-hand sides of (0.10) correspond to $L = 4\pi i \frac{\partial}{\partial \tau}$, namely the operations with respect to the period integrals τ or $\{\omega', \omega'', \eta', \eta''\}$ of the curve, which adopt to the expression (0.2); while the right-hand sides of (0.10) are an interpretation of such operations in order to adopt to the expansion (0.5) of (0.2) given by [31]. Although we suspect there are fruitful correspondences between Weierstrass, Frobenius, and Stickelberger, the authors have no details of these.

It appears difficult to generalise the Weierstrass method to the higher genus cases. There is some hint in the work of Frobenius-Stickelberger to generalise the result to these cases. In order to do so, it seems necessary to have generalisation of relations (0.10). But we do not have naive generalisations of (0.8) and (0.9).

Recently, Buchstaber and Leykin were able to generalise the above results to the sigma functions of higher genus curves ([9], see also [6–8]). In [9], Buchstaber and Leykin generalise (0.10) to higher genus curves by using the first de Rham cohomology H_{dR}^1 of the curve over the base ring, that is the space of the differential forms of the second kind modulo the exact forms (see Section 5.1). The paper [9] is our

main reference for our work. Understanding that paper requires some background on the basic theory of heat equations and singularity theory, so we will summarise their arguments and those of Frobenius and Stickelberger, with hopefully accessible explanations.

We shall explain their method by taking the curve (0.1) as an example. Firstly, we introduce a certain heat equation (the primary heat equation) satisfied by the function defined in (0.11) below, which is a generalisation of the individual terms of the series appearing in the definition (0.2) of $\sigma(u)$. Let us take the subalgebra L generated by L_0 and L_2 over $\mathbb{Q}[\mu_4, \mu_6]$ in the Lie algebra generated by $\frac{\partial}{\partial \mu_4}$ and $\frac{\partial}{\partial \mu_6}$. Thanks to a lemma due to Chevalley (Lemma 2.4) and the *horizontal derivation formula* given in [28] which is explained in Section 2.3, we see that the Lie algebra generated by L_0 and L_2 over $\mathbb{Q}[\mu_4, \mu_6]$ acts on H^1_{dR} . Take a symplectic basis $(\frac{dx}{2y}, \frac{xdx}{2y})$ of H^1_{dR} with respect to a naturally defined inner product in H^1_{dR} (See (3.6)). Let

$$\Gamma^{L} = \begin{bmatrix} -\beta & \alpha \\ -\gamma & \beta \end{bmatrix}$$

be the representation matrix of the action of an operator $L \in L$ (see (5.1)), which is called a *Gauss-Manin connection* in [9]. Then we see that α , β and γ belong to $\mathbb{Q}[\mu_4, \mu_6]$. Taking integrals along the set of closed paths α_1 and β_1 which make a symplectic homology basis of the curve, we see that the action of L gives a linear transformation of the period matrix (see (4.2))

$$arOmega = \left[egin{array}{ccc} \omega' & \omega'' \ \eta' & \eta'' \end{array}
ight]$$

with respect to the basis $(\frac{dx}{2y}, \frac{xdx}{2y})$ and paths α_1 , β_1 . This transformation is also represented by Γ^L as $L(\Omega) = \Gamma^L \Omega$ (see (5.2)). Moreover, we introduce another operator

$$H^{L} = \frac{1}{2} \begin{bmatrix} \frac{\partial}{\partial u} & u \end{bmatrix} \begin{bmatrix} \alpha & \beta \\ \beta & \gamma \end{bmatrix} \begin{bmatrix} \frac{\partial}{\partial u} \\ u \end{bmatrix} = \frac{1}{2} \left(\alpha \frac{\partial^{2}}{\partial u^{2}} + 2\beta u \frac{\partial}{\partial u} + \gamma u^{2} + \beta \right).$$

Then the function

$$G(b, u, \Omega) = \left(\frac{2\pi'}{\omega}\right)^{\frac{1}{2}} \exp\left(-\frac{1}{2}\eta'\omega'^{-1}u^{2}\right) \times \exp\left(2\pi i\left(\frac{1}{2}\omega'^{-1}\omega''b''^{2} + b''(\omega'^{-1}u + b')\right)\right),$$
(0.11)

where $b = [b' \ b'']$ is an arbitrary constant vector, satisfies the heat equation

$$(L - H^{L})G(b, u, \Omega) = 0.$$
 (0.12)

We call this (and its generalisation) the *primary heat equation* (Theorem 5.1). While checking the validity of (0.12) is rather complicated, no details are given by Buchstaber and Leykin, and the description of this equation in [9] is not entirely consistent. We denote the expression of the right-hand side (0.2) without $\Delta^{-\frac{1}{8}}$ by $\tilde{\sigma}(u)$ (see (5.23)). According to the above equation and the fact that $\tilde{\sigma}(u)$ is an infinite sum of the $G(b, u, \Omega)$ s for various b' and b'', we see that $(L - H^L) \tilde{\sigma}(u) = 0$.

At the next stage, we shall check the operators L_0 and L_2 give rise to a system of heat equations which are satisfied by the right-hand side of (0.2), including the factor $\Delta^{-\frac{1}{8}}$. Indeed, these operators are tangent to the singular locus given by $\Delta=0$ (see the former part of Subsection 5.5). The paper [9] uses knowledge of singularity theory and succeeds in generalising nicely the result of Weierstrass and Frobenius-Stickelberger. So we explain techniques from singularity theory to calculate Δ (Lemma 1.21(1)) as well as the operators tangent to the variety defined by $\Delta=0$. This stage is carried out in Subsections 5.3 and 5.5 and the result is given in (5.39).

In summary, the system of heat equations for (0.1) obtained by Weierstrass is

$$(L_{0} - H^{L_{0}}) \sigma(u) = \left(4\mu_{4} \frac{\partial}{\partial \mu_{4}} + 6\mu_{6} \frac{\partial}{\partial \mu_{6}} - u \frac{\partial}{\partial u} + 1\right) \sigma(u) = 0,$$

$$(L_{2} - H^{L_{2}}) \sigma(u) = \left(6\mu_{6} \frac{\partial}{\partial \mu_{4}} - \frac{4}{3}\mu_{4}^{2} \frac{\partial}{\partial \mu_{6}} - \frac{1}{2} \frac{\partial^{2}}{\partial u^{2}} + \frac{1}{6}\mu_{4}u^{2}\right) \sigma(u) = 0,$$

$$(0.13)$$

which is reproved as (6.8). For the general curves, the corresponding results are given as Theorem 5.2 in the text.

It is very important to determine whether the system of heat equations we obtain characterises the sigma function. For the genus one case, it was seen by Weierstrass that the recurrence (0.7) determines all the coefficients if we give an arbitrary value for b(0,0). That is, the solution space of (0.7), as well as (0.13), is of dimension one.

For a general non-singular curve, we consider the multivariate function $\sigma(u)$ defined similarly to (0.2). We can check that the operators we obtain (of Theorem 5.2) kill $\sigma(u)$. However, it is not clear whether the solution space is of dimension one over the base field. The authors could not find any reason which suggests that the solution space is one dimensional. Nevertheless, we shall show that, for any curve of genus less than or equal to three, the solution space is one dimensional by giving an explicit recurrence relation from the system of heat equations we obtain, which is described in Section 6.

Although our main results are in Subsections 6.5, 6.6, 6.7 and 6.8, we give a number of additional useful results, which may be known only by specialists, with detailed proofs in Section 5 and Subsection 6.2. Subsection 6.3 reproduces the classical result and it would be helpful to read the following Subsections. Subsection 6.4 is rewritten in a slightly different formulation (Hurwitz-type series expansion of $\sigma(u)$) from [8].

We shall explain here a notion called *modality* which was introduced by Arnol'd (see 1.3 for details). For any co-prime positive integers (e, q) with e < q, we consider a family of the curves found by certain deformations of the singularity at the origin of the curve $y^e = x^q$ (we do not use these words in the text of this paper). This family of curves is called the (e, q)-curve, which is a type of plane telescopic curve. The number of parameters necessary for this deformation is less than or equal to (e-1)(q-1). The last number is twice the genus of a generic curve of the family. The difference between (e-1)(q-1) and the number of parameters is called the *modality* of this family. For instance, the curve (0.1) is regarded as the whole of the semi-universal deformations of $y^2 = x^3$ with two parameters μ_4 and μ_6 , which is equal to twice its genus (i.e. $2 = 1 \times 2$). In this case, the modality is 0. It is known that the hyperelliptic curve given by such deformations in the case e = 2 is of modality 0. There are only two types of nonhyperelliptic plane telescopic curves of modality 0, which are the trigonal quartic curve, the (3, 4)-curve (genus three), and the trigonal quintic curve, the (3, 5)-curve (genus four). Concerning these two curves, we treat only the former one, the (3, 4)-curve, in this paper. More general curves including the (3, 5)curve are discussed in [28]. For a general hyperelliptic curve, we give its corresponding system of heat equations in Lemma 6.1. For any plane telescopic curve, we gave a simple formula for its modality in Proposition 1.10.

In the last paragraph of Section 2 in [9], there is some description of the positive modality case. On the one dimesionality problem of the solution space of the case e=2 and some positive modality cases, we refer the reader to the forthcoming paper [28].

We shall mention two additional consequences of this theory. Firstly, for hyperelliptic curves of genus less than or equal to three, we again prove partially the result of [27] on Hurwitz integrality of the expansion of the sigma function. For example it is obvious from (0.7) that $b(n_4, n_6) \in \mathbb{Z}[\frac{1}{3}]$. Similar results are shown for the hyperelliptic curves of genus two and three. This idea was suggested to Y.Ô. by Buchstaber. Secondly, this theory of heat equations in turn helps the construction of the sigma function, as explained in Lemma 4.17 of [8] (see also Section 5.6).

However, it might be possible to approach this problem via the results of Bernatska [3, 4] to get the top factor for a hyperelliptic curve corresponding to that of (0.2).

The formula (0.2) is well-known for the curve (0.1), and its generalisation (see (4.16)) is proved for the genus two hyperelliptic curve by Grant [16] by using Thomae's formula. For any curve in the family we have investigated, there is a rough explanation in Lemma 2.3 in p.98 of [7], but without using Thomae's formula.

Here, we mention the discriminant for a plain telescopic curve \mathscr{C} . There is nice algorithm using a certain determinant to compute the discriminant of \mathscr{C} as explained in 1.21 and 5.36. However, there is still a gap in this theory; that is, we do not have a general proof of coincidence of the discriminant and the determinant. If we know the weight of the discriminant in general, our idea of the proof of 5.36 works well.

We explain here that BL theory indeed gives a method to prove such a formula as (0.2) on the sigma functions, at least, for our curves of genus less than or equal to three. Firstly, assuming the expression (0.2) to be the correct sigma function, we show that it satisfies the system of heat equations. On the other hand, as we mentioned above, the solution space of the system is one dimensional and the system of heat equations gives a recursion relation, by which we have the power series expansion of the solution as shown in Section 3. Especially, we see the solution space is of dimension one. Therefore, we have a proof that the assumed expression of the sigma indeed gives the sigma function up to a non-zero absolute constant. This result is the main theorem of the present paper (see Theorem 5.3).

Finally, one of the authors S.Y. wishes to point out to the reader that his contribution on this paper is limited to the proof of the case e = 2 in Proposition 5.41.

Convention. We use the following convention. As usual, we denote by \mathbb{Z} , \mathbb{Q} , \mathbb{R} , and \mathbb{C} the ring of integers, the field of rationals, the field of real numbers, the field of complex numbers, respectively. We denote by i the imaginary unit. Mat(n, R) denotes the ring of square matrices of size n with all the entries in a ring R. Sym(n, R) denotes the set of symmetric matrix in Mat(n, R). A stands for the transpose of a matrix A. The variable of the rows and the columns of a matrix A.

1. Preliminaries

1.1. The curves

We shall use e and q instead of n and s, respectively, of the (n, s)-curves, which was usual in many previous papers on generalised sigma functions. Especially, the name (n, s)-curve (which comes from singularity theory) is used by Buchstaber and Leykin in their papers, but we wish to avoid confusion with the many n used as subscripts in sections from Section 6 onward, and the use of s for Schur polynomials in Subsection 4.1.

So, we let e and q be two fixed positive integers such that e < q and gcd(e, q) = 1. We define, for these integers, a polynomial of indeterminates X and Y

$$f(X,Y) = Y^{e} - p_{1}(X)Y^{e-1} - \dots - p_{e-1}(X)Y - p_{e}(X), \tag{1.1}$$

where $p_j(X)$ is a polynomial of X of degree $\lceil \frac{jq}{e} \rceil$ or smaller and its coefficients, which are also indeterminates, are denoted by

$$p_{j}(X) = \sum_{k: jq - ek > 0} \mu_{jq - ek} X^{k} \quad (1 \le j \le e - 1),$$

$$p_{e}(X) = X^{q} + \mu_{e(q - 1)} X^{q - 1} + \dots + \mu_{eq}.$$
(1.2)

Please note that the sign at the front of each $p_j(X)$ with $j \neq e$ in f(X, Y) is different from previous papers written by some of the authors. The base ring over which we work is quite general. For simplicity, the reader may start by taking the field $\mathbb C$ of complex numbers and assume the μ_i s to be constants belonging to this field. Let $\mathscr{C} = \mathscr{C}_{\mu}^{e,q}$ be the projective curve defined by

$$f(x, y) = 0 \tag{1.3}$$

having a unique point ∞ at infinity. This means (x, y) is a generic point of \mathscr{C} in the classical terminology. As the general elliptic curve is defined by an equation of the form

$$y^2 - (\mu_1 x + \mu_3)y = x^3 + \mu_2 x^2 + \mu_4 x + \mu_6$$

the curves $\mathscr C$ discussed here are a natural generalisation of elliptic curves.

The reason why we omit the terms of μ_i with j < 0 from f(X, Y) is seen in the proof of 1.17.

Basically our situation is that all the coefficients μ_j of f(X, Y) should be indeterminates. We denote by $\mathbb{Q}[\mu]$ the ring generated over the rationals \mathbb{Q} by all the μ_j s. Then we shall treat \mathscr{C} as a scheme over the Spec $\mathbb{Q}[\mu]$. Since we need to use analytic methods from time to time, we freely switch the standing position where μ_j s are assumed to be complex numbers or indeterminates.

This \mathscr{C} should be called an (e,q)-curve following Buchstaber, Enolskii, and Leykin [10], or a plane telescopic curve after the paper [21]. Assuming all the μ_j s are complex numbers, the genus of \mathscr{C} is (e-1)(q-1)/2 provided that it is non-singular. We will use g to denote this quantity throughout this paper whether the curve \mathscr{C} is non-singular or singular as well as in the case of the μ_j s being indeterminates: g = (e-1)(q-1)/2. In this paper, we denote by

$$f_X(x, y)$$
 or $f_1(x, y)$ [resp. $f_Y(x, y)$ or $f_2(x, y)$]

the polynomials obtained by substitution X = x, Y = y for the partial derivative of the polynomial f(X, Y) with respect to X [resp. Y]

Now we introduce a weight function as follows. For a point (x, y) in the curve \mathscr{C} given by (1.1), we define the weight wt() on $\mathbb{Q}[\mu][x, y]$ and $\mathbb{Q}[\mu][X, Y]$ by

$$wt(\mu_i) = -j, \quad wt(x) = wt(X) = -e, \quad wt(y) = wt(Y) = -q.$$
 (1.4)

Then all the equations for functions, power series, differential forms, and so on in this paper are of homogeneous weight. We see that $\operatorname{wt}(f(X,Y)) = -eq$. We will extend the notion of weight (1.4) in Subsection 4.2.

1.2. Definition of the discriminant

We shall define the discriminant of the curve \mathscr{C} .

Definition 1.5. Suppose all the μ_j s are indeterminates. The discriminant Δ of the form f(X,Y) or of the curve $\mathscr C$ defined by f(x,y)=0 is the polynomial (up to the signs \pm) of the least degree in the μ_j s with integer coefficients such that the greatest common divisor of the coefficients is 1, and every zero of Δ corresponds exactly to the case that $\mathscr C$ has a singular point.

For a curve \mathscr{C}_0 given by some fixed constants $\mu_j \in \mathbb{C}$, we always define its discriminant as the one obtained by substituting these constants to the discriminant Δ defined in 1.5. For instance, if (e, q) = (2, 3), then

$$f(X,Y) = Y^2 - (\mu_1 X + \mu_3)Y - (X^3 + \mu_2 X^2 + \mu_4 X + \mu_6)$$

and its discriminant is given by

$$\Delta = -\mu_6 \mu_1^6 + \mu_3 \mu_4 \mu_1^5 + ((-\mu_3^2 - 12\mu_6)\mu_2 + \mu_4^2)\mu_1^4$$

$$+ (8\mu_3 \mu_4 \mu_2 + \mu_3^3 + 36\mu_6 \mu_3)\mu_1^3 + ((-8\mu_3^2 - 48\mu_6)\mu_2^2 + 8\mu_4^2 \mu_2$$

$$+ (-30\mu_3^2 + 72\mu_6)\mu_4)\mu_1^2 + (16\mu_3 \mu_4 \mu_2^2 + (36\mu_3^3 + 144\mu_6 \mu_3)\mu_2 - 96\mu_3 \mu_4^2)\mu_1$$

$$+ (-16\mu_3^2 - 64\mu_6)\mu_2^3 + 16\mu_4^2 \mu_2^2 + (72\mu_3^2 + 288\mu_6)\mu_4 \mu_2$$

$$- 64\mu_4^3 - 27\mu_3^4 - 216\mu_6 \mu_3^2 - 432\mu_6^2.$$

$$(1.6)$$

Specialising $\mu_1 = \mu_3 = \mu_2 = 0$, we have the discriminant $\Delta = -16(4\mu_4^3 + 27\mu_6^2)$ of the curve defined by the Weierstrass form $y^2 = x^3 + \mu_4 x + \mu_6$ which appeared in (0.1).

For (e, q) = (2, 2g + 1), as in Section 1.3, we rewrite the equation as $y^2 = x^{2g+1} + \cdots$, where the right-hand side is a polynomial of x only. Then the discriminant of this curve is a non-zero integer multiple of the discriminant of the right-hand side as a polynomial of x only. For the (3, 4)-curve, we have Sylvester's method as described in [15] pp.118-120, as explained to the authors by C. Ritzenthaler. However, Lemma 1.21 below gives a quite general method, which seems to cover the (3, 5)-curve and more. We do have explicit forms of the discriminants of the curves with (e, q) = (2, 3), (2, 5), (2, 7), (3, 4) which we treat in this paper. Using the resultant of two forms, we mention here an alternative (but conjectural) construction for the interest of the reader, though it is essentially not used in this paper.

Definition 1.7. Let the coefficients μ_i of (1.1) be indeterminates, and define

$$R_1 = \operatorname{rslt}_X \left(\operatorname{rslt}_Y (f(X, Y), f_1(X, Y)), \operatorname{rslt}_Y (f(X, Y), f_2(X, Y)) \right),$$

$$R_2 = \operatorname{rslt}_Y \left(\operatorname{rslt}_X (f(X, Y), f_1(X, Y)), \operatorname{rslt}_X (f(X, Y), f_2(X, Y)) \right),$$

$$R = \gcd(R_1, R_2) \quad \text{in } \mathbb{Z}[\mu].$$

Here $rslt_Z$ is the Sylvester resultant with respect to Z.

Now we recall the conjecture from the paper [13].

Conjecture 1.8. Defining R by 1.7, we have the following: (1) R is always a perfect square in $\mathbb{Z}[\mu]$ and $R = \Delta^2$; (2) The discriminant Δ of the (e, q)-curve is of weight -2eqg = -eq(e-1)(q-1).

Remark 1.9. It can be confirmed that (1) of 1.8 is correct for the cases (e, q) = (2, 3), (2, 5), (2, 7), (3, 4), and (3, 5). Actually, computation by Maple for these cases shows that R is a square of some $\Delta' \in \mathbb{Z}[\mu]$. It is easy to check by Maple that Δ' is irreducible. Then, from the definition of R, we see Δ' must be Δ up to the sign, and we checked (2) of 1.8 for these cases. We prove also that (2) of 1.8 is true if $\gcd(e-1, q-1) = 1$ in 5.36.

1.3. The Weierstrass form of the curve and its modality

Starting from the equation f(x, y) = 0 in (1.1) and removing the terms of y^{e-1} and x^{q-1} by replacing y by $y + \frac{1}{e} p_1(x)$, and x by $x + \frac{1}{q} \mu_{(q-1)e}$, respectively, we get a new equation f(x, y) = 0 which is called the *Weierstrass form* of the original one. After making such transformations, we re-label the coefficients by μ_i .

For example, if (e, q) = (2, 2g + 1), the new equation is

$$f(x,y) = y^2 - (x^{2g+1} + \mu_{4g-2}x^{2g-1} + \mu_{4g-4}x^{2g-2} + \dots + \mu_{4g+2}) = 0;$$

and if (e, q) = (3, 4), the new one is

$$f(x, y) = y^3 - (\mu_2 x^2 + \mu_5 x + \mu_8)y - (x^4 + \mu_6 x^2 + \mu_9 x + \mu_{12}) = 0.$$

In these cases, the number of remaining μ_j s is 2g. However, in general, we can have some cases such that this number is less than 2g. The difference

$$2g$$
 – "the number of μ_i "

is called the *modality* (a term used in singularity theory) of the (e, q)-curve. We give here a simple formula giving modalities and, especially, determine all the curves of modality 0.

Proposition 1.10. The modality of an (e, q)-curve is given by $\frac{1}{2}(e-3)(q-3) + \lfloor \frac{q}{e} \rfloor - 1$. The only curves of modality 0 are the (2, 2g+1)-, (3, 4)-, and (3, 5)-curves.

Proof. The number of μ_i s appearing in the Weierstrass form is

$$\sum_{j=1}^{e-2} \left(\left\lfloor \frac{(e-j)q}{e} \right\rfloor + 1 \right) + (q-1) = \frac{1}{2} \sum_{j=1}^{e-1} \left(\left\lfloor \frac{(e-j)q}{e} \right\rfloor + \left\lfloor \frac{jq}{e} \right\rfloor \right) - \left\lfloor \frac{q}{e} \right\rfloor + (e-2) + (q-1)$$

$$= \frac{1}{2} \sum_{j=1}^{e-1} (q-1) - \left\lfloor \frac{q}{e} \right\rfloor + e + q - 3 = \frac{1}{2} (e-1)(q-1) + e + q - 3 - \left\lfloor \frac{q}{e} \right\rfloor.$$

Subtracting the above result from 2g = (e-1)(q-1) gives the required expression. The latter part follows directly from this. This completes the proof.

On the case for a curve with positive modality, there is some description in [9] (the end of Section 2). Since it is not clear for us how positive modality causes difficulty, we do not discuss this theme here, though we give an example of positive modality in 1.16.

From now to the end of the paper, we always assume that the equation f(x, y) = 0 of the curve \mathscr{C} is given by a Weiserstrass form and the modality of \mathscr{C} is 0.

1.4. Weight

We recall that (1.1), that is

$$f(X,Y) = Y^e - X^q - \sum_{\substack{0 \le i \le q-2 \\ 0 \le j \le e-2 \\ ie + iasea}} \mu_{eq-ie-jq} X^i Y^j.$$

We define, for any pair (i, j) with $0 \le i \le q - 2$, $0 \le j \le e - 2$

$$M_{ei+qj} = M_{ei+qj}(X, Y) = X^{i}Y^{j} \text{ and}$$

$$\text{wt}(M) = \{-\text{wt}(X^{i}Y^{j}) (= -\text{wt}(M_{ei+qj}(X, Y)) \mid 0 \le i \le q - 2, 0 \le j \le e - 2\}$$

$$= \{-(ei+qi) \mid 0 < i < q - 2, 0 < j < e - 2\}.$$
(1.12)

The sequence constituted by the elements in -wt(M) in increasing order is denoted by

$$v_1(=0)$$
, $v_2(=e)$, v_3 , \cdots , v_{2g-2} , $v_{2g-1}(=4g-2-e)$, $v_{2g}(=4g-2)$.

Because of the assumption gcd(e, q) = 1, for any $v \in wt(M)$ there exists a unique pair (i, j) such that $0 \le i \le q - 2$, $0 \le j \le e - 2$ and $M_v = X^i Y^j$. We introduce the notation

$$M(X, Y) = {}^{t}[M_{v_{j}}(X, Y) \ (j = 1, 2, \cdots, 2g)],$$

$${}^{rev}M(X, Y) = {}^{t}[M_{v_{j}}(X, Y) \ (j = 2g, 2g - 1, \cdots, 1)].$$

$$(1.13)$$

We denote the Weierstrass gap sequence of the semigroup generated by e and q in the positive integers in the increasing order by

$$w_1(=1), w_2, \cdots, w_q(=2g-1),$$
 (1.14)

which is also the Weierstrass gap sequence of \mathscr{C} at ∞ . Namely, this is the unique (finite) increasing sequence of positive integers which cannot be written in the form ae + bq with non-negative integers a, b. We denote the set of the terms in (1.14) by

$$wgs(e, q)$$
.

It is well-known that each term of the sequence is written in the form

$$w_i = 2g - 1 - v_{g-j+1} \quad (1 \le j \le g),$$

and that the assumption gcd(e, q) = 1 implies the Young tableaux associated with the sequence

$$w_{2g} - (g-1), w_{2g-1} - (g-2), \cdots, w_2 - 1, w_1 - 0$$

given by the Weierstrass gap sequences is symmetric with respect to the diagonal line from the top-left to the bottom-right. The terms in the sequence $\{v_j\}_{j=1}^{2g}$ are written also as

$$v_{j} = \begin{cases} 2g - 1 - w_{g-j+1} & \text{if } 1 \le j \le g, \\ 2g - 1 + w_{j-g} & \text{if } g + 1 \le j \le 2g. \end{cases}$$

We see that all the terms $\{M_{v_j}(X, Y)\}$ appear in f(X, Y) provided the *modality* of the curve is 0. We shall give below sample values of the data above for the convenience of the reader to follow the calculation in Section 6.

Finally, we introduce the following notation on the coefficients μ_i ;

$$\mu = \{ \mu_{eq-ie-jq} ; 0 \le i \le q-2, \ 0 \le j \le e-2, \ ie+jq \le eq \},$$

and

$$wt(\mu) = \{-wt(\mu_{eq-ie-jq}); 0 \le i \le q-2, \ 0 \le j \le e-2, \ ie+jq \le eq \}$$
$$= \{-(eq-ie-jq); 0 \le i \le q-2, \ 0 \le j \le e-2, \ ie+jq \le eq \}.$$

Example 1.15. If (e, q) = (2, 2g + 1), then the M_i s are given as follows:

j	1	2		g	g+1	g+2		2g	
w_{g-j+1}	2g - 1	2g - 3	• • •	1	1	3	• • •	2g - 1	w_{j-g}
				2g - 2					
$M_{\nu_j}(X,Y)$	1	X		X^{g-1}	X^g	X^{g+1}	• • •	X^{2g-1}	

If (e, q) = (3, 4) or (3, 5), then the M_i s are given as follows:

$$(3,4) - \text{curve:} \begin{array}{|c|c|c|c|c|c|c|c|c|}\hline j & 1 & 2 & 3 & 4 & 5 & 6 \\ \hline w_{3-j+1} & 5 & 2 & 1 & 1 & 2 & 5 & w_{j-3} \\ \hline v_j & 0 & 3 & 4 & 6 & 7 & 10 \\ \hline M_{v_j}(X,Y) & 1 & X & Y & X^2 & XY & X^2Y \\\hline \end{array}$$

All these examples, and only these, are of modality 0 as explained in (1.10).

5 6 7 8 10 11 12 11 5 4 2 1 1 2 4 5 8 11 W_{6-i+1} 3 6 7 9 10 12 13 15 16 19 22 v_i $\overline{M_{v_i}(X,Y)}$ $X X^2$ Y X^3 XY X^4 X^2Y X^5 X^3Y X^4Y X^5Y

Example 1.16. In contrast to the cases above, we have for (e, q) = (3, 7):

However, the Weierstrass form of the (3,7)-curve is given by

$$Y^{3} - (\mu_{2}X^{4} + \mu_{5}X^{3} + \mu_{8}X^{2} + \mu_{11}X + \mu_{14})Y$$
$$- (X^{7} + \mu_{6}X^{5} + \mu_{9}X^{4} + \mu_{12}X^{3} + \mu_{15}X^{3} + \mu_{18}X + \mu_{21})$$

and this equation does not include a term in $M_{22}(X, Y) = X^5Y$. This curve is of modality 1. We will not discuss this curve further in this paper.

1.5. The representation matrix for f(X, Y)-multiplication

In this subsection, we shall define a certain matrix $T \in \text{Mat}(2g, \mathbb{Q}[\mu])$ whose determinant might be essentially the discriminant of Δ .

Lemma 1.17. As a $\mathbb{Q}[\mu]$ -module, $\mathbb{Q}[\mu][X,Y]/(f_1(X,Y),f_2(X,Y))$ is of rank 2g and spanned by M(X,Y) which is defined in (1.13).

Proof. (1) Let G(X, Y) be any element in $\mathbb{Q}[\mu, X, Y]$. Paying attention to the weight with respect to X and Y, we are reducing the terms in G(X, Y) to lower degree by using $f_1(X, Y) = \cdots - qX^{q-1} + \cdots$ and $f_2(X, Y) = eY^{e-1} + \cdots$. Whenever we reduce degrees of highest weight term(s) of G(X, Y) by using one of these relations, G(X, Y) is replaced by a lower degree polynomial. So we will finally arrived at a polynomial that is a linear combination of only terms in M(X, Y).

Definition 1.18. The transpose of the representation matrix of the (-eq)f(X, Y)-plication map

$$\cdot (-eq) f(X,Y) : \mathbb{Q}[\boldsymbol{\mu}][X,Y]/(f_1,f_2) \longmapsto \mathbb{Q}[\boldsymbol{\mu}][X,Y]/(f_1,f_2) \tag{1.19}$$

with respect to the basis M(X, Y) is denoted by $T \in \text{Mat}(2g, \mathbb{Q}[\mu])$, that is

$$-eq f(X, Y)M(X, Y) \equiv M(X, Y)^{T} \mod (f_1, f_2).$$
 (1.20)

We define the subscript of the entries in T as follows. The row-index a runs through wt(M) in increasing order, and b runs through $wt(\widetilde{\mu})$ in decreasing order, and we write

$$T = [T_{a,b}] \in Mat(2g, \mathbb{Q}[\mu])$$

Then we have $\operatorname{wt}(T_{a,b}) = -(a+b)$. This is written in the usual manner as $T = [T_{v_1, eq-v_{2a+1-i}}]$.

One of the reasons why we have an extra factor -eq in (1.19) appears in 5.33 later.

Lemma 1.21. We have the following:

- 1. The determinant $\det(T)$ of the matrix T as defined in 1.18 is a non-zero rational constant multiple of a power of Δ .
- 2. The linear map (1.19) is of rank 2g.

Proof. (1) We assume all the coefficients μ_j are constants in \mathbb{C} . We have $\det(T) = 0$ if and only if the rank (called the Tjurina number at μ) of the co-kernel $\mathbb{Q}[\mu][X,Y]/(f,f_1,f_2) = \mathbb{Q}[x,y]/(f_1,f_2)$ (which is the dimension of $\mathbb{C}[X,Y]/(f,f_1,f_2)$ over \mathbb{C}) of the map is positive. This is exactly the case that the ideal (f,f_1,f_2) does not contain $1 \in \mathbb{Q}[\mu][X,Y]$. By Hilbert's Nullstellensatz (Theorem 5.4(i) in [20], for instance), we see this is equivalent to existence of a $(x,y) \in \mathbb{C}^2$ such that

$$f(x, y) = f_1(x, y) = f_2(x, y) = 0.$$
 (1.22)

Conversely $\Delta = 0$ means (1.22), and it implies the co-kernel is non-trivial. Therefore the zeroes of Δ and those of det (T) coincide. So det (T) must be a non-zero rational constant multiple of a power of Δ . (2) Since det (T) $\neq 0$ by virtue of (1), this is obvious.

Now we present the following:

Conjecture 1.23. *The determinant* det (T) *is irreducible in* $\mathbb{Q}[\mu]$.

For each (e, q), if this conjecture is true then we have immediately from 1.21 that

$$\det\left(T\right)=c\cdot\Delta\quad\text{for some }c\in\mathbb{Q}^{\times}.$$

We give the explicit value of c above for the cases in Sections 6.3, 6.4, 6.5 and 6.7.

2. The horizontal derivation formula

Much of this section was lacking in the previous versions of this paper. However, the authors are pleased that the horizontal derivation formula (see 2.1 below) and its closely related results been used in the work of [28], and these results make our arguments in the rest of the present paper much clearer.

2.1. Preliminary on derivations

In this subsection, we prepare a general notation for the succeeding subsections. Let A be a commutative ring. A map $D: A \longrightarrow A$, $a \mapsto Da$ satisfying the following properties is called a *derivation* on A; for any $a, b \in A$,

$$D(a+b) = Da + Db$$
, $D(ab) = (Da)b + a(Db)$.

We denote by Der(A) the set of all derivations on A, which is an A-module. Since Der(A) is equipped with the natural Lie bracket

$$[D_1, D_2] = D_1D_2 - D_2D_1$$
 $(D_1, D_2 \in Der(A)),$

Der(A) is a Lie algebra over A. Let M and N be two A-modules and $D \in Der(A)$ be a fixed derivation on A. A map $\widetilde{D}: M \longrightarrow N, m \mapsto \widetilde{D}m$ satisfying

$$\widetilde{D}(m_1 + m_2) = \widetilde{D}m_1 + \widetilde{D}m_2, \quad \widetilde{D}(am) = (Da)m + a\widetilde{D}m$$

is called a *derivation from M to N associated with D*. We denote by $Der_A(M, N; D)$ the set of the derivations from M to N associated with D. If M = N, then we denote this simply by

 $\operatorname{Der}_A(M;D) = \operatorname{Der}_A(M,M;D)$. Let $D_1, D_2 \in \operatorname{Der}(A)$, and $\widetilde{D}_1 \in \operatorname{Der}_A(M,N;D_1)$, $\widetilde{D}_2 \in \operatorname{Der}_A(M,N;D_2)$. Then we see that

$$a\widetilde{D}_1 \in \operatorname{Der}_A(M, N; aD_1) \ (a \in A), \ \widetilde{D}_1 + \widetilde{D}_2 \in \operatorname{Der}_A(M, N; D_1 + D_2).$$

Now let *B* be an *A*-algebra and take a derivative $D \in \operatorname{Der}(A)$. Let *M* and *N* be two *B*-modules, hence also *A*-modules. Regarding *B* as an *A*-module, we take a derivation $\widetilde{D} \in \operatorname{Der}_A(B;D)$ associated with $D \in \operatorname{Der}(A)$. Since we can regard naturally $\widetilde{D} \in \operatorname{Der}(B)$, we have the inclusion

$$\operatorname{Der}_{B}(M, N; \widetilde{D}) \subset \operatorname{Der}_{A}(M, N; D).$$

For $\widetilde{D}_1 \in \operatorname{Der}_A(M; D_1)$, $\widetilde{D}_2 \in \operatorname{Der}_A(M; D_2)$, and for any $a \in A$, $m \in M$, we have

$$[\widetilde{D}_1, \ \widetilde{D}_2] \ (= \widetilde{D}_1 \widetilde{D}_2 - \widetilde{D}_2 \widetilde{D}_1) \in \operatorname{Der}_A(M; [D_1, D_2]),$$

since $\widetilde{D}_1\widetilde{D}_2(am) = (D_1D_2a)m + (D_2a)(\widetilde{D}_1m) + (D_1a)(\widetilde{D}_2m) + a\widetilde{D}_1\widetilde{D}_2m$. This implies that if \widetilde{D}_1 and $\widetilde{D}_2 \in \operatorname{Der}_A(M;D)$ for a derivation $D \in \operatorname{Der}(A)$, then

$$[\widetilde{D}_1, \ \widetilde{D}_2] \in \operatorname{Der}_A(M;0),$$

where 0 stands for the 0-map from A to A itself, which is a derivation on A. Namely, $[\widetilde{D}_1, \ \widetilde{D}_2]$ is a A-homomorphism. In the set of all maps from M to M, we take union of these sets over Der(A) and denote it as

$$\operatorname{Der}_{A}(M) = \bigcup_{D \in \operatorname{Der}(A)} \operatorname{Der}_{A}(M;D).$$

This is also a Lie algebra over A. Instead of writing $D \in Der_A(M)$, we can also say that the derivation D acts on M, for instance.

2.2. Chevalley's lemma

We quote the following without proof from [11], p.112, Lemma 2.

Lemma 2.1. Let K be a field and R be a function field of one variable with K the field of constants. Take a transcendental element ξ in R over K and fix it. For $D \in Der(K)$, there exists a unique derivation $D_{\xi} \in Der_{K}(R;D)$ satisfying

$$D_{\varepsilon}(\xi) = 0.$$

Corollary 2.2. Suppose a derivation $D \in \text{Der}(\mathbb{Q}[\mu])$ and an element ξ in $\mathbb{Q}[\mu, x, y]$ transcendental over $\mathbb{Q}(\mu)$ are given. There is a unique extension $D_{\xi} \in \text{Der}_{\mathbb{Q}[\mu]}(\mathbb{Q}(\mu, x, y), D)$ of D satisfying

$$D_{\varepsilon}(\xi) = 0.$$

Proof. We regard ξ to be an element in $\mathbb{Q}(\mu, x, y)$. Since D extends to an element in $\mathrm{Der}(\mathbb{Q}(\mu))$ as usual, the statement follows from 2.1.

Under the situation of 2.1, we extends D_{ξ} to a derivation $\widetilde{D_{\xi}}$ on the space of differentials $R d\xi$ via

$$\widetilde{D_{\xi}}(\omega) = D_{\xi}\left(\frac{\omega}{d\xi}\right)d\xi \quad \text{for any } \omega \in R \ d\xi. \tag{2.3}$$

Namely, we have $\widetilde{D_{\xi}} \in \operatorname{Der}_{R}(R d\xi; D_{\xi}) \subset \operatorname{Der}_{K}(R d\xi; D)$. However, in the following lemma, $\widetilde{D_{\xi}}$ is denoted by D_{ξ} for simplicity.

Lemma 2.4. (Chevalley [11], p.125, Lemma 3) Here we use the notation above. Let ξ and ζ be two transcendental elements in R over K. Then we have the following relation between D_{ξ} and D_{ζ} . For any

 $w \in R$, we have

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$$D_{\xi}(wd\xi) - D_{\zeta}(wd\xi) = d(-wD_{\zeta}\xi).$$

Proof. (From Manin [19]) The operator $D_{\xi} - D_{\zeta} + (D_{\zeta}\xi)\frac{d}{d\xi}$ is a derivative on R which vanishes on K and also kills ξ . By the uniqueness of extension of a derivation on K to R, this vanishes on R. So that

$$(D_{\xi} - D_{\zeta})w + (D_{\zeta}\xi)\frac{dw}{d\xi} = 0.$$

Moreover $(D_{\xi} - D_{\zeta})(wd\xi) = (D_{\xi} - D_{\zeta})w \cdot d\xi + w \cdot (D_{\xi} - D_{\zeta})d\xi$. Since ζ is transcendental, we see $\frac{d}{d\zeta}D_{\zeta} = D_{\zeta}\frac{d}{d\zeta}$ by 2.16 below or [11], p.125, Lemma 1, and have

$$D_{\xi}d\xi = D_{\xi}\left(\frac{d\xi}{d\xi}\right)d\xi = 0, \quad D_{\zeta}d\xi = D_{\zeta}\left(\frac{d\xi}{d\zeta}\right)d\zeta = \frac{d}{d\zeta}(D_{\zeta}\xi)d\zeta = d(D_{\zeta}(\xi)).$$

Therefore

$$(D_{\xi} - D_{\zeta})(wd\xi) = -(D_{\zeta} \xi) \frac{dw}{d\xi} d\xi - w \cdot d(D_{\zeta} \xi) = -d(wD_{\zeta} \xi)$$

as desired.

For an explicit sample calculation, see Section 6.3 on the derivation $\frac{\partial}{\partial \mu_i}$.

2.3. The horizontal derivation formula

We present a useful formula 2.1 called the *horizontal derivation formula*, which is important for our definition of the first de Rham cohomology equipped with a structure of a differential module and eventually giving a sophisticated algorithm to compute the Gauss-Manin connection Γ_j (a sort of Christoffel symbol). The formula was obtained by Kouki Sato while working on [28], and coauthors of that paper have permitted us to quote from it. This formula would be useful for various applications.

In addition to the matrix $T = [T_{ij}]$ in 1.18, we introduce A_{i+e} and $B_{i+e} \in \mathbb{Q}[\mu, X, Y]$ for each $i \in \text{wt}(M)$ defined by

$$-eq \cdot M_i \cdot f(X, Y) = \sum_{j \in wt(M)} T_{ij} M_j + A_{i+e} f_X + B_{i+q} f_Y,$$
 (2.5)

where f(X, Y) is the defining polynomial of \mathscr{C} and $M_i = M_i(X, Y)$ is the one defined in 1.12. In this notation, we have

$$\operatorname{wt}(A_{i+e}) = -(i+e), \quad \operatorname{wt}(B_{i+q}) = -(i+q).$$

We denote by

$$\frac{\partial}{\partial \mu_j} \in \mathrm{Der}_{\mathbb{Q}[\mu]} \left(\mathbb{Q}(\mu, x, y); \frac{\partial}{\partial \mu_j} \right)$$

the derivation uniquely determined by 2.2 as an extension of the derivation $\frac{\partial}{\partial \mu_j} \in \text{Der}(\mathbb{Q}[\mu])$ having the property

$$\frac{\partial}{\partial \mu_i} x = 0. {(2.6)}$$

Namely, we use the same notation for the extension. It is natural to define the weight to be

$$\operatorname{wt}\left(\frac{\partial}{\partial \mu_{i}}\right) = j. \tag{2.7}$$

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Moreover, there is a unique extension $\widetilde{\ell}_i$ of the derivation

$$\ell_i = \sum_i T_{ij} \frac{\partial}{\partial \mu_j} \in \text{Der}(\mathbb{Q}[\mu])$$
 (2.8)

satisfying

$$\widetilde{\ell}_i x = 0$$
,

by 2.2 again, for which we use the same notation

$$\widetilde{\ell}_{i} = \sum_{i} T_{ij} \frac{\partial}{\partial \mu_{i}} \in \operatorname{Der}_{\mathbb{Q}[\mu]}(\mathbb{Q}(\mu, x, y); \ell_{i}). \tag{2.9}$$

Therefore, for a 1-form $\omega \in \mathbb{Q}(\mu, x, y) dx$, defining $\overline{\ell_i}$ by

$$\overline{\ell_j}(\omega) = \widetilde{\ell_j}\left(\frac{\omega}{dx}\right) dx$$

as (2.3) (be careful as this depends on the condition (2.6)), and we have an extension

$$\overline{\ell_i} \in \mathrm{Der}_{\mathbb{O}[\mu]}(\mathbb{Q}(\mu, x, y)dx; \ell_i). \tag{2.10}$$

However, we omit ~ and ~ for simplicity, and use the notation

$$\ell_i = \sum_i T_{ij} \frac{\partial}{\partial \mu_j}$$

for these extensions. This convention will be practical.

In this paper, for a polynomial $G = G(\mu, X, Y) \in \mathbb{Q}[\mu, X, Y]$, we denote by $(G)_x = G_x$, $(G)_y = G_y$, and $(G)_{\mu_j} = G_{\mu_j}$ the polynomials given by the substitution (X, Y) = (x, y) to the partial derivations $\frac{\partial}{\partial X} G(\mu, X, Y)$, $\frac{\partial}{\partial X} G(\mu, X, Y)$, and $\frac{\partial}{\partial \mu_j} G(\mu, X, Y)$. This rule is applied also for f(X, Y). Moreover, the higher-order case is similarly defined. For example, f_{yy} means the quantity given by the substitution (X, Y) = (x, y) to $\frac{\partial^2}{\partial Y^2} f(X, Y)$.

Under this convention, we present the following formula, which is mainly used for 3.2.

Theorem 2.11. (the horizontal derivation formula) Let N = N(X, Y) be a monomial of X and Y (with non-negative powers), and $P \in \mathbb{Q}[\mu]$ be an arbitrary polynomial. Then we have the following formula:

$$\ell_{j} \left(\frac{P \cdot N}{f_{y}} dx \right) = P \frac{(N)_{y} B_{j+q} - N(M_{j} + (B_{j+q})_{y}) - (N A_{j+e})_{x}}{f_{y}} dx + \ell_{j}(P)N \frac{dx}{f_{y}} + d\left(P \frac{NA_{j+e}}{f_{y}}\right). \tag{2.11}$$

Especially, if e = 2 then we have

$$\ell_{j}\left(\frac{M_{k} dx}{f_{y}}\right) = \frac{-(M_{k} A_{j+2})_{x} - M_{j+k}}{2y} dx + d\left(\frac{M_{k} A_{j+2}}{f_{y}}\right).$$

Remark 2.13. The formula (2.11) shows

$$\ell_{j} \in \operatorname{Der}_{\mathbb{Q}[\mu]} \left(\mathbb{Q}[\mu, x, y] \frac{dx}{f_{y}}, \ \mathbb{Q}[\mu, x, y] \frac{dx}{f_{y}} + d \left(\mathbb{Q}[\mu, x, y] \frac{1}{f_{y}} \right); \ell_{j} \right). \tag{2.14}$$

Since $\det(T)$ equals Δ up to a non-zero rational multiplicative constant (see 1.21(3) and 5.36 below) at least in our cases (e, q) = (2, 3), (2, 5), (2, 7), and (3, 4), we also have

$$\frac{\partial}{\partial \mu_i} \in \mathrm{Der}_{\mathbb{Q}[\mu]} \left(\mathbb{Q} \left[\frac{1}{\Delta}, \ \mu, \ x, \ y, \ \frac{1}{f_2(x, y)} \right]; \frac{\partial}{\partial \mu_i} \right).$$

Remark 2.15. (1) While operating ℓ_j on an element in $\mathbb{Q}[\mu, x, y] \frac{dx}{f_y}$, some terms with f_y^2 in its denominators appear. But, it is seen by (2.11) or (2.14) that we have only terms with f_y of 1st degree in their denominators modulo the exact forms.

- (2) Moreover, operating $\frac{\partial}{\partial \mu_j}$ on an element in $\mathbb{Q}[\mu, x, y] \frac{dx}{f_y}$, we may have the denominator with the discriminant Δ besides f_y because of (2.11) and the fact $\det([T_{ij}])$ is Δ times a rational.
- (3) Eventually, we have a nice definition 3.2 of the 1st de Rham cohomology $H^1_{dR}(\mathscr{C}/\mathbb{Q}[\mu])$ and a good differential module structure on it. This makes a clear view of our application of the theory of the Gauss-Manin connection.
- (4) One more advantage of the formula (2.11) is that it gives tremendously fast algorithm to compute many examples of the systems of heat equations satisfied by the sigma functions. Analysing such examples, the results in [28] are obtained.

We refer the reader to [28] on a proof of 2.1.

Here we note the following equality for the proof of the next lemma. Applying $\frac{\partial y}{\partial \mu_{eq-k}}$ to f(x,y) = 0, we have $f_y \frac{\partial y}{\partial \mu_{eq-k}} - M_k = 0$, so that

$$\frac{\partial y}{\partial \mu_{eq-k}} = \frac{M_k}{f_y}. (2.15)$$

We give the following lemma, by which we understand (2.11) below more clearly is a special case of Lemma 1 in p.125 of [11] (proved by the uniqueness assertion in 2.1).

Lemma 2.17. Denote by $\frac{d}{dx}$ the derivation in $\operatorname{Der}_{\mathbb{Q}[\mu]}(\mathbb{Q}(\mu, x, y); 0)$ determined by the properties that $\frac{d\mu_k}{dx} = 0$ for any $k \in \operatorname{wt}(\mu)$ and $\frac{d}{dx}x = 1$. Then for any $k \in \operatorname{wt}(\widetilde{\mu})$, we have

$$\frac{d}{dx}\frac{\partial y}{\partial \mu_k} = \frac{\partial}{\partial \mu_k}\frac{dy}{dx}.$$

Therefore, we have additionally

$$\frac{d}{dx}\ell_j = \ell_j \frac{d}{dx}$$

as a map from $\mathbb{Q}(\mu, x, y)dx$ into itself.

Proof. This is exactly Lemma 2 in [11], p.125, which we can check by using (2.16) as follows. The left-hand side is

$$\frac{\partial}{\partial \mu_k} \frac{dy}{dx} = -\frac{\partial}{\partial \mu_k} \frac{f_x}{f_y} = -\frac{\frac{\partial f_x}{\partial \mu_k}}{f_y} + \frac{f_x \frac{\partial f_y}{\partial \mu_k}}{f_y^2}$$

$$= -\frac{-(M_{eq-k})_x + f_{xy} \frac{\partial y}{\partial \mu_k}}{f_y} + \frac{f_x \cdot \left(-(M_{eq-k})_y + f_{yy} \frac{\partial y}{\partial \mu_k}\right)}{f_y^2}$$

$$= -\frac{-(M_{eq-k})_x + f_{xy} \frac{M_{eq-k}}{f_y}}{f_y} + \frac{f_x \cdot \left(-(M_{eq-k})_y + f_{yy} \frac{M_{eq-k}}{f_y}\right)}{f_y^2}.$$

On the other hand, we have

$$\frac{d}{dx} \frac{\partial y}{\partial \mu_{k}} = \frac{d}{dx} \frac{M_{eq-k}}{f_{y}} \quad (\because 2.16)$$

$$= \frac{(M_{eq-k})_{x} + (M_{eq-k})_{y} \frac{dy}{dx}}{f_{y}} - \frac{M_{eq-k} (f_{yx} + f_{yy} \frac{dy}{dx})}{f_{y}^{2}}$$

$$= \frac{(M_{eq-k})_{x} - (M_{eq-k})_{y} \frac{f_{x}}{f_{y}}}{f_{y}} - \frac{M_{eq-k} (f_{yx} - f_{yy} \frac{f_{x}}{f_{y}})}{f_{y}^{2}}.$$

These two coincide and the formula follows.

Remark 2.18. Thanks to 2.1. and

$$\ell_{j}\left(d\left(\frac{h}{f_{2}}\right)\right) = \ell_{j}\left(\frac{d}{dx}\left(\frac{h}{f_{2}}\right)\right)dx = \frac{d}{dx}\left(\ell_{j}\left(\frac{h}{f_{2}}\right)\right)dx = d\left(\ell_{j}\left(\frac{h}{f_{2}}\right)\right)$$

for any $h \in \mathbb{Q}[\mu, x, y]$ by 2.16, we see that

$$\ell_{j} \in \operatorname{Der}_{\mathbb{Q}[\mu]} \left(\mathbb{Q}[\mu, x, y] \frac{dx}{f_{y}} + d \left(\mathbb{Q}[\mu, x, y] \frac{1}{f_{y}} \right); \ell_{j} \right) \text{ and}$$

$$\ell_{j} \in \operatorname{Der}_{\mathbb{Q}[\mu]} \left(\left(\mathbb{Q}[\mu, x, y] \frac{dx}{f_{y}} + d \left(\mathbb{Q}[\mu, x, y] \frac{1}{f_{y}} \right); \ell_{j} \right) \middle/ d \left(\mathbb{Q}[\mu, x, y] \frac{1}{f_{y}} \right) \right).$$

$$(2.18)$$

While we use the same notation ℓ_j for elements in different sets above, it is supposed that there is no confusion.

Definition 2.20. For later use, we denote the Lie subalgebra generated by all the ℓ_j s over the ring $\mathbb{Q}[\mu]$ in the Lie algebra obtained as the union of the above sets by L:

$$L \subset \operatorname{Der}_{\mathbb{Q}[\mu]} \left(\mathbb{Q}[\mu, x, y] \frac{dx}{f_{y}} + d \left(\mathbb{Q}[\mu, x, y] \frac{1}{f_{y}} \right) \right). \tag{2.21}$$

Remark 2.22. The inclusion above might be an equality.

3. de Rham cohomology etc.

3.1. Differential forms of the first kind of the curve

Recall that any term of the sequence $w_1, w_2, \dots, w_g \in \text{wgs}(e, q)$ in (1.14) is written as

$$w_i = 2g - 1 - a_i e - b_i q,$$

with non-negative integers a_i , b_i . Using this notation, we define differential forms

$$\omega_{w_j} = \frac{x^{a_j} y^{b_j}}{f_2(x, y)} dx, \quad (j = 1, \dots, g).$$
(3.1)

These are of the first kind (namely holomorphic everywhere on \mathscr{C}) and of weight w_i .

3.2. Forms of the second kind and the first de Rham cohomology

In this paper, we should consider the curve \mathscr{C} and other objects arising from \mathscr{C} to be defined over the ring $\mathbb{Q}[\mu]$; in which the period matrix Ω is exceptional as is explained later, and is defined over the field \mathbb{C} of complex numbers.

Throughout this paper, we mean by the (differential) forms of the second kind all the forms without non-zero residue everywhere on \mathscr{C} . Therefore we include in them the differential forms of the first kind. However, we mean by the differential forms of the third kind the forms having non-zero residue pole somewhere on \mathscr{C} , on which we never assume that their order of such poles to be 1 and that they does not contain any form of the second kind.

It is easy to see that the set of differential forms of the second kind on $\mathscr C$ with a pole only at ∞ is exactly

$$\mathbb{Q}[\mu, x, y] \frac{dx}{f_2(x, y)}.$$

In concord with our principle that we shall treat our materials not over the fields $\mathbb{Q}(\mu)$ but over the ring $\mathbb{Q}[\mu]$, we have the following definition, thanks to the horizontal derivation formula 2.1 and 2.17.

Definition 3.2. We define the first de Rham cohomology of \mathscr{C} over $\mathbb{Q}[\mu]$ by

$$H^{1}_{\mathrm{dR}}(\mathscr{C}/\mathbb{Q}[\mu]) = \frac{\mathbb{Q}[\mu, x, y] \frac{dx}{f_{\mathcal{D}}(x, y)} + d\left(\mathbb{Q}[\mu, x, y] \frac{1}{f_{\mathcal{D}}(x, y)}\right)}{d\left(\mathbb{Q}[\mu, x, y] \frac{1}{f_{\mathcal{D}}(x, y)}\right)}.$$
(3.3)

We are never concerned with higher cohomologies in this paper. We have an important remark here.

Remark 3.4. In order to define the first de Rham cohomology over $\mathbb{Q}[\mu]$ which endures for calculation for 'horizontal' differentiations, namely, for extensions of the elements in $Der(\mathbb{Q}[\mu])$, the right-hand side of (3.3) is the 'slimmest form' as explained in the following. For an integer k, we denote by $\omega_{\mathscr{C}}(k \cdot \infty)$ (resp. by $L_{\mathscr{C}}(k \cdot \infty)$) the module consists of the forms in $\mathbb{Q}[\mu, x, y] \frac{dx}{f_2(x,y)}$ (resp. the functions (the polynomials) in $\mathbb{Q}[\mu, x, y]$) whose order of the pole at ∞ is at most k. Then we see by Theorem 8.2 in p.30 of [17] that

$$H^1_{\mathrm{dR}}(\mathscr{C}/\mathbb{Q}[\mu]) \simeq \frac{\omega_{\mathscr{C}}((2g-2)\cdot\infty)}{dL_{\mathscr{C}}((2g-1)\cdot\infty)}.$$

and this is a module of rank 2g over $\mathbb{Q}[\mu]$. We place emphasis on this that the derivatives $\ell_j s$ in (2.10) and the derivatives $L_j s$ which appear in (5.39) (and any elements in the Lie algebra generated by them) do not act on $\omega_{\mathscr{C}}((2g-2)\cdot\infty)$ but on the module $\mathbb{Q}[\mu,x,y]\frac{dx}{f_2(x,y)}+d\left(\mathbb{Q}[\mu,x,y]\frac{1}{f_2(x,y)}\right)$ in (3.3). So that the definition (3.3) is much suitable for explicit calculation on $H^1_{dR}(\mathscr{C}/\mathbb{Q}[\mu])$ as a differential L-module, where L is defined in (2.21).

3.3. Symplectic inner product

We want to choose good g differential forms η_{-w_j} ($j=g,\cdots,1$) of the second kind and of weight $-w_j$ such that the 2g forms consists of them and the forms of the first kind in (3.1) give rise to a symplectic basis of the space $H^1_{dR}(\mathscr{C}/\mathbb{Q}[\mu])$ which is equipped with a natural symplectic inner product explained below. We denote $\omega = (\omega_{w_1}, \cdots, \omega_{w_g}, \eta_{-w_g}, \cdots, \eta_{-w_l})$.

As before, (x, y) is a generic point of \mathscr{C} . It is known that the η_{-w_j} s as well as the ω_{w_j} s are defined over $\mathbb{Q}[\mu]$, namely, they are of the form $\frac{h(x,y)}{f_2(x,y)}dx$ with $h(x,y) \in \mathbb{Q}[\mu,x,y]$ (see [27], [28]). We already defined in (1.12) that

$$M(x, y) = \{ x^i y^j \mid 0 \le i \le q - 2, \ 0 \le j \le e - 2 \}.$$

The set $\left\{\frac{h(x,y)}{f_2(x,y)} dx \mid h(x,y) \in M(x,y)\right\}$ forms a basis of $H^1_{d\mathbb{R}}(\mathscr{C}/\mathbb{Q}[\mu])$ as a $\mathbb{Q}[\mu]$ -module. Here we note that the order of pole of $x^{q-2}y^{e-2}$ at ∞ , which is the largest in M(x,y), is

$$e(q-2) + q(e-2) = 2(e-1)(q-1) - 2 = 2g - 2$$

and $H^1_{d\mathbb{R}}(\mathscr{C}/\mathbb{Q}[\mu])$ is a free $\mathbb{Q}[\mu]$ -module of rank 2g.

The space $H^1_{dR}(\mathscr{C}/\mathbb{Q}[\mu])$ is equipped with the anti-symmetric inner product given by

$$\omega \star \eta = \operatorname{Res}_{P=\infty} \left(\int_{\infty}^{P} \omega \right) \eta(P)$$

for any ω , $\eta \in H^1_{d\mathbb{R}}(\mathscr{C}/\mathbb{Q}[\mu])$. This is formally defined using the formal expansion with respect to a local parameter at ∞ (see [27], [28]), which is a formal interpretation of the product $\omega \star \eta = \mathop{\mathrm{Res}}_{P \in \mathscr{C}} \left(\int_{\infty}^{P} \omega \right) \eta(P)$ if we regard the μ_j s as complex numbers and \mathscr{C} as a non-singular curve (i.e. a compact Riemann surface). Here \mathscr{C} is the regular polygon obtained from the Riemann surface attached to the curve \mathscr{C} with respect to the paths

$$\{\alpha_j, \ \beta_j \mid j=1,\cdots,g\} \tag{3.5}$$

which form a symplectic basis of the homology group $H_1(\mathcal{C}, \mathbb{Z})$ as usual.

We choose η_{-w_i} to satisfy the symplectic relations

$$\omega_{w_i} \star \omega_{w_i} = 0, \quad \eta_{-w_i} \star \eta_{-w_i} = 0, \quad \omega_{w_i} \star \eta_{-w_i} = -\eta_{-w_i} \star \omega_{w_i} = \delta_{ij}.$$
 (3.6)

The choice of η_{-w_j} is not unique but given by using so-called the *fundamental 2-form of Klein*. For a more concrete construction of these forms, we refer the reader to [27] (or to [28] for more detailed description). Especially, as a $\mathbb{Q}[\mu]$ -module, the ω_{w_j} s and η_{-w_j} s form a basis of $H^1_{dR}(\mathscr{C}/\mathbb{Q}[\mu])$.

4. The sigma function

4.1. Materials for the construction of the sigma functions

In this section, we recall the definition of the natural generalisation of (0.2) for the general curve \mathscr{C} , which is a function of g variables $u = {}^t[u_{w_g} \cdots u_{w_1}]$ with $w_j \in \text{wgs}(e, q)$ and written as $\sigma(u) = \sigma(u_{w_g}, \cdots, u_{w_1})$. It is called, analogously, the sigma function for \mathscr{C} . To define it precisely, we need to introduce the Schur polynomial, period matrices, and others.

We use the classical notation of matrices concerning theta series, so our notation is transposed from the notation of [9]. Specifically, we will denote the period matrix of a curve as (4.2) whereas Buchstaber and Leykin's papers use the transpose of this matrix. The other differences between their notation and ours will follow from this.

Letting $T = \sum_{i=1}^g u_{w_i} T^{w_i}$ with an indeterminate T, we define $\{p_k\}$ by $p_k = 0$ for negative k and

$$\sum_{k=0}^{\infty} p_k T^k = \sum_{n=0}^{\infty} \frac{T^n}{n!}.$$

Then we define $s(u) = s(u_{w_g}, \dots, u_{w_1})$ (see Section 4 in [24]) by

$$s(u) = \det\left(\left[p_{w_{g+1-i}+j-g}\right]\right). \tag{4.1}$$

This is the *Schur polynomial* corresponding to the sequence (w_g, \dots, w_1) .

From now on in this Section, we assume all the μ_j s are complex numbers and $\mathscr C$ is non-singular. The period matrices are defined by $\Omega = \begin{bmatrix} \omega' & \omega'' \\ \eta' & \eta'' \end{bmatrix}$ with

$$\omega' = \left[\int_{\alpha_{j}} \omega_{w_{g-i+1}} \right], \quad \omega'' = \left[\int_{\beta_{j}} \omega_{w_{g-i+1}} \right],$$

$$\eta' = \left[\int_{\alpha_{j}} \eta_{-w_{g-i+1}} \right], \quad \eta'' = \left[\int_{\beta_{j}} \eta_{-w_{g-i+1}} \right],$$

$$(4.2)$$

where the η_{-w_j} 's are ones of (3.6) and α_i s and β_j 's are ones of (3.5). We introduce the *g*-dimensional space \mathbb{C}^g with coordinates

$$u = {}^{t}[u_{w_{g}} \ u_{w_{g-1}} \ \cdots \ u_{w_{1}}] \tag{4.3}$$

for the domain on which the sigma function is defined. We define a lattice in this space by

$$\Lambda = \omega' \mathbb{Z}^g + \omega'' \mathbb{Z}^g. \tag{4.4}$$

For any $u \in \mathbb{C}^g$, we define $u', u'' \in \mathbb{R}^g$ by $u = \omega' u' + \omega'' u''$. Likewise, for $\ell \in \Lambda$, we write $\ell = \omega' \ell' + \omega'' \ell''$ with $\ell', \ell'' \in \mathbb{Z}^g$. In addition, we write $\omega'^{-1} t(\omega_{w_g}, \dots, \omega_{w_1}) = {}^t(\hat{\omega}_1, \dots, \hat{\omega}_g), \omega'^{-1} \omega'' = [\tau_{ij}]$, and define (see [22], p.3.82 or [18], p43)

$$\delta_{j} = -\frac{1}{2}\tau_{jj} + \sum_{i=1}^{g} \int_{\alpha_{i}} \left(\int_{\infty}^{P} \hat{\omega}_{j} \right) \hat{\omega}_{i}(P), \quad \delta = \omega'^{t} [\delta_{1} \cdots \delta_{g}] \in \mathbb{C}^{g}.$$

$$(4.5)$$

Then we define the Riemann constant by $[\delta' \ \delta'']$. It is well-known that $\delta', \delta'' \in (\frac{1}{2}\mathbb{Z})^g$ for our curve. The $[\delta' \ \delta'']$ can be taken independent of the values of μ_j s with a suitable choice of the paths of integrals in (4.5).

Using the above notation, we define a linear form $L(\)$ on $\mathbb{C}^g \times \mathbb{C}^g$ by

$$L(u, v) = {}^{t}u (\eta' v' + \eta'' v''). \tag{4.6}$$

This is \mathbb{C} -linear with respect to the first variable, and \mathbb{R} -linear with respect to the second. Moreover, we define

$$\chi(\ell) = \exp\left(2\pi i (\delta' \ell'' - \delta' \ell' + \frac{1}{2} \ell' \ell'')\right) \in \{1, -1\}$$

$$\tag{4.7}$$

for any $\ell \in \Lambda$. Let

$$\kappa: \mathbb{C}^g \longmapsto \mathbb{C}^g/\Lambda \tag{4.8}$$

be the map given by modulo Λ , and $\operatorname{Sym}^k \mathscr{C}$ be the k-th symmetric product of \mathscr{C} . Then we have the Abel-Jacobi mapping

$$\iota: \operatorname{Sym}^{k} \mathscr{C} \longrightarrow \mathbb{C}^{g}/\Lambda, \quad (P_{1}, \dots, P_{k}) \longmapsto \sum_{i=1}^{k} \left(\int_{\infty}^{P_{j}} \omega_{w_{g}}, \dots, \int_{\infty}^{P_{j}} \omega_{w_{1}} \right), \tag{4.9}$$

whose image is denoted by $\Theta^{[k]}$. We denote $\Theta = \Theta^{[g-1]}$, which is called the standard theta divisor of the Jacobian variety \mathbb{C}^g/Λ of \mathscr{C} . For k=1, the map ι is an isomorphism from \mathscr{C} to $\Theta^{[1]}$, by which we frequently identify these two.

4.2. Weight revisited

In this subsection, we assume all μ_j s in (1.1) are complex numbers. We denote by \mathcal{C}_{μ} the curve given by (1.1) and assume it is non-singular, namely, we assume it gives a Riemann surface. Here, we shall extend the notion of the weight wt of (1.4) as follows. Firstly, we define the weight of u_j , a coordinate of u in (4.3), by

$$\operatorname{wt}(u_i) = j. \tag{4.10}$$

We explain below that this definition is consistent with the settings of weight so far. For a later use in (5.40) for instance, we prepare another notation

$$wt(u) = \{ wt(u_{w_i}) | j = 1, \dots, g \} = wgs(e, q),$$

too. Let ε be an arbitrary non-zero complex number and $\mathscr{C}_{\varepsilon\mu}$ be the curve defined by (1.1) with every μ_j being replaced by $\varepsilon^{-j}\mu_j$. Then the map

$$\boldsymbol{\varepsilon}: \mathscr{C}_{\mu} \longrightarrow \mathscr{C}_{\varepsilon\mu}, \quad (x, y) \longmapsto (\varepsilon^{-e} x, \varepsilon^{-q} y)$$

is an isomorphism (i.e. an isomorphism of compact Riemann surfaces). Now we extend the defining domain of wt to the space \mathbb{C}^g of (4.3) as follows. We take a fixed reference point $(\{\mu_j^{(0)}\}, u^{(0)})$ of $(\mu, u) = (\{\mu_i\}, u)$ of (1.1) and (4.3), and assume $\mathscr{C}_{u^{(0)}}$ is also non-singular. Let

$$\mathcal{M} = \mathcal{M}(\mu^{(0)}, \, u^{(0)}) \tag{4.11}$$

be the germ of the analytic functions of (μ, u) at $(\mu^{(0)}, u^{(0)})$, where we regard them as complex variables. Let $\Phi(\mu, u) \in \mathcal{M}$. We denote by $\Phi(\varepsilon \mu, \varepsilon u)$ the function obtained from $\Phi(\mu, u)$ by replacing all μ_i by $\varepsilon^{-i}\mu$ and all u_i by $\varepsilon^i u_i$ for $i = w_g, \dots, w_1$. We say that the function obtained is induced by the mapping ε . If there is a constant integer w such that

$$\Phi(\varepsilon\mu,\varepsilon u) = \varepsilon^w \Phi(\mu,u)$$

for any $\varepsilon \in \mathbb{C}$, then we say the function $\Phi(\mu, u)$ is of weight w, and denote this as

$$\operatorname{wt}(\Phi(\mu, u)) = w$$
.

Now we explain that the definition of wt is actually an extension of the weight defined at (1.4). The coordinates x and y of \mathcal{C}_{μ} are naturally seen as functions of u_g of u in (4.3) on certain restricted domain in \mathbb{C}^g for any $\mu_j \in \mathbb{C}$, which should be denoted by $\kappa^{-1}\iota(\mathcal{C})$ by using the notation (4.8) and (4.9). Then, observing the weight of x and y as power series of u_g , their weights are -e and -q, respectively. The function $u_g \mapsto x$ above is seen as the restriction to $\kappa^{-1}\iota(\mathcal{C})$ of the Abelian function

$$u \longmapsto \frac{x_1 \cdots x_g}{\sum_{1 \le i_1 < \dots < i_{g-1} \le g} x_{i_1} \cdots x_{i_{g-1}}},\tag{4.12}$$

where $u = \iota((x_1, y_1), \dots, (x_g, y_g)) \mod \Lambda$. The function (4.12) is easily checked to be of weight -e. Under similar observation, the function $u_g \mapsto y$ is seen of weight -q. Summarising the above, the notion of weight of (1.4) is completely compatible with the former notion above as well as one on \mathcal{M} .

Take any circuit integrals of an entry of one of the matrices in (4.2) and consider the map ε . For example, we choose $\int_{\alpha_j} \omega_{w_i}$. Note that it is an element in \mathcal{M} which is a function on μ_j s and independent of u. While the map ε changes ω_{w_i} to $\varepsilon^{w_i}\omega_{w_i}$ as $\operatorname{wt}(\omega_{w_i}) = w_i$, the deformation of the path α_j of the integral no longer affects this change of value integral because of Cauchy's theorem. So that, the mapping ε induces a change of the integral

$$\int_{lpha_i} \omega_{w_i} \longmapsto \, \varepsilon^{w_i} \int_{lpha_i} \omega_{w_i},$$

for any non-zero ε . Therefore, we have

$$\operatorname{wt}\left(\int_{\alpha_j}\omega_{w_i}\right)=w_i.$$

By the argument above, the weight of such a circuit integral does not depend on its path of integral as well as the choice of the reference points $\mu_j^{(0)}$ s and $u^{(0)}$. Because of (4.9) for k = g is surjective (Jacobi's theorem) and any values $\int_{\alpha_j} \omega_{w_i}$ s are appeared as the coordinates u_{w_j} the definition of weight (4.10) is justified.

4.3. Construction of the sigma function

Using the notions defined in the previous subsections, we define the sigma function by the following characterisation. Now we fix the curve $\mathscr{C} = \mathscr{C}^{e,q}_{\mu}$.

Theorem 4.13. There exists a unique function $(\mu, u) \mapsto \sigma(u) = \sigma(\mu, u)$ having the following properties:

- (1) $\sigma(u)$ is an entire function on \mathbb{C}^g for any fixed $\mu_i s$ in \mathbb{C} ;
- (2) Supposing that the $\{\mu_i\}$ are constants in $\mathbb C$ and the discriminant Δ is not zero, we have

$$\sigma(u+\ell) = \chi(\ell) \, \sigma(u) \exp L(u+\frac{1}{2}\ell,\ell) \quad (u \in \mathbb{C}^g, \ \ell \in \Lambda),$$

where Λ , L, and χ are those of (4.4), (4.6), and (4.7), respectively;

(3) Viewing $\sigma(u)$ as an element in \mathcal{M} of (4.11) with an arbitrary reference point

$$\operatorname{wt}(\sigma(u)) = \frac{1}{24}(e^2 - 1)(q^2 - 1);$$

Moreover, $\sigma(u)$ is expanded as a power series around the origin $(0, \dots, 0)$ with coefficients in $\mathbb{Q}[\mu]$, and is of homogeneous weight $(e^2 - 1)(q^2 - 1)/24$;

- (4) $\sigma(u)|_{u=0}$ is the Schur polynomial s(u) of (4.1);
- (5) $\sigma(u) = 0 \iff u \in \kappa^{-1}(\Theta)$.

Definition 4.14. We call the function $\sigma(u)$ whose existence is guaranteed by 4.1 the sigma function of the curve \mathscr{C} .

The theorem 4.1 was proved in various ways in the literature, each version has a slightly different point of view. It is convenient to summarise here these versions from our point of view. We define

$$\tilde{\sigma}(u) = \tilde{\sigma}(u, \Omega) = \left(\frac{(2\pi)^g}{\det \omega'}\right)^{\frac{1}{2}} \exp\left(-\frac{1}{2} \iota u \, \eta' \omega'^{-1} u\right)$$

$$\cdot \sum_{\sigma''''} \exp\left(\frac{1}{2} \iota (n + \delta'') \, \omega'^{-1} \omega'' (n + \delta'') + \iota (n + \delta'') (\omega'^{-1} u + \delta')\right), \tag{4.15}$$

where det denotes the determinant. Note that the arguments in any exponential are of weight 0, so that the infinite series part of (4.15) is of weight 0 as well. It is easy to show that this function has property (1) (see 5.21 below) and that this function satisfies (2) using (5.3) below. Frobenius' method shows that the solutions of the equation (2) form a one dimensional space (see p.93 of [17]). Although this function is constructed by using Ω , it is independent of Ω . Namely, the function $\tilde{\sigma}(u,\Omega)$ is invariant under a modular transform, that is the transform of Ω by $\operatorname{Sp}(2g,\mathbb{Z})$ which come from changing the choice of α_i s and β_i s. Therefore, it is expressed as a power series of u with coefficients being functions of only the μ_j s. On the latter part of (3) and (4), we refer the reader to [24]. In that paper, $\tilde{\sigma}(u)$ times some constant is expressed as a determinant of infinite size (see also [27]). See also the paper [23] by Nakayashiki, in which he proved the sigma function is no other than (4.15) times a non-zero constant depending on μ_j s with emphasising the later part of (3). That $\tilde{\sigma}(u)$ has the property (5) come from a well-known property of Riemann theta function. Using notation we have explained previously, we define

$$\hat{\sigma}(u) = \Delta^{-\frac{1}{8}} \tilde{\sigma}(u), \tag{4.16}$$

with an appropriate choice of the $\frac{1}{8}$ th root of the discriminant Δ . It is known for g=1 and 2 that this function exactly satisfies all the properties in 4.1, namely, we have $\sigma(u) = \hat{\sigma}(u)$. For g=1, it is shown as in [26] by a transformation formulae for $\eta(\tau)$ and the theta series described in pp.176–180 of [29], and for g=2 the paper [16] by D. Grant, in which the property (4) is shown by using Thomae's formula.

However, it is not known for $g \ge 3$ if the function (4.16) is really the sigma function. The paper [9] is the first one to seriously attack this problem.

In this paper, we show, following the idea of [9], that $\sigma(u) = \hat{\sigma}(u)$ for the genus 3 curves that is for the (2, 7)-curve and the (3, 4)-curve. This means (4.16) satisfies especially (4) up to an absolutely numerical multiplicative constant. The strategy of the proof is as follows: We construct a system of linear partial differential equations (heat equations) satisfied by $\hat{\sigma}(u)$ and show that the solution space is of dimension one (over the base field) by *explicit construction* of a recursive system for the coefficients of the power series expansion of any unknown solution and *showing the uniqueness* of the solution of this system.

Then we see $\sigma(u) = \hat{\sigma}(u)$ up to a non-zero multiplicative absolutely numerical constant. This result might be seen as a generalisation of *Thomae's formula* ([30]). Section 6 is devoted to these last steps.

5. Theory of heat equations

5.1. Generalisation of the frobenius-stickelberger theory

This and the following sections are devoted to explaining the theory of Buchstaber and Leykin [9], on the differentiation of Abelian functions with respect to their parameters, as clearly as we can. That generalises the work of Frobenius and Stickelberger [14], discussed above, on the elliptic function case of this problem.

For higher genus cases, we do not have a naive generalisation of (0.8) and (0.9), which are mentioned in the Introduction. However, we can give a natural generalisation of the relations (0.10) to the curve \mathscr{C}_{μ} as explained in the next section.

As we discussed in Subsection 3.2, any element L in L of (2.21) operates linearly on the space $H^1_{dR}(\mathscr{C}/\mathbb{Q}[\mu])$. For complex variables μ_j s, we let L operate firstly on the forms with *variables* μ_j s of representative of basis of $H^1_{dR}(\mathscr{C}/\mathbb{Q}[\mu])$, then we restore μ_j s to the original values in \mathbb{C} .

Taking a derivative $L \in L$, we define $\Gamma^L \in \operatorname{Mat}(2g, \mathbb{Q}[\mu])$ as the representation matrix of the action of L by

$$L(\boldsymbol{\omega}) = \boldsymbol{\omega}^{t} \Gamma^{L} \quad \text{for } \boldsymbol{\omega} = (\omega_{w_{o}}, \cdots, \omega_{w_{1}}, \eta_{-w_{o}}, \cdots, \eta_{-w_{1}}) \in H^{1}_{d\mathbb{R}}(\mathscr{C}/\mathbb{Q}[\mu]). \tag{5.1}$$

In [9], the matrix $-^{l}(\Gamma^{L})$ defined by (5.1) is called the *Gauss-Manin connection* for the derivation (vector field) L.

From here to the end of Section 5, we assume that all the μ_j s are complex variables which vary as \mathscr{C} is non-singular. We can then use the periods ω_{ij} s and η_{ij} s.

By integrating (5.1) along each element in the chosen symplectic basis of $H_1(\mathcal{C}, \mathbb{Z})$, we get the natural action

$$L(\Omega) = \Gamma^L \Omega \tag{5.2}$$

of L on the space of Ω s for all the choices of symplectic basis of $H_1(\mathcal{C}, \mathbb{Z})$. So, we see also how L operates on the field $\mathbb{Q}(\{\omega'_{ij}\}, \{\omega''_{ij}\})$. Of course, since Ω is the period matrix of a symplectic basis, these elements must satisfy the constraint

$${}^{t}\Omega J\Omega = 2\pi i J, \text{ where } J = \begin{bmatrix} 1_{g} \\ -1_{g} \end{bmatrix}$$
 (5.3)

by (3.6). This is none other than the generalisation of Frobenius-Stickelberger's relation (0.10) and is to say that $(2\pi i)^{-\frac{1}{2}}\Omega \in \operatorname{Sp}(2g,\mathbb{C})$. It follows immediately that

$$\Omega^{-1} = \frac{1}{2\pi i} J^{-1}{}^{t} \Omega J = \frac{1}{2\pi i} \begin{bmatrix} {}^{t} \eta'' & -{}^{t} \omega'' \\ -{}^{t} \eta' & {}^{t} \omega' \end{bmatrix}.$$
 (5.4)

After operating L on both sides of (5.3), using (5.2) and (5.3), we see that the matrix Γ^L satisfies

$$^{t}\Gamma^{L}J + J\Gamma^{L} = 0$$
, i.e. $^{t}(\Gamma^{L}J) = \Gamma^{L}J$ (5.5)

because $L({}^{t}\Omega) = {}^{t}\Omega {}^{t}\Gamma^{L}$, which is to say that Γ^{L} is in the Lie algebra $\mathfrak{sp}(2g, \mathbb{Q}[\mu])$ of $\mathrm{Sp}(2g, \mathbb{Q}[\mu])$. Thus we may write

$$-\Gamma^{L}J = \begin{bmatrix} \alpha & \beta \\ {}^{t}\beta & \gamma \end{bmatrix}, \quad \Gamma^{L} = \begin{bmatrix} -\beta & \alpha \\ -\gamma & {}^{t}\beta \end{bmatrix}$$
 (5.6)

with $^t\alpha = \alpha$ and $^t\gamma = \gamma$.

Remark 5.7. (1) We use a different notation for $D(x, y, \lambda)$ compared to p.273 of [9], and for Ω , Γ and β compared to p.274 of loc. cit. Our ${}^t\omega$ equals $D(x, y, \lambda)$ by transposing and changing the sign on the latter half entries. The others are naturally modified according to this difference and taking transposes. We will give a detailed comparison of our notation with theirs in 5.57 at the end of Subsection 5.6. (2) In general, it requires some work to write down the given operator L as a partial differential operator with respect to the periods ω'_{ij} and ω''_{ij} similar to the LHS of (0.10). However, we do not use such an expression in the present paper.

Conversely, starting from a matrix

$$\Gamma = \begin{bmatrix} -\beta & \alpha \\ -\gamma & {}^{t}\beta \end{bmatrix} \in \mathfrak{sp}(2g, \mathbb{Q}[\mu]),$$

with ${}^t\alpha=\alpha$ and ${}^t\gamma=\gamma$, we get uniquely an operator $L\in L$ such that $\Gamma^L=\Gamma$. So far, this is a natural generalisation of the situation investigated by Frobenius-Stickelberger [14].

5.2. The primary heat equation

In this Section, we review the general heat equations satisfied by the sigma functions.

If we want to find second-order linear partial differential equations (heat equations) satisfied by the sigma function, we should proceed in as general a way as possible. Here, note that the equation (0.6) is satisfied not only by the Jacobi theta function (0.3) but also by each individual term of the sum in (0.3). This corresponds a statement in the proof of Theorem 13 in page 274 of [9]. Here we will review their theory of such equations, correcting a few minor errors, and apply it explicitly to more general curves than considered in [9]. We shall start from this point of view.

Take an derivative $L \in L$ and assume it is of homogeneous weight, say $\operatorname{wt}(L) = k$ (see (2.7)), we have the symmetric matrix $-\Gamma^L J = \begin{bmatrix} \alpha & \beta \\ {}^t \beta & \nu \end{bmatrix}$ with

$$\alpha = [\alpha_{-i,k-j}], \quad \beta = [\beta_{j,k-i}], \quad \gamma = [\gamma_{-i,k+j}]$$

$$\underset{j \in \text{wt}(u)}{\underset{j \in \text{wt}(u)}}{\underset{j \in \text{wt}(u)}{\underset{j \in \text{wt}(u)}}{\underset{j \in \text{wt}(u)}}{\underset{wt}(u)}}}}}}}}}}}}}$$

and we also associate with it a second-order differential operator H^L , given by

$$H^{L} = \frac{1}{2} \begin{bmatrix} {}^{t} \partial_{u} {}^{t} u \end{bmatrix} \begin{bmatrix} \alpha & \beta \\ {}^{t} \beta & \gamma \end{bmatrix} \begin{bmatrix} \partial_{u} \\ u \end{bmatrix}$$

$$= \sum_{i \in wt(u)} \sum_{i \in wt(u)} \left(\frac{1}{2} \alpha_{-i,k-j} \frac{\partial^{2}}{\partial u_{i} \partial u_{j}} + \beta_{-j,k-i} u_{i} \frac{\partial}{\partial u_{j}} + \frac{1}{2} \gamma_{-i,k+j} u_{i} u_{j} \right) + \frac{1}{2} \operatorname{Tr} \beta.$$

$$(5.8)$$

Here ∂_u denotes the column vector with g components $\frac{\partial}{\partial u_i}$, and u the column vector with g components u_i s. The very last term comes from the commutation relation $\frac{\partial}{\partial u_i} u_j = u_j \frac{\partial}{\partial u_i} + \delta_{ij}$. It is then straightforward to verify the following

Lemma 5.9. If we define a function $G_0(u, \Omega)$ (this is a Green's function) by

$$G_0(u,\Omega) = \left(\frac{(2\pi)^g}{\det \omega'}\right)^{\frac{1}{2}} \exp\left(-\frac{1}{2} u \eta' \omega'^{-1} u\right),$$

then the following equation (a heat equation) holds:

$$(L - H^L)G_0 = 0. (5.10)$$

Proof. We have

$$L G_{0} = -\frac{1}{2} \text{Tr}(\omega'^{-1} L(\omega')) G_{0} - \frac{1}{2} ({}^{t} u L(\eta') \omega'^{-1} u) G_{0} + \frac{1}{2} ({}^{t} u \eta' \omega'^{-1} L(\omega') \omega'^{-1} u) G_{0}$$

$$= \frac{1}{2} \left[\text{Tr}(\omega'^{-1} (\beta \omega' - \alpha \eta')) + ({}^{t} u ((\gamma \omega' - {}^{t} \beta \eta') \omega'^{-1} - \eta' \omega'^{-1} (\beta \omega' - \alpha \eta') \omega'^{-1}) u) \right] G_{0}$$

$$= \frac{1}{2} \left[\text{Tr}(\beta - \alpha \eta' \omega'^{-1}) + ({}^{t} u (\gamma - {}^{t} \beta \eta' \omega'^{-1} - \eta' \omega'^{-1} \beta + \eta' \omega'^{-1} \alpha \eta' \omega'^{-1}) u) \right] G_{0}$$
(5.11)

by using

$$L(\Omega) = \Gamma^{L}\Omega = \begin{bmatrix} -\beta & \alpha \\ -\gamma & {}^{t}\beta \end{bmatrix} \begin{bmatrix} \omega' & \omega'' \\ \eta' & \eta'' \end{bmatrix} = \begin{bmatrix} -\beta\omega' + \alpha\eta' & -\beta\omega'' + \alpha\eta'' \\ -\gamma\omega' + {}^{t}\beta\eta' & -\gamma\omega'' + {}^{t}\beta\eta'' \end{bmatrix}. \tag{5.12}$$

The result of (5.11) coincides with that of

$$\begin{split} H^{L_0}G_0 &= \frac{1}{2} \begin{bmatrix} {}^t\partial_u {}^tu \end{bmatrix} \begin{bmatrix} \alpha & \beta \\ {}^t\beta & \gamma \end{bmatrix} \begin{bmatrix} \partial_u \\ u \end{bmatrix} G_0 = \frac{1}{2} \begin{bmatrix} {}^t\partial_u {}^tu \end{bmatrix} \begin{bmatrix} \alpha & \beta \\ {}^t\beta & \gamma \end{bmatrix} \begin{bmatrix} -\eta'\omega'^{-1}u \\ u \end{bmatrix} G_0 \\ &= \frac{1}{2} \mathrm{Tr}({}^t\beta - \alpha \eta'\omega'^{-1}) G_0 + \frac{1}{2} \begin{bmatrix} -{}^tu\eta'\omega'^{-1} & u \end{bmatrix} \begin{bmatrix} \alpha & \beta \\ {}^t\beta & \gamma \end{bmatrix} \begin{bmatrix} -\eta'\omega'^{-1}u \\ u \end{bmatrix} G_0. \end{split}$$

Here we have used the generalised Legendre relation (5.3) and the symmetry of $\eta'\omega'^{-1}$.

Now we recall that the different terms in the expansion of the theta function are periodic translates of one another. Analogously, to construct the different terms appearing in the expansion of the sigma function, we act on G_0 by iterating an element of the Heisenberg group. For a variable $z \in \mathbb{Q}(\{\omega'_{ij}\}, \{\omega''_{ij}\})$, and a two g-component column vectors p, q whose components also belong to $\mathbb{Q}(\{\omega'_{ij}\}, \{\omega''_{ij}\})$, we introduce

$$F(z, p, q) = \exp(z) \exp({}^{t}pu) \exp({}^{t}q\partial_{u}).$$

We write its inverse operator as

$$F^{-1}(z, p, q) = \exp\left(-{}^{t}q\partial_{u}\right) \exp\left(-{}^{t}pu\right) \exp\left(-z\right).$$

Lemma 5.13. Defining F(z, p, q) for any p, q and z, and H^L for $L \in L$ as in (5.8), the operator equality

$$F^{-1}(z, p, q)(L - H^{L})F(z, p, q) = L - H^{L}$$
(5.14)

holds if and only if

$$L\begin{bmatrix} q \\ p \end{bmatrix} = \Gamma^{L} \begin{bmatrix} q \\ p \end{bmatrix} \text{ and } L(z) = \frac{1}{2} \left({}^{t}p\alpha p - {}^{t}q\gamma q \right). \tag{5.15}$$

Here Γ^L is that of (5.6).

Proof. We calculate directly that

$$F^{-1}(z, p, q) LF(z, p, q) = F^{-1}(z, p, q) \Big(L(z) + L({}^{t}p) u + L({}^{t}q) \partial_{u} \Big) F(z, p, q) + L$$
$$= L + \Big(L(z) + L({}^{t}p)(u - q) + L({}^{t}q) \partial_{u} \Big).$$

Similarly, we find

$$\begin{split} F^{-1}(z,p,q) \, H^L F(z,p,q) &= \frac{1}{2} \left[{}^t \partial_u + {}^t p \, {}^t u - {}^t q \right] \left[\! \begin{array}{c} \alpha \ \beta \\ {}^t \beta \ \gamma \end{array} \right] \left[\! \begin{array}{c} \partial_u + p \\ u - q \end{array} \right] \\ &= H^L + \left[{}^t p \ - {}^t q \right] \left[\! \begin{array}{c} \alpha \ \beta \\ {}^t \beta \ \gamma \end{array} \right] \left[\! \begin{array}{c} \partial_u \\ u \end{array} \right] + \frac{1}{2} \left[{}^t p \ - {}^t q \right] \left[\! \begin{array}{c} \alpha \ \beta \\ {}^t \beta \ \gamma \end{array} \right] \left[\! \begin{array}{c} p \\ -q \end{array} \right]. \end{split}$$

Matching coefficients of ∂_u , u, and 1, and transposing and rearranging, we see that, respectively,

$$L(q) = [-\beta \ \alpha] \begin{bmatrix} q \\ p \end{bmatrix}, \quad L(p) = [-\gamma'\beta] \begin{bmatrix} q \\ p \end{bmatrix}, \quad L(z) = \frac{1}{2} ('p\alpha p - 'q\gamma q)$$

as desired.

Corollary 5.16. The formula (5.15) holds if

$$\begin{bmatrix} q \\ p \end{bmatrix} = \Omega \begin{bmatrix} b' \\ b'' \end{bmatrix}, \quad z = z_0 + \frac{1}{2} pq, \tag{5.17}$$

where b' and b'' are arbitrary numerical constant vectors, and z_0 is an irrelevant numerical constant, which we set to zero below.

Proof. We have
$$L\left(\begin{bmatrix} q \\ p \end{bmatrix}\right) = L(\Omega) \begin{bmatrix} b' \\ b'' \end{bmatrix} = \Gamma^L \Omega \begin{bmatrix} b' \\ b'' \end{bmatrix} = \Gamma^L \begin{bmatrix} p \\ q \end{bmatrix}$$
, which is the former relation in (5.15). The latter one is checked easily.

Denoting the constant vector ${}^{t}[b'\ b'']$ simply by b, we denote p, q, and z with $z_0 = 0$ in (5.17) by p(b), q(b), and z(b), respectively. We define

$$G(b, u, \Omega) = F(z(b), p(b), q(b)) G_0(u, \Omega).$$

Using the Legendre relation (5.4), we note that ${}^{t}p\omega' - {}^{t}q\eta' = 2\pi i{}^{t}b''$, and hence we obtain

$$G(b, u, \Omega) = F(z(b), p(b), q(b)) G_0(u, \Omega)$$

$$= \exp(\frac{1}{2}{}^t pq) \exp({}^t pu) \exp({}^{-t} q\eta' \omega'^{-1} u) \exp({}^{-\frac{1}{2}{}^t} q\eta' \omega'^{-1} q) G_0$$

$$= \exp({}^{-\frac{1}{2}} (2\pi i'b'' \omega'^{-1} q) \exp(2\pi i'b'' \omega'^{-1} u) G_0$$

$$= \exp({}^{-\frac{1}{2}} (2\pi i'b'' \omega'^{-1} (\omega'b' + \omega''b'') \exp(2\pi i'b'' \omega'^{-1} u) G_0$$

$$= \left(\frac{(2\pi)^g}{\det(\omega')}\right)^{\frac{1}{2}} \exp({}^{-\frac{1}{2}{}^t} u\eta' \omega'^{-1} u) \exp(2\pi i(\frac{1}{2}{}^tb'' \omega'^{-1} \omega''b'' + {}^tb'' (\omega'^{-1} u + b'))).$$

Now, the following theorem, which is the foundation of BL theory, is obvious from (5.10) and (5.14).

Theorem 5.18. (The primary heat equation) For the function $G(b, u, \Omega)$ above, one has

$$(L - H^{L}) G(b, u, \Omega) = 0$$
 (5.19)

for any $L \in L$.

5.3. The algebraic heat operators

For the coordinates of the space in which the sigma function is defined, we do not use (u_1, \dots, u_g) for subscripts of the variable u, but denote instead, as in (4.3)

$$u=(u_{w_a},\cdots,u_{w_1}).$$

That is, the components of u are labelled by their weights, which are the Weierstrass gaps. $\Gamma^L \in \mathfrak{sp}(2g, \mathbb{Q}[\mu])$. As a corollary to Theorem 5.1, we have

Corollary 5.20. Let

$$\rho(u) = \sum_{b} c_b G(b, u, \Omega), \tag{5.21}$$

where b runs through the elements of any set $\subset \mathbb{C}^{2g}$ and $c_b \in \mathbb{C}$ are constants such that the sum converges absolutely. Then we have, for any $L \in L$, that

$$(L-H^L) \rho(u,\Omega) = 0.$$

Proof. Since both of L and H^L are independent of b, each term of $\rho(u)$ satisfies (5.19).

Remark 5.22. Assume that \mathcal{C}_{μ} is non-singular. Let Ω be the usual period matrix defined by (4.2), and δ be its Riemann constant. The function defined at (4.15) is written as

$$\tilde{\sigma}(u) = \tilde{\sigma}(u, \Omega) = \sum_{n \in \mathbb{Z}^g} G(^t[\delta' \ n + \delta''], u, \Omega). \tag{5.23}$$

Since the imaginary part of $\omega'^{-1}\omega''$ is positive definite, this series converges absolutely. This is a special case of $\rho(u)$ of (5.19).

Because both L and H^L are independent of b, there are infinitely many linearly independent entire functions $\rho(u)$ on \mathbb{C}^s satisfying $(L - H^L)\rho(u) = 0$. Moreover, since, for a fixed b, the function $G(b, u, \Omega)$ is independent of L, we see that, by switching the choice of L, there are infinitely many linearly independent operators of the form $(L - H^L)$ which satisfy $(L - H^L)\rho(u) = 0$ for some fixed $\rho(u)$.

However, because our aim is to find a method to calculate the power series expansion of the sigma function, we need a more detailed discussion. For our purpose, we require

- (A1) for any (or any element of good generators) $L \in L$ find a good mapping which associates L to a (quadratic linear differential) operator which annihilate the sigma function (4.16) as an element in the ring $\mathbb{Q}[\mu][[u]]$, and
- (A2) to show that the sigma function and its absolute constant multiples are exactly the functions in $\mathbb{Q}[\mu][[u]]$ killed by the operators obtained in (A1)

Since L is a derivation with respect to the μ_j s but H^L is a differential operator with respect to the u_{w_j} s, we see that, for some function Ξ depending only on the μ_i s,

$$L \Xi \tilde{\sigma}(u) = (L\Xi) \tilde{\sigma}(u) + \Xi (L\tilde{\sigma}(u)), \quad H^L \Xi \tilde{\sigma}(u) = \Xi (H^L \tilde{\sigma}(u)).$$

Therefore, $\Xi \tilde{\sigma}(u)$ satisfies

$$(L - H^{L})(\Xi \tilde{\sigma}(u)) = \frac{L\Xi}{\Xi} \Xi \tilde{\sigma}(u) = (L \log \Xi)\Xi \tilde{\sigma}(u). \tag{5.24}$$

If $\Xi \ \tilde{\sigma}(u)$ is the correct sigma function, the left-hand side of the above is in $\mathbb{Q}[\mu][[u]]$, So, in order to get the function $\hat{\sigma}(u)$ of (4.16), $L \log \Delta \in \mathbb{Q}[\mu]$. We shall show that this indeed holds for any $L \in L$ in the next section.

5.4. The matrix V

Throughout this section, we suppose that all the μ_j 's, x, and y are variables or indeterminates. In view of the approach in [9], we require that $L \log \Delta$ belongs to $\mathbb{Q}[\mu]$ because of conditions (A1), (A2) and equation (5.24). We also explain suitable choices for Γ for which L satisfies the condition.

Now we explain another method, known in singularity theory, to calculate the *discriminant* Δ and a basis of the space of the vector fields tangent to the variety defined by $\Delta = 0$.

Let (x, y) and (z, w) are different generic points of \mathscr{C} . Following p.112 of [8], we define a function ph((x, y), (z, w)) (pre-hessian), which is defined by

$$ph((x,y),(z,w)) = \frac{1}{2} \begin{vmatrix} \frac{f_1(x,y) - f_1(z,w)}{x - z} & \frac{f_2(x,y) - f_2(z,w)}{x - z} \\ \frac{f_1(z,y) - f_1(x,w)}{y - w} & \frac{f_2(z,y) - f_2(x,w)}{y - w} \end{vmatrix} \in \mathbb{Z}[\mu, x, y, z, w].$$

For any $F \in \mathbb{Q}[\mu][x, y]$, we define

$$\operatorname{Hess} F = \begin{vmatrix} \frac{\partial^2}{\partial x^2} F & \frac{\partial^2}{\partial x \partial y} F \\ \frac{\partial^2}{\partial y \partial x} F & \frac{\partial^2}{\partial y^2} F \end{vmatrix}. \tag{5.25}$$

Lemma 5.26. (Buchstaber-Leykin [8], p.64) Let I be the ideal in $\mathbb{Q}[\mu][x, y, z, w]$ generated by $f_1(x, y), f_2(x, y), f_1(z, w)$, and $f_2(z, w)$. The determinant ph((z, w), (x, y)) has the following properties. (1) ph((x, y), (x, y)) = Hess f(x, y). (2) ph((x, y), (z, w)) = ph((z, w), (x, y)). (3) We have

$$ph((z, w), (x, y)) F((x, y), (z, w)) \equiv ph((x, y), (z, w)) F((z, w), (x, y)) \mod I$$

for any $F((x, y), (z, w)) \in \mathbb{Q}[\mu][x, y, z, w]$.

Proof. (1) Taking the limit $z \to x$ after subtracting the second row times $\frac{y-w}{x-z}$ from the first row in ph((z, w), (x, y)) F((x, y), (z, w)), we have

$$\frac{1}{2} \begin{vmatrix} f_{11}(x,y) + f_{11}(x,w) & f_{21}(x,y) + f_{21}(x,w) \\ f_{1}(x,y) - f_{1}(x,w) & f_{2}(x,y) - f_{2}(x,w) \\ y - w & y - w \end{vmatrix},$$

where $f_{11}(x, y) = \frac{\partial^2}{\partial x^2}(x, y)$, etc. Then, by taking limit $y \to w$ we get Hess f(x, y). (2) is trivial. (3) By expanding the matrix, we see that the numerator

$$(f_{1}(x, y)f_{2}(z, y) - f_{1}(x, y)f_{2}(x, w) - f_{1}(z, w)f_{2}(z, y) + f_{1}(z, w)f_{2}(x, w))$$

$$- (f_{1}(z, y)f_{2}(x, y) - f_{1}(z, y)f_{2}(z, w) - f_{1}(x, w)f_{2}(x, y) + f_{1}(x, w)f_{2}(z, w))$$

$$= (f_{1}(x, y)f_{2}(z, y) - f_{1}(z, y)f_{2}(x, y)) - (f_{1}(x, y)f_{2}(x, w) - f_{1}(z, y)f_{2}(z, w))$$

$$- (f_{1}(z, w)f_{2}(z, y) - f_{1}(x, w)f_{2}(x, y)) + (f_{1}(z, w)f_{2}(x, w) - f_{1}(x, w)f_{2}(z, w))$$

$$= (f_{1}(x, y)f_{2}(z, y) - f_{1}(x, w)f_{2}(z, w)) - (f_{1}(x, y)f_{2}(x, w) - f_{1}(x, w)f_{2}(x, y))$$

$$- (f_{1}(z, w)f_{2}(z, y) - f_{1}(z, y)f_{2}(z, w)) + (f_{1}(z, w)f_{2}(x, w) - f_{1}(z, y)f_{2}(x, y))$$

is divisible by (z - x)(w - y), because the second expression is clearly divisible by (z - x), while the third expression is divisible by (w - y). Hence, $\operatorname{ph}((x, y), (x, y)) \in \mathbb{Q}[\mu][x, y]$. Moreover, the second expansion

is equal to

$$(f_1(x,y)f_2(z,y) - f_1(x,y)f_2(x,y) + f_1(x,y)f_2(x,y) - f_1(z,y)f_2(x,y))$$

$$- (f_1(x,y)f_2(x,w) - f_1(x,y)f_2(z,w) + f_1(x,y)f_2(z,w) - f_1(z,y)f_2(z,w))$$

$$- (f_1(z,w)f_2(z,y) - f_1(z,w)f_2(x,y) + f_1(z,w)f_2(x,y) - f_1(x,w)f_2(x,y))$$

$$+ (f_1(z,w)f_2(x,w) - f_1(z,w)f_2(z,w) + f_1(z,w)f_2(z,w) - f_1(x,w)f_2(z,w))$$

$$= f_1(x,y)(f_2(z,y) - f_2(x,y)) + (f_1(x,y) - f_1(z,y))f_2(x,y)$$

$$- f_1(x,y)(f_2(x,w) - f_2(z,w)) - (f_1(x,y) - f_1(z,y))f_2(z,w)$$

$$- f_1(z,w)(f_2(z,y) - f_2(x,y)) - (f_1(z,w) - f_1(x,w))f_2(x,y)$$

$$+ f_1(z,w)(f_2(x,w) - f_2(z,w)) + (f_1(z,w) - f_1(x,w))f_2(z,w)$$

which implies that ph((x, y), (z, w))(w - y) already belongs to *I*. A similar calculation shows that $ph((x, y), (z, w))(z - x) \in I$. For $F((z, w), (x, y)) = x^a y^b$, by using (2), we see

$$ph((z, w), (x, y)) x^{a}y^{b} - ph((x, y), (z, w)) z^{a}w^{b}$$

$$= ph((z, w), (x, y)) (x^{a}y^{b} - z^{a}w^{b})$$

$$= ph((z, w), (x, y)) (x^{a}y^{b} - x^{a}w^{b} + x^{a}w^{b} - z^{a}w^{b})$$

$$= ph((z, w), (x, y)) (x^{a}(y^{b} - w^{b}) + (x^{a} - z^{a})w^{b}) \in I.$$

Hence, (3) has been proved.

Below, we will use, instead of T, the symmetric $2g \times 2g$ matrix

$$V = [V_{a,b}] = [V_{v_i, eq-v_{2g-j+1}}] \in \operatorname{Sym}(2g, \mathbb{Q}[\mu])$$

$$b \in \operatorname{wt}(\mu)$$

$$1 \le i \le 2g$$

$$1 < i < 2g$$

where all the indices run in increasing order, defined by the equation

$$^{t}(^{\text{rev}}M(x, y)) \cdot V \cdot ^{\text{rev}}M(z, w) = f(x, y) \operatorname{ph}((z, w), (x, y)) F((x, y), (z, w))$$
 (5.28)

in the ring

$$\mathbb{Q}[\mu][x, y, z, w] / I.$$

We note that the weight of any entry of V is given by

$$\operatorname{wt}(V_{a,b}) = -(a+b).$$
 (5.29)

We define

$$H = \left[\begin{array}{c} H_{a-q+2,\,b-q-2} \end{array} \right] = \left[\begin{array}{c} H_{\nu_i-q+2,\,eq-\nu_{2g-j+1}-q-2} \end{array} \right] \\ \underset{b\in \mathrm{wt}(\mu)}{a \in \mathrm{vt}(\mu)} \\ \qquad \qquad 1 \leq i \leq 2g \\ \qquad 1 \leq j \leq 2g \end{array}$$

as the matrix given by

$$ph((x, y), (z, w)) = {}^{t}({}^{rev}M(x, y)) H^{rev}M(z, w).$$

We see $H \in \text{Mat}(2g, \mathbb{Q}[\mu])$ by consideration of 5.27 in the proof of 5.25. Moreover, as for V, the weight of any entry of H is given by

$$wt(H_{a-q+2,b-q-2}) = -(a+b-2q).$$

Example 5.30. In the case (e, q) = (2, 2g + 1), for $a = v_i = 2i - 2$ and $b = eq - v_{2g-j+1} = 4g + 2 - 2(2g - j + 1) + 2 = 2j + 2$ with $1 \le i \le g$ and $1 \le j \le g$, we see that

$$\operatorname{wt}(V_{a,b}) = \operatorname{wt}(V_{2i-2,2j+2}) = -2(i+j),$$

$$\operatorname{wt}(H_{a-q+2,\,b-q-2}) (= a+b-2q) = \operatorname{wt}(H_{v_{i-(2g+1)+2,\,v_{2g-j+1}-(2g+1)-2}}) = 2(i-j)-(2g+1)$$

Lemma 5.31. *The matrix H is of the form*

$$H = \begin{bmatrix} -eq \\ -eq & * \\ \vdots & \vdots \\ -eq & * & * \end{bmatrix}. \tag{5.32}$$

If e = 2, then we have explicitly

$$H = \begin{bmatrix} -2q & -2q & 0 \\ -2q & 0 & -2(q-2)\mu_4 \\ \vdots & \vdots & \vdots \\ -2q & \cdots -12\mu_{2(q-6)} -10\mu_{2(q-5)} & -8\mu_{2(q-4)} \\ -2q & 0 & \cdots -10\mu_{2(q-5)} & -8\mu_{2(q-4)} & -6\mu_{2(q-3)} \\ -2q & 0 & -2(q-2)\mu_4 \cdots -8\mu_{2(q-4)} & -6\mu_{2(q-3)} & -4\mu_{2(q-2)} \end{bmatrix}.$$
 (5.33)

Proof. Setting all the μ_i to be 0, we have

$$\frac{1}{2} \left| \begin{array}{c} \frac{q(-x^{q-1}+z^{q-1})}{x-z} & \frac{e(y^{e-1}-w^{e-1})}{x-z} \\ \frac{q(x^{q-1}-z^{q-1})}{y-w} & \frac{e(y^{e-1}-w^{e-1})}{y-w} \end{array} \right| = -eq(x^{q-2}+x^{q-3}z+\cdots+z^{q-2})(y^{e-2}+y^{e-3}w+\cdots+w^{e-2}).$$

It follows that the counter-diagonal entries of H are -eq. From the definitions, the weight of H is -2(eq-e-q) and $\operatorname{wt}(M_{2g}(x,y)) = -2g-1+w_g = -2(eq-q-e)$. Therefore the entries below the counter-diagonal must be 0. For the case e=2, we have

$$\frac{1}{2} \begin{vmatrix} -\frac{q(x^{q-1}-z^{q-1})+(q-2)\mu_4(x^{q-3}-z^{q-3})+\cdots+\mu_{eq-e}(x-z)}{x-z} & \frac{2y-2w}{x-z} \\ \frac{q(x^{q-1}-z^{q-1})+(q-2)\mu_4(x^{q-3}-z^{q-3})+\cdots+\mu_{eq-e}(x-z)}{y-w} & \frac{2y-2w}{y-w} \end{vmatrix}
= -2 \frac{q(x^{q-1}-z^{q-1})+(q-2)\mu_4(x^{q-3}-z^{q-3})+\cdots+\mu_{eq-e}(x-z)}{x-z}
= -2 \left(q(x^{q-2}+x^{q-3}z+\cdots+z^{q-2})+(q-2)\mu_4(x^{q-4}+x^{q-5}z+\cdots+z^{q-4})+\cdots+\mu_{eq-e} \right),$$

giving the desired form of H.

Lemma 5.34. We have $\det(V) = (-1)^g \det(T)$.

Proof. Since

$$f(x, y) \operatorname{ph}((x, y), (z, w)) = f(x, y)^{t}(\operatorname{rev} M(z, w)) H \cdot \operatorname{rev} M(x, y)$$
$$\equiv {}^{t}(\operatorname{rev} M(z, w))^{\operatorname{rev}}(-\frac{1}{eq}T) H \cdot \operatorname{rev} M(x, y) \operatorname{mod} I$$

by (1.18), and the entries in M(x, y) form a basis of $\mathbb{Q}[\mu][x, y]/(f_1(x, y), f_2(x, y))$, we see

$$V = -\frac{1}{e_a} {}^{\text{rev}}T H. \tag{5.35}$$

Since *H* is a skew-upper-triangular matrix of the form (5.32), we have proved $\det(V) = (-1)^g \det(T)$ as desired.

Lemma 5.36. We have wt(det V) = wt(det T) = -eq(e-1)(q-1).

Proof. Since the determinants of T and V are of homogeneous weight, it suffices to check the sum of weights of the counter-diagonal entries, which is given by

$$\sum_{q \in \operatorname{wt}(M)} \operatorname{wt}(T_{a,\,eq-a}) = \sum_{q \in \operatorname{wt}(M)} (-eq) = -2geq = -eq(e-1)(q-1).$$

This is the same as wt($\det(V)$) and wt($\det(T)$).

Lemma 5.37. We have
$$\text{wt}(\Delta) = -eq(e-1)(q-1)$$
. If $\gcd(e-1, q-1) = 1$, then we have $\det T = (-1)^g \det V = c \cdot \Delta$

with $c \in \mathbb{Q}^{\times}$.

Proof. Letting all the coefficients μ_j of $p_j(x)$ for $1 \le j \le e - 1$ to be zero, the discriminant Δ becomes a power of the square of the difference of all the roots of $p_e(x) = 0$. Since the weight of any root is -e, the weight of the square of the difference is

$$2 \cdot \binom{q}{2} \cdot (-e) = -eq(q-1).$$

Similar arguments on y shows that wt Δ is -qe(e-1) times an positive integer. By the assumption $\gcd(e-1,q-1)=1$, we have wt Δ is -eq(e-1)(q-1) times a positive integer. The statement follows from 5.35 combined with 1.21 (1).

Remark 5.38. The condition gcd(e-1, q-1) = 1 in 5.36 holds if e = 2 or (e, q) = (3, 4), (3, 5), for which we already know Δ explicitly as mentioned in 1.9.

From now on we assume the modality of C to be 0. For any $a \in \text{wt}(M)$, the coefficient μ_{eq-a} appears in the Weierstrass form, which is the reason why the modality is so important. Let

$$L_{k} = \sum_{i \in \text{wt}(\mu)} V_{kj} \frac{\partial}{\partial \mu_{j}} \quad (k \in \text{wt}(M)). \tag{5.39}$$

It is natural to define

$$\operatorname{wt}\left(\frac{\partial}{\partial \mu_{i}}\right) = j, \quad \operatorname{wt}(L_{\nu_{i}}) = \nu_{i}.$$

We recall the definition of the matrix Γ^{L_k} for each L_k (wt(L_k) = -k) (see 5.1), which we denote as

$$\Gamma^{L_k} = \begin{bmatrix} -eta_k & lpha_k \\ -\gamma_k & {}^t\!eta_k \end{bmatrix},$$

where α_k , $\gamma_k \in \text{Sym}(g, \mathbb{Q}[\mu])$, and

$$\alpha_{k} = [\alpha_{k;-i,k-j}], \quad \beta_{k} = [\beta_{k;j,k-i}], \quad \gamma_{k} = [\gamma_{k;-i,k+j}]$$

$$i \in \text{wt}(u)$$

$$j \in \text{wt}(u)$$

¹These should not be confused with the symplectic basis of cycles α_i and β_i in (4.2)

with decreasing order in wt(u). Then the sum of two indices of any entry gives its weight;

$$\operatorname{wt}(\alpha_{k:-i,k-i}) = -i + (k-j), \quad \operatorname{wt}(\beta_{k:i,k-i}) = j + (k-i), \quad \operatorname{wt}(\gamma_{k:-i,k+i}) = -i + (k+j).$$

Note once again that $\Gamma^{L_k} \in Mat(2g, \mathbb{Q}[\mu])$ follows from 2.1. Just to be sure, we shall redefine, as defined in (5.8),

$$H^{L_{k}} = \frac{1}{2} \begin{bmatrix} \frac{\partial}{\partial u_{w_{g}}} & \cdots & \frac{\partial}{\partial u_{w_{1}}} & u_{w_{g}} & \cdots & u_{w_{1}} \end{bmatrix} \begin{bmatrix} \alpha_{k} & \beta_{k} \\ {}^{i}\beta_{k} & \gamma_{k} \end{bmatrix} \begin{bmatrix} \frac{\partial}{\partial u_{w_{g}}} \\ \vdots \\ \frac{\partial}{\partial u_{w_{1}}} \\ u_{w_{g}} \\ \vdots \\ u_{w_{1}} \end{bmatrix}$$

$$= \frac{1}{2} \sum_{i \in \text{wt}(u)} \sum_{j \in \text{wt}(u)} \left(\alpha_{k;-i,k-j} \frac{\partial^{2}}{\partial u_{i} \partial u_{j}} + 2\beta_{k;j,k-i} u_{i} \frac{\partial}{\partial u_{j}} + \gamma_{k;-i,k+j} u_{i} u_{j} \right) + \frac{1}{2} \operatorname{Tr} \beta_{k}.$$

$$(5.41)$$

5.5. The operators tangent to the discriminant

We prove the following proposition for which there is no proof in [9].

Proposition 5.42. (Buchstaber-Leykin) Let

$$L = M(x, y)^{t} [L_{y_1} L_{y_2} \cdots L_{y_{2n}}].$$

Then, in the ring $\mathbb{Q}[\mu][x,y]/(f_1,f_2)$, we have

$$L(\Delta) = -\text{Hess}f \cdot \Delta. \tag{5.43}$$

Proof. For the case e=2, f(x,y) is of the form $y^2-p_2(x)$. We denote $p_2(x)=p(x)$ for simplicity. Moreover, we denote $p'(x)=\frac{\partial}{\partial x}p(x)$ and $p''(x)=\frac{\partial^2}{\partial x^2}p(x)$. In this case, the ring $\mathbb{Q}[\mu][x,y]/(f_1,f_2)$ is identified with $\mathbb{Q}[\mu][x]/(p'(x))$ since $f_1(x,y)=\frac{\partial}{\partial y}f(x,y)=2y$. Let F be a splitting field of p(x). We write the factorisation of p(x) in F as $p(x)=(x-a_1)\cdots(x-a_q)$. Then μ_{2i} is $(-1)^i$ times the fundamental symmetric function of a_1,\cdots,a_q of degree i. Of course the ring $\mathbb{Q}[\mu]$ is a sub-ring of $\mathbb{Q}[a_1,\cdots,a_q]$. The Hessian of $f(x,y)=y^2-p(x)$ is

$$\begin{vmatrix} -p''(x) & 0 \\ 0 & 2 \end{vmatrix} = -2 p''(x).$$

The main idea is to consider $\frac{\text{Hess}f}{2f} = \frac{p''(x)}{p(x)}$ in the localised ring

$$(F[x]/(p'(x)))_{p(x)}$$

of F[x]/(p'(x)) with respect to the multiplicative set $\{1, p(x), p(x)^2, \dots\}$ (see [20], Section 4). The following calculation is done in the localised ring above. Since $\gcd(p'(x), p(x)) = 1$ in this situation, we see $(F[x]/(p'(x)))_{p(x)} = F[x]/(p'(x))$. Now, we have

$$\begin{split} \frac{p''(x)}{p(x)} &= \sum_{(i,j),i < j} \frac{2}{(x - a_i)(x - a_j)} = \sum_{(i,j),i < j} \frac{2}{a_i - a_j} \left(\frac{1}{x - a_i} - \frac{1}{x - a_j} \right) \\ &= 2 \sum_{i=1}^q \left(\sum_{j \neq i} \frac{1}{a_i - a_j} \right) \frac{1}{x - a_i} = -2 \sum_{i=1}^q \left(\sum_{j \neq i} \frac{1}{a_i - a_j} \right) \frac{1}{p'(a_i)} \frac{-p'(a_i)}{x - a_i} \\ &= -2 \sum_{i=1}^q \left(\sum_{j \neq i} \frac{1}{a_i - a_j} \right) \frac{1}{p'(a_i)} \frac{p'(x) - p'(a_i)}{x - a_i} = -2 \sum_{i=1}^q c_i \frac{p'(x) - p'(a_i)}{x - a_i}, \end{split}$$

where

$$c_i = \left(\sum_{i \neq i} \frac{1}{a_i - a_j}\right) \frac{1}{p'(a_i)}.$$

Since $\operatorname{Hess} f(x, y) = -2p''(x)$ and p(x) = -f(x, y) in the localised ring, it suffices to show that

$$\frac{\partial}{\partial \mu_{2i}} \log \Delta = -2 \sum_{i=1}^{q} c_i a_i^{q-i}$$

up to a non-zero constant multiple. Indeed, if we have the formula above, we have

$$\begin{split} \frac{L(x)\Delta}{\Delta} &= \sum_{i,k} M_i(x,y) V_{ik} \frac{\partial}{\partial \mu_{2i}} \log \Delta = -2 \sum_{i,k} M_i(x,y) V_{ik} \sum_{j=1}^q c_j a_j^{q-k} \\ &= -2 \sum_{j=1}^q c_j \sum_{i,k} M_i(x,y) V_{ik} a_j^{q-k} = -2 \sum_{j=1}^q c_j f(x,y) \operatorname{ph} \big((x,y), (a_j,0) \big) \\ &= -2 f(x,y) \sum_{i=1}^q c_j \left(-2 \right) \frac{p'(x) - p'(a_j)}{x - a_j} = -2 f(x,y) \frac{p''(x)}{p(x)} = 2 p''(x) = -\operatorname{Hess} f(x,y). \end{split}$$

Here we have used

$$ph((x, y), (a_j, 0)) = \frac{1}{2} \begin{vmatrix} \frac{-p'(x) - p'(a_j)}{x - a_j} & \frac{2y}{x - a_j} \\ \frac{-p'(x) - p'(a_j)}{y} & \frac{2y}{y} \end{vmatrix} = -2 \frac{p'(x) - p'(a_j)}{x - a_j}.$$

To calculate $\frac{\partial \log(\Delta)}{\partial \mu_{2i}}$, we remove the assumption $\mu_2 = 0$. Since Δ is some non-zero constant multiple of

$$\prod_{i \leq j} (a_i - a_j)^2,$$

we easily get the $q \times q$ -matrix $\left[\frac{\partial \mu_{2j}}{\partial a_j}\right]$, and then we get $\frac{\partial \log(\Delta)}{\partial \mu_{2j}}$ by using its inverse matrix. For (e,q)=(3,4), (3,5), we know only a proof by direct calculation with Maple by using the explicit form of Δ and the operators L_{v_i} s.

Remark 5.44. There is another proof of 5.41 in [28]).

The following lemma is required by the proof of the next proposition.

Lemma 5.45. The derivations $\ell_j s$ and $L_j s$ are liftable to the vector fields on \mathscr{C} . Namely, there exist vector fields $\widetilde{\ell}_j s$ and $\widetilde{\ell}_j s$ on \mathscr{C} such that their induced vector fields with respect to $\pi : \mathscr{C} \to \operatorname{Spec} \mathbb{Q}[\mu]$ coincide with $\ell_j s$ and $L_j s$, respectively.

Proof. Recall the definition of T that is (2.5), namely,

$$-eq \cdot f(X,Y) \cdot M_i = \sum_{b \in \text{wtM}}^{2g} T_{a,b} M_a + A_a f_1(X,Y) + B_a f_2(X,Y).$$

Then the vector field

$$\ell_i = \sum_{i=1}^{2g} T_{ij} \frac{\partial}{\partial \mu_{w_j}} \in \text{Der}(\mathbb{Q}[\mu])$$

is liftable with respect to $\pi: \mathscr{C} \to \operatorname{Spec} \mathbb{Q}[\mu]$. Indeed, if we define

$$\widetilde{\ell}_i = \sum_{i=1}^{2g} T_{ij} \frac{\partial}{\partial \mu_{w_j}} + A_i \frac{\partial}{\partial x} + B_i \frac{\partial}{\partial y},$$

namely, for any $G(\mu, X, Y) \in \mathbb{Q}[\mu, X, Y]$,

$$\widetilde{\ell}_i: G(\mu, X, Y) \longmapsto \left(\sum_{i=1}^{2g} T_{ij} \frac{\partial}{\partial \mu_{w_j}} + A_i \frac{\partial}{\partial X} + B_i \frac{\partial}{\partial Y}\right) G(\mu, X, Y) \Big|_{(X,Y)=(x,y)},$$

we see at $(x, y, \mu) \in \mathscr{C}$ that

$$\widetilde{\ell}_i f = \sum_{i=1}^{2g} T_{ij} \frac{\partial f}{\partial \mu_{w_j}} + A_i \frac{\partial f}{\partial x} + B_i \frac{\partial f}{\partial y} = \sum_{i=1}^{2g} T_{ij} M_j + A_i f_1(x, y) + B_i f_2(x, y) = f(x, y) \cdot M_i = 0.$$

Therefore $\widetilde{\ell}_i$ is a vector field on $\mathscr C$ and its restriction to Spec $\mathbb Q[\mu]$ is ℓ_i . We see similarly that L_i is also liftable to $\mathscr C$.

On the operators in L and the discriminant Δ , we have the following.

Proposition 5.46. For a derivation $D \in \text{Der}(\mathbb{Q}[\mu])$, D is tangent to the discriminant Δ if and only if $D \in L$.

Proof. This follows from Kyoji Saito's theorem (see Theorem A4 in [5]). See also Corollary 3 on p.2716 to the theorem on the previous page in [32] and Corollary 3.4 in [1]. However, the 'if '-part of the statement for the cases (e, q) = (2, q), (3, 4) is contained in 5.41.

Obviously, we see

$$\left[\bigoplus_{i}\mathbb{Q}[\mu]\frac{\partial}{\partial\mu_{i}},\bigoplus_{i}\mathbb{Q}[\mu]\frac{\partial}{\partial\mu_{i}}\right]\subset\bigoplus_{i}\mathbb{Q}[\mu]\frac{\partial}{\partial\mu_{i}},$$

but on $\{\ell_i\}$, we have the following.

Corollary 5.47. We have $[\ell_i, \ell_i] \in \bigoplus_i \mathbb{Q}[\mu] \ell_i$ in $Der(\mathbb{Q}[\mu])$. Moreover,

$$L = \bigoplus_{i} \mathbb{Q}[\mu] \ \ell_{i} \subset \operatorname{Der}_{\mathbb{Q}[\mu]} \left(\mathbb{Q}[\mu, x, y] \frac{dx}{f_{y}} + d \left(\mathbb{Q}[\mu, x, y] \frac{1}{f_{y}} \right) \right).$$

Proof. Since $[\ell_i, \ell_j]$ is tangent to Δ by 5.41, 5.45 shows the first assertion. Therefore, we have the second assertion from 2.2.

Because of 5.35, 5.47, and det $([H_{ij}]) = (eq)^{2g} \in \mathbb{Q}$, we see the Lie algebra generated by L_k s in (5.39) is no other than L, namely,

$$L = \bigoplus_{k} \mathbb{Q}[\mu] L_{k}. \tag{5.48}$$

The structure constants of the algebra L with respect to $\{L_{\nu_j}\}$ belong to $\mathbb{Q}[\mu]$, so it is a polynomial Lie algebra, as discussed in [6]. The corresponding fundamental relations of $\{L_{\nu_j}\}$ for (e, q) = (2, 3), (2, 5), (2, 7) and (3, 4) are available on request.

5.6. The sigma function as a solution of the heat equations

Before showing that the function (4.16) is exactly the sigma function $\sigma(u)$ (see Lemma 4.17 in [9]), we shall first describe some heuristic arguments supporting this result.

From the definition of L_0 and 5.29, we have

$$L_0 = \sum_{i} (eq - v_i) \mu_{eq - v_j} \frac{\partial}{\partial \mu_{eq - v_j}}, \text{ and } L_0(F(\mu)) = -\text{wt}(F(\mu))F(\mu)$$
(5.49)

for any homogeneous form $F(\mu) \in \mathbb{Q}[\mu]$. The operator L_0 is called *Euler vector field*.

Lemma 5.50. On $H^1_{d\mathbb{R}}(\mathscr{C}/\mathbb{Q}[\mu])$, we have

$$L_0{}^t\boldsymbol{\omega} = \begin{bmatrix} -w_g & & & & & \\ & \ddots & & & & \\ & & -w_1 & & & \\ & & & w_g & & \\ & & & \ddots & \\ & & & & w_1 \end{bmatrix} {}^t\boldsymbol{\omega} = \Gamma_0{}^t\boldsymbol{\omega}.$$

Proof. For a power series expansion at ∞ of any 1-form ω of homogeneous weight w

$$\omega = \sum_{i} c_{j} t^{j+w} dt,$$

where *t* is a local parameter at ∞ of weight 1, $c_j \in \mathbb{Q}[\mu]$ is of homogeneous weight -j-1,

$$L_{0}\left(\sum_{j}c_{j}t^{j+w}dt\right) + w\sum_{j}c_{j}t^{j+w}dt = \sum_{j}(j+1)c_{j}t^{j+w}dt + \sum_{j}wc_{j}t^{j+w}dt$$
$$= \sum_{j}(j+w+1)c_{j}t^{j+w}dt = d\left(\sum_{j}c_{j}t^{j+w+1}\right).$$

If ω is any one of ω_{w_i} , which is of the form $\frac{h(x,y)}{f_2(x,y)} dx$ with $h(x,y) \in \mathbb{Q}[\mu][x,y]$, we see the last above is

$$d\left(\frac{h(x,y)}{f_2(x,y)} \cdot t \frac{dx}{dt}\right). \tag{5.51}$$

Since we can choose t as a quotient of monomials of x and y (see [27], Section 3), (5.51) is an exact form. So that

$$L_0(\omega) = -\operatorname{wt}(\omega) \omega \text{ in } H^1_{dR}(\mathscr{C}/\mathbb{Q}[\mu]).$$

As $\operatorname{wt}(\omega_i) = i$ and $\operatorname{wt}(\eta_{-i}) = -i$, the statement is now obvious.

The function $\sigma(u)$, characterised in 4.1, is a power series of homogeneous weight, which must be written as²

$$\sigma(u) = u_1^{(e^2-1)(q^2-1)/24}$$

$$\sum_{\{n_{eq-v_j},\ell_{w_i}\}} a(\ell_{w_2},\cdots,\ell_{w_g},n_{eq-v_1},\cdots,n_{eq-v_{2g}}) \prod_{j=1}^{2g} (\mu_{eq-v_j} u_1^{eq-v_j})^{n_{eq-v_j}} \prod_{i=2}^{g} \left(\frac{u_{w_i}}{u_1^{w_i}}\right)^{\ell_{w_i}},$$
(5.52)

where the $a(\ell_{w_2}, \dots, \ell_{w_g}, n_{eq-v_1}, \dots, n_{eq-v_{2g}})$'s are absolute constants and the set of 3g-1 variables $\{n_{eq-v_j}, \ell_{w_i}\}$ runs through the non-negative integers such that

$$\frac{(e^2-1)(q^2-1)}{24} - \sum_{i=2}^g \ell_{w_i} + \sum_{i=1}^{2g} n_{eq-v_j} \ge 0.$$

Here, we shall mention that in Lemma 4.17 of [8] and its proof here along the lines of our reconstruction of BL theory, that is if $\sigma(u)$ can be written as $\sigma(u) = \Delta^{-M} \tilde{\sigma}(u)$ with a numerical constant M, then $M = \frac{1}{9}$. Before doing so, we point out the following lemma.

Lemma 5.53. The constant

$$((2\pi)^g/(\det \omega'))^{\frac{1}{2}} \det (V)^{-\frac{1}{8}} = ((2\pi)^g/(\det \omega'))^{\frac{1}{2}} \det (T)^{-\frac{1}{8}}, \tag{5.54}$$

is of weight $(e^2 - 1)(q^2 - 1)/24$. Hence, if (e, q) = (2, 3), (2, 5), (2, 7), or (3, 4), (see 5.36) or if the conjecture 1.23 is true, $((2\pi)^g/(\det \omega'))^{\frac{1}{2}} \Delta^{-\frac{1}{8}}$ is also of weight $(e^2 - 1)(q^2 - 1)/24$.

Proof. We know the weight of det $(V)^{\frac{1}{8}}$ is -eq(e-1)(q-1)/8 by 5.35. The weight of det (ω') is $\sum_{i=1}^{g} w_i$, which equals

$$\sum_{i=1}^{g} w_i = \frac{eq(e-1)(q-1)}{4} - \frac{(e^2-1)(q^2-1)}{12}$$

by p.97 of [7]. Hence the weight of the constant (5.54) is $\frac{(e^2-1)(q^2-1)}{24}$.

Remark 5.55. (1) Note that the weight of the constant above is exactly that of $\sigma(u)$. (2) From (5.24) and (5.54), we see the series (5.52) and both of

$$\det(V)^{-\frac{1}{8}}\tilde{\sigma}(u)$$
 and $\Delta^{-\frac{1}{8}}\tilde{\sigma}(u)$

are killed by

$$L_{0} - H^{L_{0}} - \frac{1}{8} L_{0} \log \Delta = L_{0} - H^{L_{0}} + \text{wt}(\sigma(u))$$

$$= \sum_{j=1}^{g} (eq - v_{j}) \mu_{eq-v_{j}} \frac{\partial}{\partial \mu_{eq-v_{j}}} - \sum_{j=1}^{g} w_{j} u_{w_{j}} \frac{\partial}{\partial u_{w_{j}}} + \frac{(e^{2} - 1)(q^{2} - 1)}{24}.$$
(5.56)

In the rest of the paper, we use the notation

$$H_{\nu_i} = H^{L_{\nu_i}} - \frac{1}{8}L_{\nu_i} \log \Delta,$$

where $H^{L_{v_i}}$ is defined by (5.41). Then 5.21 and (5.24) imply the following.

²A different notation here, the ℓ_{w_i} s here are positive integers, not the operators in (2.8).

Theorem 5.57. We have $(L_{v_i} - H_{v_i}) \hat{\sigma}(u) = 0$ for $j = 1, \dots, 2g$.

The following theorem is one of the important consequences of the BL theory.

Theorem 5.58. The function $\sigma(u)$ is equal to $\hat{\sigma}(u)$ up to a non-zero absolute constant.

Proof. For (e, q) = (2, 3), (2, 5), (2, 7),and (3, 4), we will solve the system of equations

$$(L_{v_i} - H_{v_i}) \varphi(u) = 0 \quad (i = 1, \dots, 2g)$$
 (5.59)

for an unknown entire function $\varphi(u)$, and show that the solution space of this system is of dimension 1, in Section 6. Any solution eventually satisfies the properties of $\sigma(u)$ in (4.1). Hence we have proved that $\sigma(u)$ is equal to $\hat{\sigma}(u)$ up to a non-zero absolute constant.

From now on, throughout this paper, we denote

$$\Gamma_{v_i} = \Gamma^{L_{v_j}}$$
.

Especially, $\Gamma_0 = \Gamma^{L_0} = \Gamma^{L_{\nu_1}}$.

Remark 5.60. As noted above in 5.7, our notation differs from that of Buchstaber and Leykin; we denote the matrix Γ_j in p.274 of [9] by Γ_j^{BL} and we define the sub-matrices of $-J\Gamma_j^{BL}$ and $\Gamma_{v_i}J$ by

$$-J\Gamma_{j}^{\mathrm{BL}} = \begin{bmatrix} \alpha_{j}^{\mathrm{BL}} \ {}^{t}(\beta_{j}^{\mathrm{BL}}) \\ \beta_{j}^{\mathrm{BL}} \ \ \gamma_{j}^{\mathrm{BL}} \end{bmatrix}, \ \ \Gamma_{\nu_{j}}J = \begin{bmatrix} \alpha_{\nu_{j}} \ \beta_{\nu_{j}} \\ {}^{t}(\beta_{\nu_{j}}) \ \gamma_{\nu_{j}} \end{bmatrix}$$

by following the notation of [9] and the present paper. Then we have for any j that

$$\alpha_i^{\mathrm{BL}} = \alpha_{\nu_i}, \quad \beta_i^{\mathrm{BL}} = {}^{t}(\beta_{\nu_i}), \quad \gamma_i^{\mathrm{BL}} = \gamma_{\nu_i}, \quad \Gamma_i^{\mathrm{BL}} = {}^{t}(\Gamma_{\nu_i}).$$

6. Solving the heat equations

6.1. The initial conditions

For the rest of the paper, we shall solve the system of equations (5.59) for the (2, 3)-, (2, 5)-, (2, 7)-, and (3, 4)-curves. We frequently switch from regarding the μ_j s as indeterminates to regarding them as elements in \mathbb{C} . We suppose the following two initial conditions for any solution $\varphi(u)$ solving (5.59): **IC1**. $\varphi(u) \in \mathbb{Q}[\mu][[u_{w_g}, \cdots, u_{w_1}]]$, and **IC2**. $\varphi(u)$ is of homogeneous weight $\frac{1}{24}(e^2 - 1)(q^2 - 1)$ with respect to u_i s and μ_j s.

Since the property (4) in 4.1 is stronger than these conditions, there may be a possibility to reduce the characterisation in 4.1 of the sigma function, in general.

It is not clear to the authors which part of [9] shows that the space of the solutions $\varphi(u) = \varphi(\mu, u_{w_g}, \dots, u_{w_2}, u_{w_1}) \in \mathbb{Q}[\mu][[u_{w_g}, \dots, u_{w_2}, u_{w_1}]]$ of (5.59) is one dimensional. The main part of the present paper, that is from 6.3 to the end of the paper, is a partial answer to this question.

6.2. General results for the (2, 3)-curve

In this subsection, we discuss the hyperelliptic case, that is the case e = 2. Firstly, we give the explicit expression for the entries of the matrix V of (5.28). The authors know that the issue in this subsection is described in p.566 in V.I.Arnol'd's [1] and p.65 in [2]. Since they do not know any source which contains a proof, we shall give a detailed proof here.

Lemma 6.1. We have

$$\begin{split} V_{2i-2,2j+2} &= -\frac{2i(q-j)}{q} \; \mu_{2i}\mu_{2j} + \sum_{m=1}^{m_0} 2(j-i+2m) \; \mu_{2(i-m)} \; \mu_{2(j+m)} \\ &= -\frac{2i(q-j)}{q} \; \mu_{2i}\mu_{2j} + \sum_{\ell=\ell_0}^{i-1 \text{ or } j} 2(i+j-2\ell) \; \mu_{2\ell} \; \mu_{2(i+j-\ell)}, \end{split}$$

where $\mu_0 = 1$, $\mu_2 = 0$, $m_0 = \min\{i, q - j\}$, and $\ell_0 = \max\{0, i + j - q\}$.

Proof. First of all, assuming the first equality, we show the second equality. To change the first expression to the second with summation to i-1, we use the substitution $\ell=i-m$. It is obvious that the second equality with summation to i-1 is equal to one with summation to j for i=j, j+1. For the case of i < j, the difference of the two is expressed as

$$\sum_{\ell=i}^{j} 2(i+j-2\ell) \, \mu_{2\ell} \, \mu_{2(i+j-\ell)} = -\sum_{\ell'=i}^{j} 2(i+j-2\ell') \, \mu_{2(i+j-\ell')} \, \mu_{2\ell'}$$

setting $\ell' = i + j - \ell$, it is clear that this vanishes. We see the case j < i in a similar way. The matrix $V = [V_{2i-2,2j+2}]$ is symmetric by definition. However, if the Lemma is proved, we see this directly, by subtracting the term for $\ell = j$ from the first term. Now, noting that in the hyperelliptic case, the $M_{2j-2}(X, Y)$ are independent of Y, we define $M^{(2i-2)} = M^{(2i-2)}(X) \in \mathbb{Z}[\mu][X]$ by using $[H_{2i-q,2j-q}]$ of (5.33):

$$M^{(2i-2)}(X) = \sum_{i=1}^{q-1} H_{2i-q, 2j-q} M_{2q-2-2j}(X, Y) = \sum_{m=0}^{i-1} 2(q+1+m-i) \, \mu_{2(i-m-1)} X^m.$$

While we are treating $f(X, Y) = Y^2 - p_2(X)$, we denote $p_2(X)$ by p(X) in this proof, for a less cumbersome notation.

Since $f_1 = p'(X)$, $f_2 = 2Y$, we see $\mathbb{Q}[\mu][X,Y]/(f_1,f_2)$ is isomorphic to $\mathbb{Q}[\mu][X]/(p'(X))$. So that, it suffices to know explicitly the residue $V^{(i)} = V^{(i)}(X)$ of degree less than q-1 of the division of p(X) $M^{(2i-2)}(X)$ by p'(X) for $1 \le i \le q-1$. The key to this proof is that we actually know the quotient $Q^{(2i)} = Q^{(2i)}(X) \in \mathbb{Q}[\mu][X]$, as well as $V^{(2q+2i-2)} = V^{(2q+2i-2)}(X)$ defined below, of this division! Namely, we will show that, if we define functions

$$Q^{(2i)}(X) = \sum_{m=1}^{i} 2\mu_{2(i-m)} X^m + \frac{2i}{q} \mu_{2i},$$

then the expression

$$V^{(2q+2i-2)}(X) = p(X) M^{(2i-2)}(X) - p'(x) Q^{(2i)}(X)$$
(6.2)

is of degree less than q-1. Moreover, we can calculate all the terms of $V^{(2q+2i-2)}$ explicitly, which are no other than the $V_{2i-2,2j-2}$'s.

Let us start to calculate each term of X^k of the right-hand side of (6.2) for any $k \ge 0$. We divide the calculation into four cases. (i) The case $k \ge q$. In this case, $M^{(2i-2)}$ has terms only up to X^{i-1} ($i-1 \le q-2 < q \le k$), and p(X) has terms up to X^q ($q \le k$). Therefore, we find that the coefficient C_{2k} of X^k in $M^{(2i-2)}(X)$ p(X) is given by

$$C_{2k} = \sum_{m=k-q}^{i-1} 2(q+1-i+m) \,\mu_{2(i-1-m)} \,\mu_{2(q-k+m)}$$
$$= \sum_{m'=q-1-k}^{i} 2(k-m'+1) \,\mu_{2(q-1-k+m')} \,\mu_{2(i-m')},$$

where we have changed the summation index by q - k + m = i - m'. On the other hand, $Q^{(2i)}$ has terms up to X^i ($i \le q - 1 < q \le k$), and p'(X) has terms up to X^{q-1} (q - 1 < k), so we see

"Coeff. of
$$X^k$$
 in $Q^{(i)}(X)$ $p'(X)$ " = $\sum_{m=k-q+1}^{i} 2 \mu_{2(i-m)} \mu_{2(q-1-k+m)}(k-m+1)$.

So the right-hand side of (6.2) has no term in X^k for $k \ge q$. (ii) The case k = q - 1. Since $M^{(2i-2)}$ has terms only up to X^{i-1} ($i - 1 \le q - 2 < q - 1 = k$), we see that

"Coeff. of
$$X^k$$
 in $M^{(2i-2)}(X) p(X)$ " = $\sum_{m=0}^{i-1} 2(q+1-i+m) \mu_{2(i-1-m)} \mu_{2(1+m)}$

$$= \sum_{m'=0}^{i-1} 2(q-m') \,\mu_{2m'} \,\mu_{2(i-m')} = \sum_{m'=1}^{i-1} 2(q-m') \,\mu_{2m'} \,\mu_{2(i-m')} + 2q \,\mu_0 \mu_{2i},$$

where we have changed the index of summation by m+1=i-m'. In this case $Q^{(2i-2)}$ has terms up to X^i ($i \le q-1=k$), and p'(X) has terms up to X^{q-1} (q=k), we have that the coefficient C_{2k} of X^k in $Q^{(2i)}(X)$ p'(X) is given by

$$C_{2k} = \sum_{m=1}^{i} 2 \,\mu_{2(i-m)} \,\mu_{2m}(q-m) + \frac{2i}{q} \mu_{2i} \,\mu_0 \,q$$

$$= \sum_{m=1}^{i-1} 2 \,\mu_{2(i-m)} \,\mu_{2m}(q-m) + 2(q-i) \,\mu_0 \,\mu_{2i} + 2i \,\mu_{2i} \,\mu_0.$$

So the right-hand side of (6.2) has no term in X^{q-1} . (iii) The case i-1 < k < q-1. Since $M^{(2i-2)}$ has terms only up to X^{i-1} , we see that the coefficient D_{2k} of X^k in $M^{(2i-2)}(X)$ p(X) is given by

$$D_{2k} = \sum_{m=0}^{i-1} 2(q+1+m-i) \,\mu_{2(i-m-1)} \,\mu_{2(q-k+m)}$$
$$= \sum_{m=1}^{i} 2(q+m-i) \,\mu_{2(i-m)} \,\mu_{2(q-1-k+m)}$$

by rewriting m as m-1. On the other hand, the coefficient C_{2k} of X^k in $Q^{(2i)}(X) p'(X)$ is

$$C_{2k} = \frac{2i}{q} \mu_{2i} (k+1) \mu_{q-1-k} + \sum_{m=1}^{i} 2 \mu_{2(i-m)} (k-m-1) \mu_{2(q-1-k+m)}.$$

So the coefficient of X^k in the right-hand side of (6.2) is

$$\sum_{m=1}^{i} 2(q-1-k+2m-i) \, \mu_{2(i-m)} \, \mu_{2(q-1-k+m)} + \frac{2i}{q}(k+1) \mu_{2i} \, \mu_{2(q-1-k)}$$

and $V_{2i-2,2j-2}$, which is no other than the value of this at k=q-1-j, is given by

$$\sum_{m=1}^{i} 2(j+2m-i) \, \mu_{2(i-m)} \, \mu_{2(j+m)} + \frac{2i}{q} (q-j) \mu_{2i} \, \mu_{2j}$$

as desired since i < k + 1 = q - j.

(iv) The case k < i - 1. Since $M^{(2i-2)}$ has terms up to X^{i-1} , of higher degree than X^k , we see that the coefficient D_{2k} of X^k in $M^{(2i-2)}(X)$ p(X) is given by

$$D_{2k} = \sum_{m=0}^{k} 2(q+1+m-i) \,\mu_{2(i-m-1)} \,\mu_{2(q-k+m)}$$
$$= \sum_{m=1}^{k+1} 2(q+m-i) \,\mu_{2(i-m)} \,\mu_{2(q-1-k+m)}$$

on replacing the summation index m by m+1. Similarly, $Q^{(2i)}$ has terms up to X^i exceeding X^k again, and

"Coeff. of
$$X^k \operatorname{inp}'(X) Q^{(2i)}(X)$$
"
$$= \frac{2i}{q} \mu_{2i} \mu_{q-1-k} + \sum_{i=1}^{k+1} 2 \mu_{2(i-m)} (k-m-1) \mu_{2(q-1-k+m)}$$

with an extra term for m = k + 1 which is zero. So the coefficient of X^k in the right-hand side of (6.2) is

$$\sum_{m=1}^{k+1} 2(q-1-k+2m-i) \,\mu_{2(i-m)} \,\mu_{2(q-1-k+m)} + \frac{2i}{q}(k+1)\mu_{2i} \,\mu_{2(q-1-k)}$$

and then V_{ij} , which is no other than the value of this at k = q - 1 - j, is given by

$$V_{2i-2, 2j-2} = \sum_{m=1}^{q-j} 2(j+2m-i) \,\mu_{2(i-m)} \,\mu_{2(j+m)} + \frac{2i}{q}(q-j)\mu_{2i} \,\mu_{2j}$$

as desired since $q - j = k + 1 \le i$.

Secondly, we give the values $L_{\nu_i}(\log \Delta) = \frac{L_{\nu_i}\Delta}{\Delta}$ for the case (e, q) = (2, q).

Lemma 6.3. If e = 2, then we have $L_{2i}(\Delta) = -2(q-j)(q-1-j)\mu_{2i} \Delta$ for $0 \le j \le q-2$.

Proof. Since the Hessian of $f(X, Y) = Y^2 - p_2(X)$ is

$$\begin{vmatrix} -p_2''(X) & 0 \\ 0 & 2 \end{vmatrix} = -2 p_2''(X)$$

$$= -2(q(q-1)X^{q-2} + (q-2)(q-3)\mu_4 X^{q-4} + \dots + 2 \cdot 1 \mu_{q-3}),$$

this lemma follows from (5.43).

6.3. Heat equations for the (2, 3)-curve

In this section we recall Weierstrass' result which gives a recursive relation for the coefficients of the power series expansion of his sigma function at the origin. We refer the reader to (12) and (13) in p. 314 of [14] also. Here we derive Weierstrass' result by following the method of [9], namely, following the theory described in previous sections, but without using the general results 6.1 and 6.3, in order to demonstrate the ideas of the theory.

Weierstrass' original method is explained in [31] and some explanation of it is available in [25]. It is easy to get L_0 and L_2 :

$$V = \begin{bmatrix} 4\mu_4 & 6\mu_6 \\ 6\mu_6 - \frac{4}{3}\mu_4^2 \end{bmatrix}, \text{ and } \begin{cases} L_0 = 4\mu_4 \frac{\partial}{\partial \mu_4} + 6\mu_6 \frac{\partial}{\partial \mu_6} \\ L_2 = 6\mu_6 \frac{\partial}{\partial \mu_4} - \frac{4}{3}\mu_4^2 \frac{\partial}{\partial \mu_6}. \end{cases}$$
(6.4)

In this case, we see V = T since

$$ph((x, y), (z, w)) = -6x - 6z = \begin{bmatrix} x & 1 \end{bmatrix} \begin{bmatrix} -6 \\ -6 \end{bmatrix} \begin{bmatrix} z \\ 1 \end{bmatrix}.$$

Then $\Delta = 2^2 \cdot 3 \cdot \det(V)$ (see 1.6). The differential forms

$$\omega_1 = \frac{dx}{2y}, \quad \eta_{-1} = \frac{xdx}{2y}$$

form a symplectic basis of $H^1_{\mathrm{dR}}(\mathscr{C}/\mathbb{Q}[\mu])$. We have $\boldsymbol{\omega}=(\,\omega_1,\,\,\eta_{-1}\,)$. Bearing in mind Lemma 2.4, we proceed by using $x^{-\frac{1}{2}}$ as the local parameter satisfying $\frac{\partial}{\partial \mu_j}x=0$ for $j=4,\,6$, and we compute the matrix Γ as follows. Using f(x,y)=0, we see $2y\frac{\partial}{\partial \mu_4}y=x$ and $2y\frac{\partial}{\partial \mu_6}y=1$, so that

$$\frac{\partial}{\partial \mu_4} y = \frac{x}{2y}, \quad \frac{\partial}{\partial \mu_6} y = \frac{1}{2y}.$$

Therefore, we have

$$\frac{\partial}{\partial \mu_6} \omega_1 = -\frac{1}{4v^3} dx, \quad \frac{\partial}{\partial \mu_4} \omega_1 = \frac{\partial}{\partial \mu_6} \eta_{-1} = -\frac{x}{4v^3} dx, \quad \frac{\partial}{\partial \mu_4} \eta_{-1} = -\frac{x^2}{4v^3} dx, \tag{6.5}$$

and

$$d\left(\frac{1}{y}\right) = -\frac{1}{y^2}dy = -\frac{1}{y^2}\frac{dy}{dx}dx = -\frac{1}{y^2}\frac{3x^2 + \mu_4}{2y}dx = 6\frac{\partial}{\partial\mu_4}\eta_{-1} + 2\mu_4\frac{\partial}{\partial\mu_6}\omega_1,$$

$$d\left(\frac{x}{y}\right) = \frac{ydx - xdy}{y^2} = \frac{y - x\frac{dy}{dx}}{y^2}dx = \frac{y - x\frac{3x^2 + \mu_4}{2y}}{y^2}dx$$

$$= \frac{y - \frac{3y^2 - 2\mu_4 x - 3\mu_6}{2y}}{y^2}dx = -\omega_1 - 4\mu_4\frac{\partial}{\partial\mu_4}\omega_1 - 6\mu_6\frac{\partial}{\partial\mu_6}\omega_1 = -\omega_1 - L_0\omega_1,$$

$$d\left(\frac{x^2}{y}\right) = \frac{2xydx - x^2dy}{y^2} = \frac{2xy - x^2\frac{dy}{dx}}{y^2}dx = \frac{2xy - x^2\frac{3x^2 + \mu_4}{2y}}{y^2}dx$$

$$= \frac{2xy - \frac{3x(y^2 - \mu_4 x - \mu_6) + \mu_4 x^2}{2y}}{y^2}dx = \frac{xdx}{2y} + \frac{\mu_4 x^2}{y^3}dx + \frac{3}{2}\frac{\mu_6 x}{y^3}dx$$

$$= \eta_{-1} - L_0\eta_{-1}$$

$$= \eta_{-1} + \frac{4}{3}\mu_4^2\frac{\partial}{\partial\mu_6}\omega_1 - 6\mu_6\frac{\partial}{\partial\mu_4}\omega_1 - \frac{2}{3}\mu_4d\left(\frac{1}{y}\right) \quad (\text{by (6.6)})$$

$$= \eta_{-1} - L_2\omega_1 - \frac{2}{3}\mu_4d\left(\frac{1}{y}\right).$$

Accordingly, we see

$$\begin{split} L_{2}\eta_{-1} &= 6\mu_{6}\frac{\partial}{\partial\mu_{4}}\eta_{-1} - \frac{4}{3}\mu_{4}^{2}\frac{\partial}{\partial\mu_{6}}\eta_{-1} \\ &= -2\mu_{6}\mu_{4}\frac{\partial}{\partial\mu_{6}}\omega_{1} - \frac{4}{3}\mu_{4}^{2}\frac{\partial}{\partial\mu_{4}}\omega_{1} + \mu_{6}d\left(\frac{1}{y}\right) \quad \text{(by (6.5) and (6.6))} \\ &= -\frac{\mu_{4}}{3}\left(6\mu_{6}\frac{\partial}{\partial\mu_{6}}\omega_{1} + 4\mu_{4}\frac{\partial}{\partial\mu_{4}}\omega_{1}\right) + \mu_{6}d\left(\frac{1}{y}\right) \\ &= -\frac{\mu_{4}}{3}L_{0}\omega_{1} + \mu_{6}d\left(\frac{1}{y}\right) = \frac{\mu_{4}}{3}\omega_{1} + \mu_{6}d\left(\frac{1}{y}\right). \end{split}$$

Summarising these results, we have on $H^1_{dR}(\mathscr{C}/\mathbb{Q}[\mu])$ that

$$L_0{}^t \boldsymbol{\omega} = \Gamma_0{}^t \boldsymbol{\omega}, \ L_2{}^t \boldsymbol{\omega} = \Gamma_2{}^t \boldsymbol{\omega}, \ \text{where} \ \Gamma_0 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \ \Gamma_2 = \begin{bmatrix} 1 \\ \frac{\mu_4}{2} \end{bmatrix}.$$

Note that, by these equations, we have $L_j\Omega = \Gamma_j\Omega$ with $\Omega = \begin{bmatrix} \omega' & \omega'' \\ \eta' & \eta'' \end{bmatrix}$ as in (5.12). Since $(L_0, L_2)(\det(T)) = (12, 0) \det(T)$ (by 6.3), $\Delta = 2^2 \cdot 3 \cdot \det(T)$, and (5.49), we have arrived at

$$(L_0 - H_0)\sigma(u) = \left(4\mu_4 \frac{\partial}{\partial \mu_4} + 6\mu_6 \frac{\partial}{\partial \mu_6} - u\frac{\partial}{\partial u} + 1\right)\varphi(u) = 0,$$

$$(L_2 - H_2)\sigma(u) = \left(6\mu_6 \frac{\partial}{\partial \mu_4} - \frac{4}{3}\mu_4^2 \frac{\partial}{\partial \mu_6} - \frac{1}{2}\frac{\partial^2}{\partial u^2} + \frac{1}{6}\mu_4 u^2\right)\varphi(u) = 0,$$
(6.8)

where $H_j = H^{L_j} + \frac{1}{8}L_j \log \Delta$ for j = 0 and 2. From the first of (6.8) and the conditions **IC1**, **IC2**, the solution function is of the form

$$\varphi(u) = u \sum_{n_1, n_2 \ge 0} b(n_4, n_6) \frac{(\mu_4 u^4)^{n_4} (\mu_6 u^6)^{n_6}}{(1 + 4n_4 + 6n_6)!}.$$

Using the second equation we then have a recurrence relation

$$b(n_4, n_6) = \frac{2}{3}(4n_4 + 6n_6 - 1)(2n_4 + 3n_6 - 1)b(n_4 - 1, n_6)$$

$$-\frac{8}{3}(n_6 + 1)b(n_4 - 2, n_6 + 1) + 12(n_4 + 1)b(n_4 + 1, n_6 - 1)$$
(6.9)

if $n_4 \ge 0$, $n_6 \ge 0$, $(n_4, n_6) \ne (0, 0)$, and $b(n_4, n_6) = 0$ if $n_4 < 0$ or $n_6 < 0$. Since the term $b(n_4, n_6)$ on the left-hand side has weight $4n_4 + 6n_6$, and the terms b(i, j) on the right-hand side have weight smaller than this, all terms may be found from (6.9). Therefore, any solution of (6.8) is a constant times the function

$$\varphi(u) = \sigma(u) = u + 2\mu_4 \frac{u^5}{5!} + 24\mu_6 \frac{u^7}{7!} - 36\mu_4^2 \frac{u^9}{9!} - 288\mu_4 \mu_6 \frac{u^{11}}{11!} + \cdots$$

6.4. Heat equations for the (2, 5)-curve

In this section, we list the analogous results for the heat equations for the curve

$$\mathcal{C}_{\mu}: y^2 = x^5 + \mu_4 x^3 + \mu_6 x^2 + \mu_8 x + \mu_{10}.$$

We note here that our results correct a sign in [8]; the overall constant $\frac{1}{80}$ at the 4th line from bottom in page 68 of [8] should be $-\frac{1}{80}$. Here we give the Hurwitz series version of the algorithm. Now, we take a usual symplectic basis of differentials

$$\omega_3 = \frac{1}{2y}dx$$
, $\omega_1 = \frac{x}{2y}dx$, $\eta_{-3} = \frac{3x^3 + \mu_4 x}{2y}dx$, $\eta_{-1} = \frac{x^2}{2y}dx$

of $H^1_{d\mathbb{R}}(\mathscr{C}/\mathbb{Q}[\mu])$. The matrix V for this case is given by

$$V = \begin{bmatrix} 4\mu_4 & 6\mu_6 & 8\mu_8 & 10\mu_{10} \\ 6\mu_6 & -\frac{12}{5}\mu_4^2 + 8\mu_8 & -\frac{8}{5}\mu_4\mu_6 + 10\mu_{10} & -\frac{4}{5}\mu_4\mu_8 \\ 8\mu_8 & -\frac{8}{5}\mu_4\mu_6 + 10\mu_{10} & -\frac{12}{5}\mu_6^2 + 4\mu_4\mu_8 & 6\mu_4\mu_{10} - \frac{6}{5}\mu_6\mu_8 \\ 10\mu_{10} & -\frac{4}{5}\mu_4\mu_8 & 6\mu_4\mu_{10} - \frac{6}{5}\mu_6\mu_8 & 4\mu_{10}\mu_6 - \frac{8}{5}\mu_8^2 \end{bmatrix}.$$

A calculation by Maple along 1.5 gives $\Delta = 2^4 \cdot 5 \cdot \det(V)$. The operators L_j are given by

$${}^{t}[L_{0} L_{2} L_{4} L_{6}] = V^{t} \left[\frac{\partial}{\partial \mu_{4}} \frac{\partial}{\partial \mu_{6}} \frac{\partial}{\partial \mu_{8}} \frac{\partial}{\partial \mu_{10}} \right].$$

While the authors have the explicit commutation relations of these L_i , we shall not include these here because their explicit forms are not needed in this paper. However, these commutators are all in the span of the L_i . By 6.3, we see that these L_i 's operate on the discriminant Δ as follows:

$$[L_0 \ L_2 \ L_4 \ L_6]\Delta = [40 \ 0 \ 12 \mu_4 \ 4 \mu_6]\Delta.$$

The representation matrices Γ_i for the L_i acting on $H^1_{dR}(\mathscr{C}/\mathbb{Q}[\mu])$ are

$$\Gamma_{0} = \begin{bmatrix} -3 \\ -1 \\ 3 \\ 1 \end{bmatrix}, \quad \Gamma_{2} = \begin{bmatrix} \frac{4}{5} \mu_{4} & 1 \\ \frac{4}{5} \mu_{4}^{2} - 3\mu_{8} & -\frac{4}{5} \mu_{4} \\ \frac{3}{5} \mu_{4} & 1 \end{bmatrix},$$

$$\Gamma_{4} = \begin{bmatrix} -\mu_{4} & 1 \\ \frac{6}{5} \mu_{6} & 1 \\ \frac{6}{5} \mu_{4} \mu_{6} - 6\mu_{10} - \mu_{8} \mu_{4} - \frac{6}{5} \mu_{6} \\ -\mu_{8} & \frac{2}{5} \mu_{6} \end{bmatrix}, \quad \Gamma_{6} = \begin{bmatrix} \frac{3}{5} \mu_{8} & 1 \\ \frac{3}{5} \mu_{4} \mu_{8} - 2\mu_{10} & -\frac{3}{5} \mu_{8} \\ -2 \mu_{10} & \frac{1}{5} \mu_{8} \end{bmatrix}.$$

Therefore, we find the following operators H_i :

$$\begin{split} H_0 &= 3u_3\frac{\partial}{\partial u_3} + u_1\frac{\partial}{\partial u_1} - 3, \\ H_2 &= \frac{1}{2}\frac{\partial^2}{\partial u_1^2} + u_1\frac{\partial}{\partial u_3} - \frac{4}{5}\mu_4u_3\frac{\partial}{\partial u_1} - \frac{3}{10}\mu_4{u_1}^2 - \left(\frac{3}{2}\mu_8 - \frac{2}{5}\mu_4^2\right)u_3^2, \\ H_4 &= \frac{\partial^2}{\partial u_1\partial u_3} - \frac{6}{5}\mu_6u_3\frac{\partial}{\partial u_1} + \mu_4u_3\frac{\partial}{\partial u_3} - \frac{1}{5}\mu_6u_1^2 + \mu_8u_1u_3 + \left(3\mu_{10} - \frac{3}{5}\mu_4\mu_6\right)u_3^2 - \mu_4, \\ H_6 &= \frac{1}{2}\frac{\partial^2}{\partial u_2^2} - \frac{3}{5}\mu_8u_3\frac{\partial}{\partial u_1} - \frac{1}{10}\mu_8u_1^2 + 2\mu_{10}u_3u_1 - \frac{3}{10}\mu_8\mu_4u_3^2 - \frac{1}{2}\mu_6. \end{split}$$

By the equation $(L_0 - H_0) \varphi(u) = 0$ and the conditions **IC1** and **IC2**, the solution function must be of the form

$$\varphi(u) = \sigma(u_3, u_1) = \sum_{\substack{m, n_4, n_6, n_8, n_{10} \ge 0 \\ 3 - 3m + 4n_4 + 6n_6 + 8n_8 + 10n_{10} \ge 0}} \left[b(m, n_4, n_6, n_8, n_{10}) \right.$$

$$\cdot \frac{u_1^3 \left(\frac{u_3}{u_1^3}\right)^m \left(\mu_4 u_1^4\right)^{n_4} \left(\mu_6 u_1^6\right)^{n_6} \left(\mu_8 u_1^8\right)^{n_8} \left(\mu_{10} u_1^{10}\right)^{n_{10}}}{m! \left(3 - 3m + 4n_4 + 6n_6 + 8n_8 + 10n_{10}\right)!} \right].$$

Let $k = 3 - 3m + 4n_4 + 6n_6 + 8n_8 + 10n_{10}$. Then the other heat equations $(L_j - H_j) \varphi(u) = 0$ imply the following recursion scheme:

$$b(m, n_4, n_6, n_8, n_{10}) = \begin{cases} B_2 & (\text{if } k > 1 \text{ and } m \ge 0) \\ B_1 & (\text{if } k = 1 \text{ and } m > 0) \\ B_0 & (\text{if } k = 0 \text{ and } m > 1), \end{cases}$$

where the B_i are given by

$$B_2 = 20(n_8 + 1) b(m, n_4, n_6, n_8 + 1, n_{10} - 1) \\ + 16(n_6 + 1) b(m, n_4, n_6 + 1, n_8 - 1, n_{10}) \\ + 12(n_4 + 1) b(m, n_4 + 1, n_6 - 1, n_8, n_{10}) \\ - \frac{24}{5}(n_6 + 1) b(m, n_4 - 2, n_6 + 1, n_8, n_{10}) \\ + \frac{3}{5}(k - 3)(k - 2) b(m, n_4 - 1, n_6, n_8, n_{10}) \\ - \frac{8}{5}(n_{10} + 1) b(m, n_4 - 1, n_6, n_8 - 1, n_{10} + 1) \\ - \frac{16}{5}(n_8 + 1) b(m, n_4 - 1, n_6, n_8 - 1, n_{10} + 1) \\ - 2(k - 2) b(m + 1, n_4, n_6, n_8, n_{10}) \\ - 3m(m - 1) b(m - 2, n_4, n_6, n_8 - 1, n_{10}) \\ + \frac{4}{5}m(m - 1) b(m - 2, n_4 + 2, n_6, n_8, n_{10}) \\ + \frac{8}{5}m b(m - 1, n_4 - 1, n_6, n_8, n_{10}) \\ + \frac{10}{5}(n_8 + 1) b(m - 1, n_4, n_6 + 1, n_8, n_{10} - 1) \\ - \frac{12}{5}(n_8 + 1) b(m - 1, n_4, n_6 - 2, n_8 + 1, n_{10}) \\ - \frac{6}{5}(n_{10} + 1) b(m - 1, n_4, n_6 - 1, n_8 - 1, n_{10}) \\ - \frac{1}{5}(5m - 10 + 8n_6 - 20n_8 - 30n_{10}) b(m - 1, n_4 + 1, n_6, n_8, n_{10}) \\ - \frac{1}{5}(m - 1)(m - 2) b(m - 3, n_4 - 1, n_6, n_8, n_{10}) \\ + \frac{3}{5}(m - 1) b(m - 2, n_4, n_6 - 1, n_8, n_{10}) \\ + \frac{6}{5}(m - 1) b(m - 2, n_4, n_6, n_8, n_{10} - 1) \\ + \frac{1}{5}(12n_8 - 40n_{10} - 5) b(m - 2, n_4, n_6, n_8, n_{10} - 1) \\ + 20(n_4 + 1) b(m - 2, n_4 + 1, n_6, n_8, n_{10} - 1) \\ + \frac{8}{5}(n_6 + 1) b(m - 2, n_4 - 1, n_6, n_8 + 1, n_{10}) \\ + \frac{3}{5}(m - 2)(m - 3) b(m - 4, n_4 - 1, n_6, n_8 - 1, n_{10}) \\ + \frac{3}{5}(m - 2)(m - 3) b(m - 4, n_4 - 1, n_6, n_8 - 1, n_{10}).$$

From these, we see that the expansion of $\sigma(u)$ is Hurwitz integral over $\mathbb{Z}[\frac{1}{5}]$.

Remark 6.10. Actually, the above recurrence scheme is one of several possible recurrence relations. However, we see any such system gives the same solution space by the following argument. Here, of course, we suppose that $b(m, n_4, \dots, n_{10}) = 0$ if k or any of the explicit arguments is negative. For any finite subset $S \subset \{(m, n_4, \dots, n_{10}) \mid k, n_4, \dots, n_{10} \geq 0\}$, we take the set E_S of relations h between $\{b(m, n_4, \dots, n_{10})\}$ such that any $b(m, n_4, \dots, n_{10})$ appears as a term in h provided that $(m, n_4, \dots, n_{10}) \in S$. For instance, if we consider

$$S = \{(1, 0, 0, 0, 0), (0, 0, 0, 0, 0), (0, 1, 0, 0, 0), (1, 1, 0, 0, 0), (2, 1, 0, 0, 0)\},\$$

then E_S consists of the following 4 equations:

$$b(0, 0, 0, 0, 0) = -2b(1, 0, 0, 0, 0),$$

$$b(0, 1, 0, 0, 0) = 12b(0, 0, 0, 0, 0) - 10b(1, 1, 0, 0, 0),$$

$$b(1, 1, 0, 0, 0) = \frac{6}{5}b(1, 0, 0, 0, 0) - 4b(2, 1, 0, 0, 0) - \frac{16}{5}b(0, 0, 0, 0, 0),$$

$$b(2, 1, 0, 0, 0) = \frac{1}{5} \cdot 0 \cdot b(1, 0, 0, 0, 0).$$

The solution space of such a system of linear equations E_S is of dimension 1 or larger because we have at least one iteration system as above whose solution space is of dimension 1. Since E_S is independent of the choice of recursion system, any recursion system must include the same solution space of dimension 1.

The first few terms of the sigma expansion are given as follows (up to a constant multiple):

$$\sigma(u_3, u_1) = u_3 - 2\frac{u_1^3}{3!} - 4\mu_4 \frac{u_1^7}{7!} - 2\mu_4 \frac{u_3 u_1^4}{4!} + 64\mu_6 \frac{u_1^9}{9!} - 8\mu_6 \frac{u_3 u_1^6}{6!}$$

$$-2\mu_6 \frac{u_3^2 u_1^3}{2!3!} + \mu_6 \frac{u_3^3}{3!} + (1600\mu_8 - 408\mu_4^2) \frac{u_1^{11}}{11!}$$

$$-(4\mu_4^2 + 32\mu_8) \frac{u_3 u_1^8}{8!} - 8\mu_8 \frac{u_3^2 u_1^5}{2!5!} - 2\mu_8 \frac{u_3^3 u_1^2}{3!2!} + \cdots$$

6.5. The heat equations for the (2,7)-curve

We take the hyperelliptic genus three curve $\mathscr C$ in the Weierstrass form

$$y^2 = f(x) = x^7 + \mu_4 x^5 + \mu_6 x^4 + \mu_8 x^3 + \mu_{10} x^2 + \mu_{12} x + \mu_{14}$$

The discriminant Δ of \mathscr{C} is the resultant of f and f_1 . It has 320 terms and is of weight 84. The matrix V is given by

$$V = \begin{bmatrix} 4 \,\mu_4 & 6 \,\mu_6 & 8 \,\mu_8 \\ 6 \,\mu_6 & -\frac{4}{7} \left(5 \,\mu_4^2 - 14 \,\mu_8\right) & -\frac{2}{7} \left(8 \,\mu_6 \mu_4 - 35 \,\mu_{10}\right) \\ 8 \,\mu_8 & -\frac{2}{7} \left(8 \,\mu_6 \mu_4 - 35 \,\mu_{10}\right) & \frac{4}{7} \left(21 \,\mu_{12} - 6 \,\mu_6^2 + 7 \,\mu_4 \mu_8\right) \\ 10 \,\mu_{10} & -\frac{12}{7} \left(\mu_4 \mu_8 - 7 \,\mu_{12}\right) & \frac{2}{7} \left(49 \,\mu_{14} - 9 \,\mu_6 \mu_8 + 21 \,\mu_4 \mu_{10}\right) \\ 12 \,\mu_{12} & -\frac{2}{7} \left(4 \,\mu_4 \mu_{10} - 49 \,\mu_{14}\right) & \frac{4}{7} \left(14 \,\mu_4 \mu_{12} - 3 \,\mu_6 \mu_{10}\right) \\ 14 \,\mu_{14} & -\frac{4}{7} \,\mu_4 \mu_{12} & \frac{2}{7} \left(35 \,\mu_4 \mu_{14} - 3 \,\mu_6 \mu_{12}\right) \end{bmatrix}$$

$$\begin{array}{c} 10\,\mu_{10} & 12\,\mu_{12} \\ -\frac{12}{7}\,\left(\mu_{4}\mu_{8}-7\,\mu_{12}\right) & -\frac{2}{7}\,\left(4\,\mu_{4}\mu_{10}-49\,\mu_{14}\right) \\ \frac{2}{7}\,\left(21\,\mu_{4}\mu_{10}-9\,\mu_{6}\mu_{8}+49\,\mu_{14}\right) & \frac{4}{7}\,\left(14\,\mu_{4}\mu_{12}-3\,\mu_{6}\mu_{10}\right) \\ \frac{4}{7}\,\left(7\,\mu_{6}\mu_{10}-6\,\mu_{8}^{2}+14\,\mu_{4}\mu_{12}\right) & \frac{2}{7}\,\left(21\,\mu_{6}\mu_{12}-8\,\mu_{10}\mu_{8}+35\,\mu_{4}\mu_{14}\right) \\ \frac{2}{7}\,\left(21\,\mu_{6}\mu_{12}-8\,\mu_{10}\mu_{8}+35\,\mu_{4}\mu_{14}\right) & \frac{4}{7}\,\left(7\,\mu_{12}\mu_{8}-5\,\mu_{10}^{2}+14\,\mu_{6}\mu_{14}\right) \\ \frac{8}{7}\,\left(7\,\mu_{6}\mu_{14}-\mu_{12}\mu_{8}\right) & \frac{2}{7}\,\left(21\,\mu_{14}\mu_{8}-5\,\mu_{12}\mu_{10}\right) \\ & \frac{8}{7}\,\left(7\,\mu_{6}\mu_{14}-\mu_{12}\mu_{8}\right) & \frac{2}{7}\,\left(21\,\mu_{14}\mu_{8}-5\,\mu_{12}\mu_{10}\right) \\ & \frac{4}{7}\,\left(7\,\mu_{14}\mu_{10}-3\,\mu_{12}^{2}\right) \end{array}\right].$$

Here a calculation by Maple along 1.5 shows that $\Delta = 2^6 \cdot 7 \cdot \det(V)$. Then we have

$${}^{t}[L_{0} L_{2} L_{4} L_{6} L_{8} L_{10}] = V^{t} \left[\frac{\partial}{\partial \mu_{4}} \frac{\partial}{\partial \mu_{6}} \frac{\partial}{\partial \mu_{8}} \frac{\partial}{\partial \mu_{10}} \frac{\partial}{\partial \mu_{12}} \frac{\partial}{\partial \mu_{14}} \right].$$

Using 6.3, their operation on Δ are given by

$$[L_0 L_2 L_4 L_6 L_8 L_{10}](\Delta) = [84\ 0\ 40\mu_4\ 24\mu_6\ 12\mu_8\ 4\mu_{10}]\Delta.$$

As for the (2, 5)-case, we have fundamental relations for these L_i as a set of generators of certain Lie algebra, which we do not include here. The symplectic basis of $H^1_{dR}(\mathscr{C}/\mathbb{Q}[\mu])$ is

$$\omega_5 = \frac{dx}{2y}, \quad \omega_3 = \frac{xdx}{2y}, \quad \omega_1 = \frac{x^2dx}{2y}, \quad \eta_{-5} = \frac{(5x^5 + 3\mu_4x^3 + 2\mu_6x^3 + \mu_8x^2)dx}{2y},$$
$$\eta_{-3} = \frac{(3x^4 + \mu_4x^2)dx}{2y}, \quad \eta_{-1} = \frac{x^3dx}{2y}.$$

With respect to these, the matrices $\Gamma_j = \begin{bmatrix} -\beta_j & \alpha_j \\ -\gamma_j & {}^t\beta_j \end{bmatrix}$ are given as follows:

$$\alpha_{0} = O, \quad \beta_{0} = \begin{bmatrix} 5 & 3 & \\ & 1 \end{bmatrix}, \quad \gamma_{0} = O,$$

$$\alpha_{2} = \begin{bmatrix} & & 3 & \\ & 1 \end{bmatrix}, \quad \beta_{2} = \begin{bmatrix} & & 3 & \\ & -\frac{4}{7}\mu_{4} & & 1 \\ & & -\frac{8}{7}\mu_{4} \end{bmatrix},$$

$$\gamma_{2} = \begin{bmatrix} -\frac{1}{7}(4\mu_{4}\mu_{8} - 35\mu_{12}) & & \\ & & -\frac{5}{7}\mu_{4} \end{bmatrix},$$

$$\gamma_{2} = \begin{bmatrix} -\frac{1}{7}(8\mu_{4}\mu_{8} - 35\mu_{12}) & & \\ & & -\frac{5}{7}\mu_{4} \end{bmatrix},$$

$$\alpha_{4} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \ \beta_{4} = \begin{bmatrix} 3\mu_{4} & 1 \\ -\frac{6}{7}\mu_{6} & \mu_{4} \\ -\frac{12}{7}\mu_{6} \end{bmatrix},$$

$$\gamma_{4} = \begin{bmatrix} -\frac{2}{7}(3\mu_{6}\mu_{8} - 35\mu_{14}) & 3\mu_{12} \\ 3\mu_{12} & -\frac{6}{7}(2\mu_{4}\mu_{6} - 7\mu_{10}) & \mu_{8} \\ \mu_{8} & -\frac{4}{7}\mu_{6} \end{bmatrix},$$

$$\alpha_{6} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \ \beta_{6} = \begin{bmatrix} 2\mu_{6} & \mu_{4} \\ -\frac{8}{7}\mu_{8} \\ -\frac{9}{7}\mu_{8} \end{bmatrix},$$

$$\gamma_{6} = \begin{bmatrix} 3\mu_{4}\mu_{12} - \frac{8}{7}\mu_{8}^{2} & 6\mu_{14} & \mu_{12} \\ 6\mu_{14} & -\frac{9}{7}\mu_{4}\mu_{8} + 9\mu_{12} & 2\mu_{10} \\ \mu_{12} & 2\mu_{10} & -\frac{3}{7}\mu_{8} \end{bmatrix},$$

$$\alpha_{8} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \ \beta_{8} = \begin{bmatrix} \mu_{8} \\ -\frac{10}{7}\mu_{10} \\ \mu_{12} & -\frac{6}{7}\mu_{10} \end{bmatrix},$$

$$\gamma_{8} = \begin{bmatrix} 6\mu_{4}\mu_{14} + 2\mu_{6}\mu_{12} - \frac{10}{7}\mu_{8}\mu_{10} & \mu_{4}\mu_{12} & 2\mu_{14} \\ \mu_{4}\mu_{12} & -\frac{6}{7}\mu_{4}\mu_{10} + 12\mu_{14} & 3\mu_{12} \\ 2\mu_{14} & 3\mu_{12} & -\frac{2}{7}\mu_{10} \end{bmatrix},$$

$$\alpha_{10} = \begin{bmatrix} 1 \\ \end{bmatrix}, \ \beta_{10} = \begin{bmatrix} -\frac{5}{7}\mu_{12} \\ 2\mu_{14} & -\frac{3}{7}\mu_{12} \end{bmatrix},$$

$$\gamma_{10} = \begin{bmatrix} 4\mu_{6}\mu_{14} - \frac{5}{7}\mu_{8}\mu_{12} & 2\mu_{4}\mu_{14} \\ 2\mu_{4}\mu_{14} & -\frac{3}{7}\mu_{4}\mu_{12} & 4\mu_{14} \\ 4\mu_{14} & -\frac{1}{7}\mu_{12} \end{bmatrix}.$$

These give a set of heat equations $(L_i - H_i) \sigma(u) = 0$ as before.

6.6. The sigma function for the (2,7)-curve

We now solve (5.59) in the (2,7) case. The initial conditions IC1, IC2 of (5.59) in this case are as follows:

$$\varphi(u) \in \mathbb{Q}[\mu][[u_5, u_3, u_1]],$$
 and $\varphi(u)$ is of homogeneous weight6.

Following [8] but in the Hurwitz series form as [31], we write any solution $\varphi(u)$ as

$$\varphi(u_{5}, u_{3}, u_{1}) = \sum_{\substack{\ell, m, n_{4}, n_{6}, n_{8}, \\ n_{10}, n_{12}, n_{14}}} b(\ell, m, n_{4}, n_{6}, n_{8}, n_{10}, n_{12}, n_{14})$$

$$\cdot (\mu_{4}u_{1}^{4})^{n_{4}} (\mu_{6}u_{1}^{6})^{n_{6}} (\mu_{8}u_{1}^{8})^{n_{8}} (\mu_{10}u_{1}^{10})^{n_{10}} (\mu_{12}u_{1}^{12})^{n_{12}} (\mu_{14}u_{1}^{14})^{n_{14}}$$

$$\cdot \frac{u_{1}^{6} (\frac{u_{5}}{u_{1}^{5}})^{\ell} (\frac{u_{3}}{u_{1}^{3}})^{m}}{(6 - 5\ell - 3m + 4n_{4} + 6n_{6} + 8n_{8} + 10n_{10} + 12n_{12} + 14n_{14})! \ell! m!} \bigg],$$

giving a solution of $(L_0 - H_0) \varphi(u) = 0$. If we define

$$k = 6 - 5\ell - 3m + 4n_4 + 6n_6 + 8n_8 + 10n_{10} + 12n_{12} + 14n_{14}$$

the above expression is rewritten as

$$\varphi(u_{5}, u_{2}, u_{1}) = \sum b(\ell, m, n_{4}, n_{6}, n_{8}, n_{10}, n_{12}, n_{14})$$

$$\cdot \mu_{4}^{n_{4}} \mu_{6}^{n_{6}} \mu_{8}^{n_{8}} \mu_{10}^{n_{10}} \mu_{12}^{n_{12}} \mu_{14}^{n_{14}} \frac{u_{5}^{\ell}}{\ell!} \frac{u_{3}^{m}}{m!} \frac{u_{1}^{k}}{k!},$$
(6.11)

where we require all the integer indices k, ℓ , m, n_4 , n_6 , n_8 , n_{10} , n_{12} , n_{14} to be non-negative.

Note that the *u*-weight of this expression is $k_0 = 6 + 4n_4 + 6n_6 + 8n_8 + 10n_{10} + 12n_{12} + 14n_{14}$, which does not depend on ℓ or m. (Note also that $k = k_0 - 5\ell - 3m$). For fixed n_4 , n_6 , n_8 , n_{10} , n_{12} , $n_{14} \ge 0$, $k_0 \ge 0$ is fixed, and for non-negative k, we require $\ell = 0, \ldots, \lfloor (k_0 + 6)/5 \rfloor$, $m = 0, \ldots, \lfloor (6 + k_0 - 5\ell)/3 \rfloor$. As noted above, if we insert this ansatz into the equation for $(L_0 - H_0)\varphi = 0$, we get an expression which is identically zero, for any set of $b(\ell, m, n_4, n_6, n_8, n_{10}, n_{12}, n_{14})$.

If we insert this ansatz into the expression for $(L_2 - H_2)\varphi = 0$, we get (after some algebra, and providing k > 0) the recurrence relation shown below, involving 20 terms (compare the equations on p.68 of [8] for the genus 2 case). We can structure this relation by the *weight* of each *b* coefficient of (6.11) (more precisely by the weight of the corresponding term in the expansion). We will call this P_2 :

$$-7b(\ell, m, n_4, n_6, n_8, n_{10}, n_{12}, n_{14})$$

$$+14(2-k)b(\ell, m+1, n_4, n_6, n_8, n_{10}, n_{12}, n_{14})$$

$$-42mb(\ell+1, m-1, n_4, n_6, n_8, n_{10}, n_{12}, n_{14})$$

$$+196(n_{12}+1)b(\ell, m, n_4, n_6, n_8, n_{10}, n_{12}+1, n_{14}-1)$$

$$+168(n_{10}+1)b(\ell, m, n_4, n_6, n_8, n_{10}+1, n_{12}-1, n_{14})$$

$$+140(n_8+1)b(\ell, m, n_4, n_6, n_8+1, n_{10}-1, n_{12}, n_{14})$$

$$+112(n_6+1)b(\ell, m, n_4, n_6+1, n_8-1, n_{10}, n_{12}, n_{14})$$

$$+5(3-k)(2-k)b(\ell, m, n_4-2, n_6+1, n_8, n_{10}, n_{12}, n_{14})$$

$$-8(n_{14}+1)b(\ell, m, n_4-1, n_6, n_8, n_{10}, n_{12}-1, n_{14}+1)$$

$$-16(n_{12}+1)b(\ell, m, n_4-1, n_6, n_8, n_{10}, n_{12}-1, n_{14}+1)$$

$$-24(n_{10}+1)b(\ell, m, n_4-1, n_6, n_8-1, n_{10}+1, n_{12}, n_{14})$$

$$-32(n_8+1)b(\ell, m, n_4-1, n_6-1, n_8+1, n_{10}, n_{12}, n_{14})$$

$$+84(n_4+1)b(\ell, m, n_4+1, n_6-1, n_8, n_{10}, n_{12}, n_{14})$$

$$+84(n_4+1)b(\ell, m-2, n_4, n_6, n_8-1, n_{10}, n_{12}, n_{14})$$

$$+8m(m-1)b(\ell, m-2, n_4-2, n_6, n_8, n_{10}, n_{12}, n_{14})$$

$$+16mb(\ell, m-1, n_4-1, n_6, n_8, n_{10}, n_{12}, n_{14})$$

$$+36\ell(\ell-1)b(\ell-2, m, n_4-1, n_6, n_8, n_{10}, n_{12}, n_{14})$$

$$+4\ell(\ell-1)b(\ell-2, m, n_4-1, n_6, n_8, n_{10}, n_{12}, n_{14})$$

$$+8\ell b(\ell-1, m+1, n_4-1, n_6, n_8, n_{10}, n_{12}, n_{14})$$

This relation applies only for k > 1 and can be written as

$$\begin{split} P_2 &: b(\ell, m, n_4, n_6, n_8, n_{10}, n_{12}, n_{14}) \\ &= 2 (2 - k) b(\ell, 1 + m, n_4, n_6, n_8, n_{10}, n_{12}, n_{14}) \\ &- 6m b(1 + \ell, m - 1, n_4, n_6, n_8, n_{10}, n_{12}, n_{14}) + \text{`` lower weight terms''}, \end{split}$$

where the lower weight terms have coefficients which are quadratic or linear in ℓ , m, n_4 , n_6 , n_8 , n_{10} , n_{12} , n_{14} , times integers or rational numbers with denominators 7. Here the number $4n_4 + 6n_6 + 8n_8 + 10n_{10} + 12n_{12} + 14n_{14}$ for

$$b(\ell, m, n_4, n_6, n_8, n_{10}, n_{12}, n_{14})$$

is the μ weight of the term. For P_2 , the left-hand side and the first two terms on the right-hand side all have the μ -weight $W = 4n_4 + 6n_6 + 8n_8 + 10n_{10} + 12n_{12} + 14n_{14}$. The next highest μ -weight terms of the 'lower weight terms' are of μ -weight W - 2, and the lowest weight terms are of μ -weight W - 12.

Putting the same ansatz into $(L_4 - H_4)\varphi = 0$ we get another recurrence P_4 with 20 terms, providing m > 0 and k > 0. We can write this as

$$P_4: b(\ell, 1+m, n_4, n_6, n_8, n_{10}, n_{12}, n_{14})$$

$$= -7(k-1) b(1+\ell, m-1, n_4, n_6, n_8, n_{10}, n_{12}, n_{14}) + \text{``lower weight terms''}.$$

Here the lower weight terms have the same property as P_2 . We have another relation from the equation $(L_6 - H_6)\varphi = 0$

$$P_6$$
: $b(\ell, m+2, n_4, n_6, n_8, n_{10}, n_{12}, n_{14})$
+ $2b(1+\ell, m, n_4, n_6, n_8, n_{10}, n_{12}, n_{14}) =$ "lower weight terms".

We can write this in two different ways which will each come in useful

$$\begin{split} P_{6a} &: b(l, m, n_4, n_6, n_8, n_{10}, n_{12}, n_{14}) \\ &= -2 \, b(l+1, m-2, n_4, n_6, n_8, n_{10}, n_{12}, n_{14}) + \text{``lower weight terms''}, \\ P_{6b} &: 2 \, b(l, m, n_4, n_6, n_8, n_{10}, n_{12}, n_{14}) \\ &= -b(l-1, m+2, n_4, n_6, n_8, n_{10}, n_{12}, n_{14}) + \text{``lower weight terms''}. \end{split}$$

Continuing, we have two further relations, from the equations $(L_8 - H_8)\varphi = 0$ and $(L_{10} - H_{10})\varphi = 0$,

$$P_8: b(\ell+1, m+1, n_4, n_6, n_8, n_{10}, n_{12}, n_{14}) = \text{``lower}\mu - \text{weight terms''},$$

 $P_{10}: b(\ell+2, m, n_4, n_6, n_8, n_{10}, n_{12}, n_{14}) = \text{``lower}\mu - \text{weight terms''},$

where the lower μ -weight terms have the same properties as P_2 and P_4 . The relations P_6 , P_8 , P_{10} have a total of 24, 24, 19 terms respectively. As before, we need to normalise the expansion, so we choose b(1, 0, 0, 0, 0, 0, 0, 0) = 1. We need to find relations which either express coefficients in terms of ones with lower or equal μ -weight.

Clearly, we must take care with our recurrence relation to avoid infinite looping. We find that the following choice of recurrence scheme results in a sequence which decreases the μ -weight after no

more than one extra step at any point in the recurrence:

$$b(\ell, m, n_4, n_6, n_8, n_{10}, n_{12}, n_{14})$$

$$= \begin{cases}
0 & \text{if } \min\{k, \ell, m, n_4, n_6, n_8, n_{10}, n_{12}, n_{14}\} < 0, \\
1 & \text{if } \ell = 1, m = n_4 = n_6 = n_8 = n_{10} = n_{12} = n_{14} = 0, \\
\text{rhs}(P_2) & \text{if } k > 1, \\
\text{rhs}(P_4) & \text{if } k = 1, m > 0, \\
\text{rhs}(P_{6a}) & \text{if } k = 1, m = 0 \text{ (and } \ell > 0), \\
\text{rhs}(P_{6b}) & \text{if } k = 0, m > 1, \\
\text{rhs}(P_8) & \text{if } k = 0, m = 1 \text{ and } \ell > 0, \\
\text{rhs}(P_{10}) & \text{if } k = 0, m = 0 \text{ and } \ell > 1.
\end{cases}$$

Note that the structure of this complicated linear recurrence relation does *not* depend on the moduli μ_i . We have used this to calculate the terms on the Hurwitz series for the solution up to weight 40 in u_i (weight 34 in the μ_i). As for the (2, 5)-curve, there is another possible recursion scheme:

$$b(\ell, m, n_4, n_6, n_8, n_{10}, n_{12}, n_{14})$$

$$= \begin{cases}
0 & \text{if } \min\{k, \ell, m, n_4, n_8, n_{10}, n_{12}, n_{14}\} < 0, \\
1 & \text{if } \ell = 1, m = n_4 = n_8 = n_{10} = n_{12} = n_{14} = 0, \\
\text{rhs}(P_{10}) & \text{if } \ell > 1, \\
\text{rhs}(P_8) & \text{if } \ell = 1, m > 0, \\
\text{rhs}(P_{6a}) & \text{if } \ell = 1, m = 0 \text{ and } k > 0, \\
\text{rhs}(P_4) & \text{if } \ell = 0, m > 0 \text{ and } k > 0, \\
\text{rhs}(P_{6b}) & \text{if } \ell = 0, m > 0 \text{ and } k = 0, \\
\text{rhs}(P_2) & \text{if } \ell = 0, \text{ and } m = 0.
\end{cases}$$

We have used this to calculate the terms in the series up to weight 40 in $\{u_j\}$, or equivalently, weight 35 in the $\{\mu_i\}$. The first few terms of the expansion are given as follows (up to a constant multiple):

$$\varphi(u) = \sigma(u_5, u_3, u_1) = 16 \frac{u_1^6}{6!} - 2 \frac{u_1^3 u_3}{3!} - 2 \frac{u_3^2}{2!} + u_5 u_1 + 64 \mu_4 \frac{u_1^{10}}{10!} + 36 \mu_4 \frac{u_1^7 u_3}{7!}$$

$$-4 \mu_4 \frac{u_1^4 u_3^2}{4!2!} - 2 \mu_4 \frac{u_1 u_3^3}{3!} + 2 \mu_4 \frac{u_5 u_1^5}{5!} - 512 \mu_6 \frac{u_1^{12}}{12!} + 64 \mu_6 \frac{u_1^9 u_3}{9!}$$

$$+16 \mu_6 \frac{u_1^6 u_3^2}{6!2!} - 8 \mu_6 \frac{u_1^3 u_3^3}{3!^2} - 8 \mu_6 \frac{u_3^4}{4!} + 24 \mu_6 \frac{u_5 u_1^7}{7!} + \cdots$$

Further studies are required to establish whether there are other recursion schemes which can be used to generate the series, and which recursions could be considered the most efficient in some sense.

6.7. The heat equations for the (3,4)-curve

We take the trigonal genus three curve $\mathscr{C} = \mathscr{C}_{\mu}^{3,4}$ in the Weierstrass form

$$y^3 = (\mu_8 + \mu_5 x + \mu_2 x^2)y + x^4 + \mu_6 x^2 + \mu_9 x + \mu_{12}.$$

The matrix V is given by

$$V = \begin{bmatrix} V_{a,b} \\ {}_{a \in \{0,3,4,6,7,10\}} \\ {}_{b \in \{2,5,6,8,9,12\}} \end{bmatrix} = \begin{bmatrix} V^{(1,1)} & V^{(1,2)} \\ {}^{t}V^{(1,2)} & V^{(2,2)} \end{bmatrix},$$

where

$$V^{(1,1)} = \begin{bmatrix} 2 \mu_2 & 5 \mu_5 & 6 \mu_6 \\ 5 \mu_5 & \frac{1}{6} \mu_2^4 - 4 \mu_2 \mu_6 + 8 \mu_8 & -\frac{1}{2} \mu_2^2 \mu_5 + 9 \mu_9 \\ 6 \mu_6 & -\frac{1}{2} \mu_2^2 \mu_5 + 9 \mu_9 & \frac{2}{3} \mu_2^2 \mu_6 + \frac{10}{3} \mu_2 \mu_8 + \frac{5}{3} \mu_5^2 \end{bmatrix}$$

and

$$\begin{split} V^{(1,2)} = \begin{bmatrix} 8 \, \mu_8 & 9 \, \mu_9 \\ \frac{1}{12} \, \mu_2{}^3\mu_5 - \frac{1}{2} \, \mu_2\mu_9 - \frac{3}{2} \, \mu_5\mu_6 & \frac{1}{6} \, \mu_2{}^3\mu_6 - \frac{1}{3} \, \mu_2{}^2\mu_8 - \frac{1}{6} \, \mu_2\mu_5{}^2 - 3 \, \mu_6{}^2 + 12 \, \mu_{12} \\ \frac{4}{3} \, \mu_2{}^2\mu_8 - \frac{7}{12} \, \mu_2\mu_5{}^2 + 12 \, \mu_{12} & \frac{4}{3} \, \mu_2{}^2\mu_9 - \frac{7}{6} \, \mu_2\mu_5\mu_6 + \frac{13}{3} \, \mu_5\mu_8 \\ & 12 \, \mu_{12} \\ \frac{1}{12} \, \mu_2{}^3\mu_9 - \frac{1}{6} \, \mu_2\mu_5\mu_8 - \frac{3}{2} \, \mu_6\mu_9 \\ & 2 \, \mu_2{}^2\mu_{12} - \frac{7}{12} \, \mu_2\mu_5\mu_9 + \frac{8}{3} \, \mu_8{}^2 \end{bmatrix}, \end{split}$$

and the remaining elements are

$$\begin{split} V_{6,8} &= \frac{1}{24} \, \mu_2{}^2 \mu_5{}^2 + 6 \, \mu_2 \mu_{12} - \frac{7}{2} \, \mu_5 \mu_9 + 4 \, \mu_6 \mu_8, \\ V_{6,9} &= V_{5,4} = \frac{1}{12} \, \mu_2{}^2 \mu_5 \mu_6 + \frac{7}{6} \, \mu_2 \mu_5 \mu_8 - \frac{5}{12} \, \mu_5{}^3 - \frac{3}{2} \, \mu_6 \mu_9, \\ V_{6,10} &= V_{6,4} = \frac{1}{24} \, \mu_2{}^2 \mu_5 \mu_9 + \frac{4}{3} \, \mu_2 \mu_8{}^2 - \frac{5}{12} \, \mu_5{}^2 \mu_8 + 6 \, \mu_6 \mu_{12} - \frac{9}{4} \, \mu_9{}^2, \\ V_{7,9} &= \frac{1}{6} \, \mu_2{}^2 \mu_6{}^2 + 2 \, \mu_2{}^2 \mu_{12} + \frac{5}{3} \, \mu_2 \mu_5 \mu_9 - \frac{8}{3} \, \mu_2 \mu_6 \mu_8 - \frac{4}{3} \, \mu_5{}^2 \mu_6 + \frac{8}{3} \, \mu_8{}^2, \\ V_{7,12} &= V_{6,5} &= \frac{1}{12} \, \mu_2{}^2 \mu_6 \mu_9 + 3 \, \mu_2 \mu_5 \mu_{12} - \frac{5}{6} \, \mu_2 \mu_8 \mu_9 - \frac{5}{12} \, \mu_5{}^2 \mu_9 - \frac{1}{2} \, \mu_5 \mu_6 \mu_8, \\ V_{10,12} &= \frac{1}{24} \, \mu_2{}^2 \mu_9{}^2 + 2 \, \mu_2 \mu_8 \mu_{12} + \mu_5{}^2 \mu_{12} - \frac{11}{6} \, \mu_5 \mu_8 \mu_9 + \frac{4}{3} \, \mu_6 \mu_8{}^2. \end{split}$$

The discriminant Δ of \mathscr{C} is calculated by Maple along 1.5, has 670 terms and is of weight 72. The result shows $\Delta = 3^3 \cdot 4^2 \cdot \det(V)$. Now, after a calculation by Maple (which shows 5.41), we have

$$[L_0 L_3 L_4 L_6 L_7 L_{10}] \Delta = [72 \ 0 \ -8\mu_2^2 \ 12\mu_6 \ -8\mu_2\mu_5 \ -\mu_5^2 -4\mu_2\mu_8] \Delta.$$

As in the (2,7)-case, we have fundamental relations for these L_i as a set of generators of certain Lie algebra. The symplectic basis of $H^1_{d\mathbb{R}}(\mathscr{C}/\mathbb{Q}[\mu])$ in this case is given by

$$\omega_5 = \frac{dx}{3y^2}, \ \omega_2 = \frac{xdx}{3y^2}, \ \omega_1 = \frac{ydx}{3y^2}, \ \eta_{-5} = \frac{5x^2ydx}{3y^2}, \ \eta_{-2} = \frac{2xydx}{3y^2}, \ \eta_{-1} = \frac{x^2dx}{3y^2}.$$

The matrices $\Gamma_j = \begin{bmatrix} -\beta_j & \alpha_j \\ -\gamma_i & {}^t\beta_i \end{bmatrix}$ are given as follows³:

$$\begin{split} &\alpha_0 = O, \;\; \beta_0 = \begin{bmatrix} 5 \\ 2 \\ 1 \end{bmatrix}, \;\; \gamma_0 = O, \\ &\alpha_3 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \;\; \beta_3 = \begin{bmatrix} \frac{2}{12} \mu_2^3 - \frac{3}{2} \mu_6 & -\frac{1}{2} \mu_2 \\ -\frac{1}{6} \mu_5 \mu_2 & -\frac{1}{3} \mu_2^2 \end{bmatrix}, \\ &\gamma_3 = \begin{bmatrix} 5 \mu_3 \mu_8 - \frac{1}{3} \mu_2^2 \mu_9 + \frac{1}{12} \mu_2^4 \mu_5 - \frac{5}{3} \mu_2 \mu_3 \mu_6 & -\mu_2 \mu_8 & \mu_9 \\ -\mu_2 \mu_8 & \frac{2}{3} \mu_5 \mu_2 & \frac{1}{6} \mu_2^3 - \mu_6 \end{bmatrix}, \\ &\alpha_4 = \begin{bmatrix} 1 \\ \frac{1}{3} \mu_2 \end{bmatrix}, \;\; \beta_4 = \begin{bmatrix} \frac{2}{3} \mu_2^2 & 1 \\ -\frac{7}{12} \mu_5 \mu_2 \\ \frac{5}{3} \mu_8 & \frac{2}{3} \mu_5 \end{bmatrix}, \\ &\gamma_4 = \begin{bmatrix} -\frac{7}{12} \mu_2^2 \mu_3^2 + 9 \mu_2 \mu_{12} + \frac{5}{3} \mu_5 \mu_9 + \frac{11}{3} \mu_6 \mu_8 & \frac{2}{3} \mu_2 \mu_9 & -\frac{1}{3} \mu_2 \mu_8 \\ -\frac{1}{3} \mu_2 \mu_8 & \frac{4}{3} \mu_2 \mu_6 + \frac{4}{3} \mu_8 & -\frac{1}{2} \mu_5 \mu_2 \end{bmatrix}, \\ &\alpha_6 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \;\; \beta_6 = \begin{bmatrix} \mu_6 \\ \frac{1}{24} \mu_2^2 \mu_5 - \frac{5}{4} \mu_9 & -\frac{1}{4} \mu_5 \end{bmatrix}, \\ &\gamma_6 = \begin{bmatrix} \mu_6 \\ \frac{1}{24} \mu_2^2 \mu_5 - \frac{5}{4} \mu_9 & -\frac{1}{4} \mu_5 \\ \frac{1}{3} \mu_2 \mu_8 & \frac{5}{12} \mu_5^2 & -\frac{1}{6} \mu_5 \mu_2 \end{bmatrix}, \\ &\gamma_6 = \begin{bmatrix} 1 \\ \frac{1}{34} \mu_2^2 \mu_5 - \frac{5}{4} \mu_9 & -\frac{1}{4} \mu_5 \\ \frac{1}{3} \mu_2 \mu_8 - \frac{5}{12} \mu_2^2 \mu_5 - \frac{1}{2} \mu_9 & 2 \mu_8 \end{bmatrix}, \\ &\gamma_7 = \begin{bmatrix} 1 \\ 1 \\ 2 \mu_2 \mu_{12} + \frac{2}{3} \mu_5 \mu_9 - \mu_6 \mu_8 & \frac{2}{3} \mu_5 \mu_9 - \mu_6 \mu_8 & \frac{2}{3} \mu_5 \mu_8 \\ \frac{3}{3} \mu_2 \mu_9 - \frac{1}{2} \mu_5 \mu_9 - \mu_6 \mu_8 & \frac{2}{3} \mu_5 \mu_8 \\ \frac{2}{3} \mu_5 \mu_8 & -\frac{1}{6} \mu_5^2 + \frac{1}{6} \mu_2^2 \mu_6 - \frac{1}{6} \mu_5^2 + \frac{1}{6} \mu_2^2 \mu_6 - \frac{1}{3} \mu_2 \mu_8 \end{bmatrix}, \\ &\gamma_7 = \begin{bmatrix} 2 \mu_2 \mu_{12} + \frac{2}{3} \mu_5 \mu_9 - \mu_6 \mu_8 & \frac{2}{3} \mu_5 \mu_9 - \mu_6 \mu_8 & \frac{2}{3} \mu_5 \mu_8 \\ \frac{2}{3} \mu_5 \mu_8 & -\frac{1}{6} \mu_5^2 + \frac{1}{6} \mu_2^2 \mu_6 - \frac{1}{3} \mu_3 \mu_8 & 2 \mu_9 \end{bmatrix}, \\ &\gamma_7 = \begin{bmatrix} 2 \mu_5 \mu_5 - \frac{5}{3} \mu_5 \mu_5 - \frac{1}{3} \mu_5 \mu_6 - \frac{1}{6} \mu_5^2 + \frac{1}{6} \mu_2^2 \mu_6 - \frac{1}{3} \mu_2 \mu_8 - \frac{1}{15} \mu_2^2 \mu_5 - \frac{1}{15} \mu_2^2 \mu_5 - \frac{1}{15} \mu_2 \mu_5 \mu_8 \end{pmatrix}, \\ &\gamma_7 = \begin{bmatrix} 2 \mu_5 \mu_5 - \frac{5}{3} \mu_5 \mu_8 - \frac{5}{3} \mu_5 \mu_6 + \frac{1}{6} \mu_5^2 \mu_6 - \frac{1}{6} \mu_5^2 + \frac{1}{6} \mu_2^2 \mu_6 - \frac{1}{6} \mu_5^2 \mu_5 - \frac{1}{6} \mu_5^2 \mu_6 - \frac{1}{6} \mu_5^2 \mu_5 - \frac{1}{6} \mu_5^2 \mu_6 - \frac{1}{6} \mu_5^2 \mu_5 \mu_8 - \frac{1}{15} \mu_2 \mu_5 \mu_9 - \frac{1}{15} \mu_5 \mu_5 - \frac{1}{15} \mu_5 \mu_5 - \frac{1}{15} \mu_5 \mu_5 - \frac{1}{15} \mu_5 \mu_5 - \frac{1}{6} \mu_5^2 \mu_5 \mu_6 - \frac{1}{6} \mu_5^2 \mu_5 \mu_6 - \frac{1}{6} \mu_5^2 \mu_5 \mu_6 - \frac{1}{6} \mu_5^2 \mu_5 \mu_5 - \frac{1}{15} \mu_5 \mu_5 \mu_5 - \frac{1}{$$

³These should not be confused with the symplectic basis of cycles α_j and β_j in (4.2)

$$\begin{split} \alpha_{10} &= \begin{bmatrix} 1 \\ \frac{1}{3} \, \mu_{8} \end{bmatrix}, \; \beta_{10} = \begin{bmatrix} -\frac{1}{3} \, \mu_{2} \mu_{8} \\ \frac{1}{24} \, \mu_{2}^{2} \mu_{9} - \frac{5}{12} \, \mu_{5} \mu_{8} \\ \mu_{2} \mu_{12} - \frac{5}{12} \, \mu_{5} \mu_{9} + \frac{1}{3} \, \mu_{6} \mu_{8} & -\frac{1}{6} \, \mu_{2} \mu_{9} \end{bmatrix}, \\ \gamma_{10} &= \begin{bmatrix} \gamma_{10}^{[1,1]} & 2 \, \mu_{12} \mu_{5} - \frac{5}{6} \, \mu_{8} \mu_{9} & \frac{2}{3} \, \mu_{8}^{2} \\ 2 \, \mu_{12} \mu_{5} - \frac{5}{6} \, \mu_{8} \mu_{9} & 4 \, \mu_{2} \mu_{12} - \frac{1}{3} \, \mu_{5} \mu_{9} & -\frac{1}{6} \, \mu_{5} \mu_{8} + \frac{1}{12} \, \mu_{2}^{2} \mu_{9} \\ \frac{2}{3} \, \mu_{8}^{2} & -\frac{1}{6} \, \mu_{5} \mu_{8} + \frac{1}{12} \, \mu_{2}^{2} \mu_{9} & 3 \, \mu_{12} \end{bmatrix}, \\ \left(\gamma_{10}^{[1,1]} &= \frac{1}{24} \, \mu_{2}^{3} \, \mu_{5} \mu_{9} + \mu_{2}^{2} \, \mu_{8}^{2} - \frac{5}{12} \, \mu_{2} \mu_{5}^{2} \, \mu_{8} + 3 \, \mu_{2} \mu_{6} \mu_{12} - \frac{7}{6} \, \mu_{2} \mu_{9}^{2} \\ -\frac{5}{12} \, \mu_{5} \mu_{6} \mu_{9} + \frac{1}{3} \, \mu_{6}^{2} \, \mu_{8} + 9 \, \mu_{8} \mu_{12} \right). \end{split}$$

6.8. The sigma function for the (3, 4)-curve

Following [8] and from the conditions **IC1**, **IC2** of (5.59), but using the Hurwitz series form, the sigma function is of the form

$$\sigma(u_{5}, u_{2}, u_{1}) = \sum_{\ell, m, n_{2}, n_{5}, n_{6}, n_{8}, n_{9}, n_{12}} \left[b(\ell, m, n_{2}, n_{5}, n_{6}, n_{8}, n_{9}, n_{12}) u_{1}^{5} \left(\frac{u_{5}}{u_{1}^{5}} \right)^{\ell} \cdot \left(\frac{u_{2}}{u_{1}^{2}} \right)^{m} \left(\mu_{2} u_{1}^{2} \right)^{n_{2}} \left(\mu_{5} u_{1}^{5} \right)^{n_{5}} \left(\mu_{6} u_{1}^{6} \right)^{n_{6}} \left(\mu_{8} u_{1}^{8} \right)^{n_{8}} \left(\mu_{9} u_{1}^{9} \right)^{n_{9}} \left(\mu_{12} u_{1}^{12} \right)^{n_{12}} \left(\ell! \, m! \, (5 - 5\ell - 2m + 2n_{2} + 5n_{5} + 6n_{6} + 8n_{8} + 9n_{9} + 12n_{12})! \right) \right].$$

for the (3, 4)-curve. If we define

$$k = 5 - 5\ell - 2m + 2n_2 + 5n_5 + 6n_6 + 8n_8 + 9n_9 + 12n_{12}$$

we can rewrite the above expression as

$$\sigma(u_5, u_2, u_1) = \sum b(\ell, m, n_2, n_5, n_6, n_8, n_9, n_{12}) \cdot \frac{\mu_2^{n_2} \mu_5^{n_5} \mu_6^{n_6} \mu_8^{n_8} \mu_9^{n_9} \mu_{12}^{n_{12}} u_5^{\ell} u_2^{m} u_1^{k}}{\ell! \, m! \, k!},$$

where we require all the integer indices k, ℓ , m, n_2 , n_5 , n_6 , n_8 , n_9 , n_{12} to be non-negative. Note that the u-weight of this expression is $k_0 = 5 + 2n_2 + 5n_5 + 6n_6 + 8n_8 + 9n_9 + 10n_{12}$, which does not depend on ℓ or m. (Note also that $k = k_0 - 5\ell - 2m$.) For fixed n_2 , n_5 , n_8 , n_6 , n_9 , $n_{12} \ge 0$, $k_0 \ge 0$ is fixed, and for non-negative k, we require $\ell = 0, \ldots, \lfloor k_0/5 \rfloor$, $m = 0, \ldots, \lfloor (k_0 - 5\ell)/2 \rfloor$. In addition, we can use the condition that σ is an odd function, $\sigma(-u) = -\sigma(u)$; this tells us that if k_0 is even(odd) then we should restrict ourselves to m even(odd) respectively.

If we insert this ansatz into the equation for $(L_0 - H_0)\sigma = 0$, we get an expression which is identically zero, whatever the values for the $b(\ell, m, n_2, n_5, n_6, n_8, n_9, n_{12})$. If we insert the ansatz into the equation for $(L_3 - H_3)\sigma = 0$, we get (after some algebra) the recurrence relation shown below, involving 34 terms (compare the equations on p.68 of [8] for the genus 2 case). We can structure the relation by the *weight* of each *b* coefficient (more precisely by the weight of the corresponding term in the sigma expansion).

Contrarily to the (2, 3)-, (2, 5)-, (2, 7)-curves, we could not find any approach for the (3, 4)-curve to prove Hurwitz integrality of the expansion of $\sigma(u)$.

We call the recurrence relation, generated from $(L_3 - H_3)\sigma = 0$, R_3 :

$$\begin{aligned} +48m\ b(\ell+1,m-1,n_2,n_5,n_6,n_8,n_9,n_{12})\\ +48m\ b(\ell+1,m-1,n_2,n_5,n_6,n_8,n_9,n_{12})\\ =-12(4-k)(3-k)\ b(\ell,m,n_2,n_5-1,n_6,n_8,n_9,n_{12})\\ -36(n_8+1)\ b(\ell,m,n_2,n_5-1,n_6-1,n_8+1,n_9,n_{12})\\ +4(n_9+1)\ b(\ell,m,n_2-3,n_5,n_6-1,n_8,n_9+1,n_{12})\\ +2(n_{12}+1)\ b(\ell,m,n_2-3,n_5,n_6,n_8,n_9-1,n_{12}+1)\\ +4(n_5+1)\ b(\ell,m,n_2-4,n_5+1,n_6,n_8,n_9,n_{12})\\ -8(n_9+1)\ b(\ell,m,n_2-2,n_5,n_6,n_8-1,n_9+1,n_{12})\\ +2(n_8+1)\ b(\ell,m,n_2-3,n_5-1,n_6,n_8+1,n_9-1,n_{12})\\ -96(n_5+1)\ b(\ell,m,n_2-1,n_5+1,n_6-1,n_8,n_9,n_{12})\\ -12(n_8+1)\ b(\ell,m,n_2-1,n_5,n_6,n_8+1,n_9-1,n_{12})\\ -12(n_6+1)\ b(\ell,m,n_2-1,n_5-1,n_6,n_8-1,n_9,n_{12})\\ -4(n_{12}+1)\ b(\ell,m,n_2-1,n_5-1,n_6,n_8-1,n_9,n_{12})\\ -4(n_{12}+1)\ b(\ell,m,n_2-1,n_5-2,n_6,n_8,n_9+1,n_{12})\\ +120(n_2+1)\ b(\ell,m,n_2+1,n_5-1,n_6,n_8,n_9,n_{12})\\ -24m(3-k)\ b(\ell,m+1,n_2-1,n_5,n_6,n_8,n_9,n_{12})\\ -24m(3-k)\ b(\ell,m-1,n_2,n_5,n_6-1,n_8,n_9,n_{12})\\ -24m(3-k)\ b(\ell,m-1,n_2,n_5,n_6,n_8,n_9-1,n_{12})\\ +24\ell(3-k)\ b(\ell-1,m,n_2,n_5,n_6,n_8,n_9-1,n_{12})\\ +24\ell(3-k)\ b(\ell-1,m,n_2-1,n_5-1,n_6,n_8,n_9,n_{12})\\ +24\ell(3-k)\ b(\ell-1,m,n_2-1,n_5-1,n_6,n_8,n_9,n_{12})\\ +24\ell(3-k)\ b(\ell-1,m,n_2-1,n_5-1,n_6,n_8,n_9,n_{12})\\ +24\ell(\ell-1)\ b(\ell-2,m,n_2-4,n_5-1,n_6,n_8,n_9,n_{12})\\ +20\ell(\ell-1)\ b(\ell-2,m,n_2-1,n_5-1,n_6,n_8,n_9,n_{12})\\ +24\ell m\ b(\ell-1,m-1,n_2-2,n_5,n_6,n_8,n_9-1,n_{12})\\ +20\ell(\ell-1)\ b(\ell-2,m,n_2-1,n_5-1,n_6,n_8,n_9,n_{12})\\ +20\ell(\ell-1)\ b(\ell-2,m,n_2,n_5,n_6-1,n_8,n_9-1,n_{12})\\ +20\ell(\ell-1,m+1,n_2,n_5,n_6-1,n_8,n_9-1,n_{12})\\ +20\ell(\ell-1,m+1,n_2,n_5,n_6-1,n_$$

Note the two expressions on the left-hand side, which are the highest weight terms, at weight $W = 2n_2 + 5n_5 + 6n_6 + 8n_8 + 9n_9 + 12n_{12}$. The next highest weight term (underlined) is of weight W - 2, and the lowest weight terms are of weight W - 13. Putting the ansatz into the equation for $(L_4 - H_4)\sigma$ we get another recurrence with 27 terms, which we call R_4 :

$$-12 b(\ell, m+2, n_2, n_5, n_8, n_6, n_9, n_{12}) \\ + 24(4-k) b(\ell+1, m, n_2, n_5, n_6, n_8, n_9, n_{12}) \\ = 4 \frac{b(\ell, m, n_2-1, n_5, n_6, n_8, n_9, n_{12})}{+16\ell m b(\ell-1, m-1, n_2-1, n_5, n_6, n_8, n_9-1, n_{12})} \\ + 16\ell m b(\ell-1, m+1, n_2-1, n_5-1, n_6, n_8, n_9-1, n_{12}) \\ - 14\ell b(\ell-1, m+1, n_2-1, n_5-1, n_6, n_8, n_9, n_{12}) \\ + 40\ell b(\ell-1, m, n_2, n_5, n_6, n_8-1, n_9, n_{12}) \\ + 16m b(\ell, m-1, n_2, n_5-1, n_6, n_8, n_9, n_{12}) \\ - 7\ell(\ell-1) b(\ell-2, m, n_2-2, n_5-2, n_6, n_8, n_9, n_{12}) \\ + 108\ell(\ell-1) b(\ell-2, m, n_2-1, n_5, n_6, n_8, n_9, n_{12}-1) \\ + 44\ell(\ell-1) b(\ell-2, m, n_2, n_5, n_6-1, n_8, n_9, n_{12}) \\ + 12(5-k)(4-k) b(\ell, m, n_2, n_5, n_6-1, n_8, n_9, n_{12}) \\ + 8\ell(4-k) b(\ell-1, m, n_2-1, n_5, n_6, n_8-1, n_9, n_{12}) \\ + 20\ell(\ell-1) b(\ell-2, m, n_2, n_5, n_6, n_8+1, n_9, n_{12}-1) \\ - 288(n_8+1) b(\ell, m, n_2, n_5, n_6, n_8+1, n_9, n_{12}-1) \\ - 64(n_{12}+1) b(\ell, m, n_2, n_5, n_6, n_8-2, n_9, n_{12}+1) \\ - 40(n_6+1) b(\ell, m, n_2, n_5-2, n_6+1, n_8, n_9, n_{12}) \\ - 216(1+n_5) b(\ell, m, n_2, n_5+1, n_6, n_8, n_9-1, n_{12}) \\ - 80(n_6+1) b(\ell, m, n_2-1, n_5, n_6+1, n_8-1, n_9, n_{12}) \\ - 4(\ell-1-n_9-8n_5-2n_6+k+2m-2n_2) \\ b(\ell, m, n_2-2, n_5, n_6, n_8-1, n_9+1, n_{12}) \\ + 14(n_8+1) b(\ell, m, n_2-1, n_5-2, n_6, n_8+1, n_9, n_{12}) \\ + 14(n_1+1) b(\ell, m, n_2-1, n_5-1, n_6, n_8, n_9-1, n_{12}) \\ + 14(n_2+1) b(\ell, m, n_2-1, n_5-1, n_6, n_8, n_9-1, n_{12}) \\ + 16m(m-1) b(\ell, m, n_2+1, n_5, n_6-1, n_8, n_9, n_{12}) \\ + 16m(m-1) b(\ell, m-2, n_2-1, n_5, n_6-1, n_8, n_9, n_{12}) \\ + 16m(m-1) b(\ell, m-2, n_2-1, n_5, n_6-1, n_8, n_9, n_{12}).$$

As for R_3 , the two expressions on the left-hand side, are the highest weight terms, at weight $W = 2n_2 + 5n_5 + 6n_6 + 8n_8 + 9n_9 + 12n_{12}$. The next highest weight terms are of weight W - 2, and the lowest weight terms are of weight W - 14.

We see that the two recurrence relations have the same terms in b. Hence we can take linear combinations to get two relations, each with only one leading term at weight W

$$S_{3,4}: b(\ell, m, n_2, n_5, n_8, n_6, n_9, n_{12}) = \frac{1}{k - m + 1} \text{ (lower weight terms)} \quad (m \neq 0),$$

$$T_{3,4}: b(\ell, m, n_2, n_5, n_8, n_6, n_9, n_{12}) = \frac{1}{k - m} \text{ (lower weight terms)} \quad (l \neq 0).$$

These $S_{3,4}$ and $T_{3,4}$ connect the left-hand side with terms of relative weight -2 and lower, down to -14. In addition we have other relations from the equations $(L_6 - H_6)\sigma = 0$, $(L_7 - H_7)\sigma = 0$, and $(L_{10} - H_{10})\sigma = 0$ that

$$R_6$$
: $b(\ell, m, n_2, n_5, n_8, n_6, n_9, n_{12}) =$ "lower weight terms",
 R_7 : $b(\ell, m, n_2, n_5, n_8, n_6, n_9, n_{12}) =$ "lower weight terms",
 R_{10} : $b(\ell, m, n_2, n_5, n_8, n_6, n_9, n_{12}) =$ "lower weight terms",

respectively. Here the right-hand sides are linear in the coefficients b with coefficients at most quadratic in k, ℓ , m, n_2 , n_5 , n_8 , n_6 , n_9 , n_{12} over the rationals but each denominator is a divisor of 24.

 R_6 , R_7 , R_{10} have a total of 37, 47, 42 terms respectively and connect the left-hand side with terms of relative weight -5, -5, -8 and lower, down to -16, -17, -20 respectively.

Ideally, we would like to proceed as follows. Suppose we have already calculated the b coefficients at weight W-2. Then we would like to use one of the above to calculate each coefficient at weight W. We could proceed in this manner to calculate coefficients at successive weight levels to the required number of terms. However, this approach needs some modification. Recall that the weight does not depend on ℓ or m. Clearly if $\ell > 1$ we can use R_6 , and if $\ell = 1$, m > 0, we can use R_7 . Similarly if $\ell = 1$, k > 0, we can use R_6 . A short calculation shows that if $\ell = 1$, one of these two possibilities holds except in the special case $\ell = 1$, $m = n_2 = n_5 = n_8 = n_6 = n_9 = n_{12} = 0$ which is covered later. For the case $\ell = 0$ we cannot use R_6 , R_7 , R_{12} . If $m \neq 0$ and $m \neq (k+1)$ we can use $S_{3,4}$. All the possibilities considered so far will reduce the weight by 2. There remain the cases m = 0 and m = (k+1) to deal with.

The case $\ell = 0$, m = 0 is handled as follows. Take $48(k - m) T_{3.4}$:

$$48(m-k)b(\ell, m, n_2, n_5, n_6, n_8, n_9, n_{12})$$

$$= 8b(\ell-1, m, n_2-1, n_5, n_6, n_8, n_9, n_{12})$$

$$+ 12kb(\ell-1, m+2, n_2, n_5, n_6, n_8, n_9, n_{12}) + \cdots$$

Shifting by $n_2 \rightarrow n_2 + 1$, the first term in the right-hand side is expressed as

$$b(\ell - 1, m, n_2, n_5, n_6, n_8, n_9, n_{12})$$

$$= -6(m - k - 2) b(\ell, m, n_2 + 1, n_5, n_6, n_8, n_9, n_{12})$$

$$-\frac{3}{2}(k + 2) b(\ell - 1, m + 2, n_2, n_5, n_6, n_8, n_9, n_{12}) + \cdots$$

On the right-hand side, we now have two terms of non-negative relative weight as above of relative weight +2 which comes from the underlined term in R_3 and of relative weight 0 which comes from the underlined term in R_4 . Putting $\ell = 1$, m = 0, we have, say $T_{3,4}^{(0)}$, that

$$b(0, 0, n_2, n_5, n_6, n_8, n_9, n_{12})$$

$$= -6 (k - 3 + 5 \ell + 2 m) b(1, 0, n_2 + 1, n_5, n_6, n_8, n_9, n_{12})$$

$$-\frac{3}{2} (k - 3 + 5 \ell + 2 m) b(0, 2, n_2, n_5, n_6, n_8, n_9, n_{12}) + \cdots$$

The first term in the right-hand side has $\ell = 1$, m = 0, and $k = 5 + 2n_2 + ... > 0$. Hence, we can apply R_7 to this term to give a term with maximum relative weight +2 - 5 = -3. The second term has $\ell = 0$, m = 2, and $k = 1 + 2n_2 + 5n_5 + \cdots$ so k + 1 > 2 and hence $k + 1 \neq m$. For this term, we can apply $S_{3,4}$ to produce a term of maximum relative weight 0 - 2 = -2. Hence both terms of weight ≥ 0 can be

expressed as terms of relative weight ≤ -2 , so our chain eventually decreases in weight. The case $\ell = 0$, m = (k + 1) is treated as follows. Take R_3 , shift by $m \to m - 1$, and set $\ell = 0$ to get

$$R_3^{(0)}$$
: $b(0, m, n_2, n_5, n_6, n_8, n_9, n_{12})$
= $-2(m-1)b(1, m-2, n_2, n_5, n_6, n_8, n_9, n_{12}) +$ " lower weight terms".

Now the first term on the right, $b(1, m-2, n_2, n_5, n_6, n_8, n_9, n_{12})$, is of the same weight as the term on the left. Write this as

$$b(1, m', n_2, n_5, n_6, n_8, n_9, n_{12}),$$

with corresponding k-value k'. If $\min(k',m') < 0$ then this term is zero as discussed above. If k' = 0, m' = 0, it is easy to show that $m' = n_2 = n_5 = n_8 = n_6 = n_9 = n_{12} = 0$, and this term b(1,0,0,0,0,0,0,0,0) cannot be reduced further. Otherwise one or both of k' = 0, m' is positive, so we can apply R_7 or R_6 to reduce the term to terms of relative weight ≤ -2 , so our chain terminates or decreases in weight. These choices, plus the requirement discussed above that $b(\ell, m, n_2, n_5, n_6, n_8, n_9, n_{12}) = 0$ if any of the $\{k, \ell, m, n_2, n_5, n_6, n_8, n_9, n_{12}\}$ are negative, define all the $b(\ell, m, n_2, n_5, n_6, n_8, n_9, n_{12})$ in terms of the so-far undefined b(1, 0, 0, 0, 0, 0, 0, 0). Therefore the solution of the system

$$(L_i - H_i)\sigma(u) = 0$$
 $(j = 0, 3, 4, 6, 7, 10)$

is of dimension one. Choosing b(1, 0, 0, 0, 0, 0, 0, 0) = 1, we summarise with $k = 5 - 5\ell - 2m + 2n_2 + 5n_5 + 8n_8 + 6n_6 + 9n_9 + 12n_{12}$ as defined as above as follows:

$$b(\ell,m,n_2,n_5,n_8,n_6,n_9,n_{12}) =$$

$$= \begin{cases} 0 & \text{if } \min(k,\ell,m,n_2,n_5,n_6,n_8,n_9,n_{12}) < 0, \\ 1 & \text{if } \ell = 1, m = n_2 = n_5 = n_8 = n_6 = n_9 = n_{12} = 0, \\ \text{rhs}(R_{10}) & \text{if } \ell > 1, \\ \text{rhs}(R_7) & \text{if } \ell > 0, m > 0, \\ \text{rhs}(R_6) & \text{if } \ell > 0, k > 0, \\ \text{rhs}(S_{3,4}) & \text{if } \ell = 0, m \neq 0 \\ \text{and } m \neq (k+1), \end{cases}$$

$$\text{rhs}(T_{3,4}^{(0)}) & \text{if } l = m = 0, \\ \text{rhs}(R_3^{(0)}) & \text{if } \ell = 0 \\ \text{and } m = (k+1). \end{cases}$$

We have used this to calculate the terms in the sigma series up to weight 40 in $\{u_j\}$, or equivalently, weight 35 in the $\{\mu_i\}$. The first few terms of the sigma expansion are given as follows (up to a constant multiple):

$$\sigma(u_5, u_2, u_1) = u_5 + \frac{6 u_1^5}{5!} - 2 \frac{u_1 u_2^2}{2!} - 2\mu_2 \frac{u_1^3 u_2^2}{2! \cdot 3!} + 30\mu_2 \frac{u_1^7}{7!} - 2\mu_2^2 \frac{u_1 u_2^4}{4!}$$

$$-2\mu_2^2 \frac{u_1^5 u_2^2}{2! \cdot 5!} + 126\mu_2^2 \frac{u_1^9}{9!} + 24\mu_5 \frac{u_1^8 u_2}{8!} - \mu_5 \frac{u_5 u_2 u_1^3}{3!} + 8\mu_5 \frac{u_2^5}{5!}$$

$$-2\mu_6^2 \frac{2 u_5 u_2^2 u_1^2}{2! \cdot 2!} + 6\mu_6 \frac{u_5 u_1^6}{6!} + 24\mu_6 \frac{u_1^7 u_2^2}{2! \cdot 7!} - 2\mu_3^3 \frac{u_1^7 u_2^2}{2! \cdot 7!}$$

$$-2\mu_2^3 \frac{u_1^3 u_2^4}{4! \cdot 3!} + 432\mu_6 \frac{u_1^{11}}{11!} + 510\mu_2^3 \frac{u_1^{11}}{11!}$$

$$-\mu_2 \mu_5 u_1^5 \frac{u_5 u_2}{5!} - \mu_2 \mu_5 \frac{u_5 u_2^3 u_1}{3} + 288\mu_2 \mu_5 \frac{u_1^{10} u_2}{10!} + \cdots$$

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