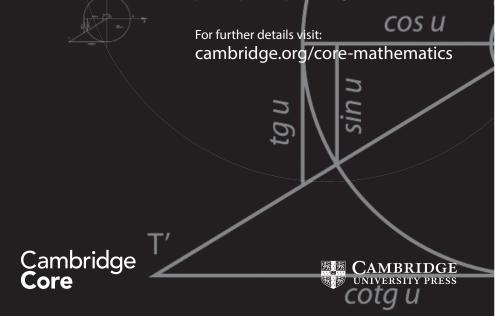
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## Ergodic theory and dynamical systems

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