How many tigers *Panthera tigris* are there in Huai Kha Khaeng Wildlife Sanctuary, Thailand? An estimate using photographic capture-recapture sampling

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Abstract We used capture-recapture analyses to estimate the density of a tiger *Panthera tigris* population in the tropical forests of Huai Kha Khaeng Wildlife Sanctuary, Thailand, from photographic capture histories of 15 distinct individuals. The closure test results (z = 0.39, P = 0.65) provided some evidence in support of the demographic closure assumption. Fit of eight plausible closed models to the data indicated more support for model M_h, which incorporates individual heterogeneity in capture probabilities. This model generated an average capture probabilities. This model generated an average capture probability $\hat{p} = 0.42$ and an abundance estimate of $\hat{N}(\hat{SE}[\hat{N}]) = 19$ (9.65) tigers. The sampled area of $\hat{A}(W)(\hat{SE}[\hat{A}(W)]) = 477.2$ (58.24) km² yielded a density estimate of $\hat{D}(\hat{SE}[\hat{D}]) = 3.98$ (0.51) tigers per 100 km². Huai Kha Khaeng Wildlife Sanctuary could therefore hold 113 tigers and the entire

Western Forest Complex *c*. 720 tigers. Although based on field protocols that constrained us to use sub-optimal analyses, this estimated tiger density is comparable to tiger densities in Indian reserves that support moderate prey abundances. However, tiger densities in wellprotected Indian reserves with high prey abundances are three times higher. If given adequate protection we believe that the Western Forest Complex of Thailand could potentially harbour >2,000 wild tigers, highlighting its importance for global tiger conservation. The monitoring approaches we recommend here would be useful for managing this tiger population.

Keywords Camera traps, capture-recapture models, *Panthera tigris*, population estimation, Thailand, tiger.

Introduction

The tiger *Panthera tigris* is categorized as Endangered on the IUCN Red List (IUCN, 2006) and during the past 3 decades substantial efforts have been invested in tiger conservation by governments and non-governmental agencies. However, these efforts are constrained by a lack of reliable data on the distribution as well as densities of wild tiger populations. Furthermore, dissemination of putative 'tiger numbers' (Jackson, 1993), often based on guesswork or demonstrably faulty methods (Karanth, 1987, 1988; Karanth *et al.*, 2003) masks a real scarcity of reliable data. Therefore, there is an urgent need

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to obtain reliable estimates of tiger densities at a large number of sites across the 1.2 million km^2 geographic range of the species (Seidensticker *et al.*, 1999).

Thailand is a key tiger range state, with 25% of its land area under forest cover, 16% of it being managed under wildlife and national park protection legislation (Pattanavibool & Dearden, 2002). In addition, increasing societal wealth and an official commitment to sciencebased tiger conservation (Tunhikorn et al., 2004) make Thailand a critical region for tiger conservation. Consequently, attempts have been made to map accurately the distribution of tiger populations in Thailand from field surveys (Rabinowitz, 1993, 1999; Smith et al., 1999; Tunhikorn et al., 2004; WEFCOM, 2004). However, to use such maps for managing wild tiger populations there is an additional need to estimate densities and sizes of individual tiger populations at specific sites. This critical need has been enunciated in Thailand's national action plan for tigers (Tunhikorn et al., 2004). The national plan also identifies the 18,000 km² Western Forest Complex, which contains 17 protected areas, including Huai Kha Khaeng Wildlife Sanctuary, as the most important tiger conservation area in the country.

Although reliable estimation of tiger abundance is difficult because of their elusive behaviour and naturally low densities, recent development of automated camera traps and their application within a formal framework of capture-recapture population sampling (see Karanth et al., 2004b, for a review) have enabled investigators to obtain rigorous density estimates in India (Karanth & Nichols, 1998; Karanth et al., 2004a,c), Nepal (Wegge et al., 2004), Malaysia (Kawanishi & Sunquist, 2004) and Indonesia (O'Brien et al., 2003). Unlike previous tiger monitoring approaches based on footprint total counts (Panwar, 1980), radio-telemetry (Sunquist, 1981; Smith, 1993) or raw photographic trapping rates (Carbone et al., 2001), capture-recapture methods can effectively deal with the typical inability of surveys to detect all individual tigers present in an area (i.e. detection probability P <1; Williams et al., 2002). Photographic capturerecapture sample surveys of tigers conducted in habitats ranging from evergreen, semi-deciduous and deciduous forests to alluvial grasslands (O'Brien et al., 2003; Karanth et al., 2004a; Kawanishi & Sunquist, 2004; Wegge et al., 2004) show that reliable estimates can be generated at relatively low densities of 2-3 tigers per 100 km², although their variances tend to be large because of the small number of traps typically deployed in such studies. A recent study (Karanth et al., 2006) that integrated photo-capture data across space and time employing the Robust Design (Pollock et al., 1990; Lebreton et al., 1992; Kendall et al., 1997; Williams et al., 2002) demonstrated the power of capture-recapture analyses to detect changes in the temporal dynamics of a tiger population.

However, prior to this study, there has not been an estimate of tiger abundance in Thailand based on capture-recapture analyses. Here we present the results of a post hoc capture-recapture analysis of camera trap survey data collected in Huai Kha Khaeng Wildlife Sanctuary during 2004-2005. The objectives of our analysis were to: (1) Assess the potential for employing camera trap surveys in the semi-deciduous forests that form a large proportion of tiger habitat in Thailand (Tunhikorn et al., 2004). (2) Analyse the tiger photocapture data in a formal capture-recapture sampling framework (Otis et al., 1978; White et al., 1982; Williams et al., 2002) to generate estimates of capture probability, population size, effectively sampled area and tiger density based on survey protocols developed in India (Karanth et al., 2002; Nichols & Karanth, 2002). (3) Assess whether tiger densities in Huai Kha Khaeng are comparable to densities recorded in ecologically similar semi-deciduous forest sites in India (Karanth et al., 2004c). (4) Examine the general implications of our results for understanding tiger ecology and monitoring wild tiger populations in Thailand.

Study area

This study was carried out in the forests around Khao Nang Rum research station within the $2,780 \text{ km}^2$ Huai

Kha Khaeng Wildlife Sanctuary (Fig. 1). The area is rugged and hilly over altitudes of 200-1,600 m, has an annual temperature range of 10-35°C and annual precipitation of *c*. 1,500 mm. It supports four vegetation types: dry deciduous dipterocarp forests, mixed deciduous forest, dry evergreen forest, and hill evergreen forest, depending on rainfall patterns and edaphic factors (Srikosamatara, 1993; Tunhikorn *et al.*, 2004; WEFCOM, 2004). From earlier food habit studies in the area (Petdee, 2000), principal prey species of tigers are wild pig *Sus scrofa*, sambar *Cervus unicolor*, common muntjac *Muntiacus muntjac*, banteng *Bos javanicus* and gaur *Bos frontalis*. Other potential tiger prey include wild buffalo *Bubalus bubalis* and Malayan tapir *Tapirus indicus*.

Methods

Field methods

The original goal was to document the presence of tigers and other mammals in the area using camera-trap techniques. Therefore, trapping was done on an ad hoc basis without employing recommended survey protocols (Karanth *et al.*, 2002; Nichols & Karanth, 2002). Twelve Trailmaster (Goodson & Associates, Lenexa, USA) and 10 CamTrakker (CamTrakker, Georgia, USA) units were deployed to cover a 211 km² area using 103 trap locations (Fig. 1).

Trapping was carried out from 9 February 2004 to 1 February 2005 using 14 clusters of trap locations. These clusters are analogous to trapping blocks (Nichols & Karanth, 2002), with each block consisting of *c*. seven trap locations. The sampling effort varied among blocks: eight locations were trapped for >20 days, 49 locations for 16-19 days, 12 locations for *c*. 15 days and the remaining 34 locations were trapped for <15 days. On average there were *c*. 15 trap-days at each location, and this trapping effort was uniform across the study area. The moving of traps among blocks did not follow a strict pre-designed sequence and was driven by logistics as well as opportunities for setting traps at tiger kill sites. However, in combination, data from all these blocks covered the area evenly (Fig. 1).

Of particular concern for the analysis was the long survey duration of 12 months, resulting in the possibility of the sampled tiger population being demographically open (Otis *et al.*, 1978). Given the high turnover of individuals in tiger populations (Karanth *et al.*, 2006), such lack of closure could bias estimates of population size. However, the following aspects of the survey encouraged us to attempt a post-hoc statistical analysis of these data under a formal capture-recapture sampling framework: (1) There were two opposing cameras at each trap location, at a distance of *c*. 3-5 m from the

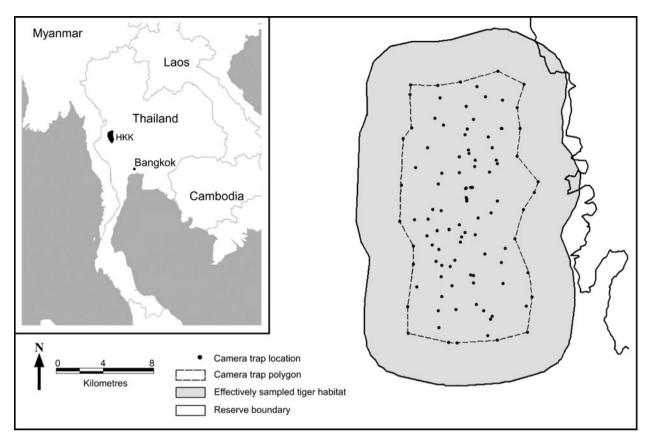


Fig. 1 The Khao Nang Rum camera-trap survey area in Huai Kha Khaeng Wildlife Sanctuary. Inset shows the Sanctuary's location (HKK) in Thailand.

anticipated path of moving tigers at *c*. 45 cm height, which obtained good photographs of both flanks, enabling unambiguous identification of individuals. (2) The camera trap locations were selected based on signs of past tiger activity to maximize capture probabilities, resulting in a relatively large number (n = 17) of individual tigers being photo-captured. (3) The maximum spacing between any two trap locations was <2.3 km, thus ensuring that there were no holes in the sampled area and that every tiger in the sampled population had a non-zero probability of being photo-captured during each sampling occasion.

Analysis

Given the potential for lack of demographic closure (Karanth *et al.*, 2002; Williams *et al.*, 2002) in the data we would have preferred to use open model analyses (Karanth *et al.*, 2006). However, the lack of simultaneous natural temporal coverage of the entire survey area (because we had to construct our sampling occasions as described above) precluded this option. Therefore, we constructed closed model capture histories following survey design 4 of Nichols & Karanth (2002), ensuring

that capture data from well spaced locations were included in every sampling occasion. We constructed five sampling occasions based on the calendar dates on which each location was trapped (Otis *et al.*, 1978; Karanth & Nichols, 1998). Because of low capture rates, tiger photo-capture data from three successive calendar dates at each trapping location were combined before being assigned to a specific sampling occasion. We thus ensured that equal trapping effort was expended and the entire area was sampled during each of the sampling occasions.

The individual tiger capture histories in the standard X-matrix format (Otis *et al.*, 1978; White *et al.*, 1982) were analysed using models developed for closed populations (Otis *et al.*, 1978; White *et al.*, 1982) implemented in the software *CAPTURE* (Rexstad & Burnham, 1991). We tested the population closure assumption against our data. The closure test (Otis *et al.*, 1978; White *et al.*, 1978; White *et al.*, 1982) implemented in *CAPTURE* is based on the number of sample periods separating the times of first and last capture for each animal caught at least twice. If animals are entering and/or leaving the sampled population during the survey period, the time between first and last captures should be shorter on average than if all animals were present during the entire survey period.

The capture-recapture models implemented in *CAP*-*TURE* consider potential effects of behavioural response of tigers to camera trapping (e.g. trap-avoidance: model M_b), time-specific variation (e.g. weather changes over the 3-day sampling occasions: model M_t), and heterogeneity among individual animals (e.g. caused by factors such as territorial status or trap access: model M_h), as well as more complex models such as M_{bh} , M_{th} , M_{tb} and M_{tbh} that incorporate occurrence of the effects of heterogeneity, trap response and time in different combinations.

We fitted the null model M_0 and each of the above seven models to our data using *CAPTURE* (Rexstad & Burnham, 1991) and examined results of goodness-of-fit and betweenmodel tests, and the overall discriminant function, to guide the selection of an appropriate model for the data. The selected model was then used for estimating capture probabilities \hat{p} and abundance \hat{N} . We estimated the effectively sampled area using an approach evaluated by Wilson & Anderson (1985), and computed tiger densities by dividing the population size by the sampled area. This computational approach is fully described elsewhere (Karanth & Nichols, 1998; Nichols & Karanth, 2002).

Results

Photographic captures of tigers

In a total sampling effort of 1,509 trap-days we obtained 124 tiger photographs (59 right flanks, 57 left flanks, four frontal, four rear) of 15 individual tigers judged to be >12 months of age (10 females, four males, one of unknown sex). Individual tigers could be clearly identified from stripe patterns (Karanth *et al.*, 2002) and were given unique identification numbers (HKT-101-HKT-117). We obtained both left and right profile photos for 12 individuals, and three more animals were identified from only left profiles. Capture data for two cubs were excluded from the analysis.

The capture histories generated from the field survey (Table 1) show that the number of individuals caught was small ($M_{t+1} = 15$), as expected in a low to medium density tiger population (Karanth *et al.*, 2004c). Four animals were caught in all five sampling occasions, one was caught in four occasions, two animals were caught thrice, two others twice and six individual tigers were caught only once. We expected this low recapture rate for several individuals to induce substantial uncertainty in our estimates.

Estimates of effectively sampled area

The polygon formed by the outer-most camera traps (Fig. 1) was 211 km^2 . For the 10 individual tigers that were caught more than once, the maximum distance

 Table 1
 Capture histories of tigers photo-trapped in Huai Kha

 Khaeng Wildlife Sanctuary, Thailand, during 2004-2005.

	Sampling occasion					
Identification no.	1	2	3	4	5	Age/sex*
HKT-101	1	1	1	1	1	F
HKT-102	1	0	1	1	1	F
HKT-103	1	0	1	0	1	F
HKT-104	1	1	1	1	1	F
HKT-105	1	1	1	1	1	F
HKT-106	1	1	1	1	1	М
HKT-107	0	0	0	1	1	М
HKT-108	0	1	0	1	1	F
HKT-109	1	0	0	0	0	F
HKT-110	0	0	1	0	0	М
HKT-111	0	0	0	0	1	F
HKT-112	0	1	0	0	0	U
HKT-113	0	0	1	0	0	F
HKT-115	1	1	0	0	0	С
HKT-116	0	1	0	0	0	С
HKT-114	0	0	0	0	1	М
HKT-117	1	0	1	0	0	F

*F, female >12 months; M, male >12 months; U, unknown sex >12 months; C, cubs <12 months (not included in the capture-recapture analysis).

between photo-captures was 0.90-16.05 km, with a mean value of 7.11 km. Using the approach described more fully elsewhere (Karanth & Nichols, 1998; Nichols & Karanth, 2002), we estimated the effectively sampled area as $\hat{A}(W)(\hat{SE}[\hat{A}(W)]) = 477.2$ (58.24) km².

Tests for population closure and model selection

The statistical test for population closure implemented in *CAPTURE* (Rexstad & Burnham, 1991) was consistent with the assumption that our tiger population was closed during the survey period (z = 0.39, P = 0.65). Because of the long (12 months) survey period, we would have liked to consider open models as well but the ad hoc field sampling design precluded this possibility. We assumed that our data supported the closure assumption, albeit not strongly.

The test for presence of individual heterogeneity in capture probabilities showed that the null model M_0 was rejected in favour of the model incorporating heterogeneity M_h ($\chi^2 = 10.07$, df = 1, P <0.002). The goodness-of-fit test results for models M_h and M_b (incorporating trapresponse behaviour) provided no evidence of lack of fit ($\chi^2 = 3.85$, df = 4, P = 0.43 and $\chi^2 = 2.57$, df = 4, P = 0.64, respectively). The tests also did not reject the null model M_0 in favour of alternative models M_b ($\chi^2 = 0.77$, df = 1, P = 0.38) or M_t (time-specific variation in capture probabilities; $\chi^2 = 2.86$, df = 4, P = 0.58). Model M_{bbr} , which accommodates heterogeneity as well as

trap response was not favoured over the more parsimonious M_h model ($\chi^2 = 0.67$, df = 2, P = 0.72).

The overall discriminant function model selection algorithm in CAPTURE (Rexstad & Burnham, 1991) scored the competing models as: $M_0 = 0.88$, $M_h = 1.00$, $M_b = 0.38, M_{bh} = 0.57, M_t = 0.0, M_{th} = 0.41, M_{tb} =$ 0.37, $M_{tbh} = 0.64$. The higher scoring model M_h is more likely to have generated the observed capture history data in comparison to lower scoring models. This choice of model M_b in statistical tests reported above is consistent with past results (Karanth et al., 2004c) as well as aspects of tiger biology. Resident breeding tigers maintain home ranges that overlap between the sexes. Additionally, some individuals in the population are nonbreeding 'floaters', which may not have stable home ranges (Sunquist, 1981; Smith, 1993; Karanth & Sunquist, 2000). These space use patterns, as well as location of our camera traps in relation to home ranges of individuals, were likely to induce differences in capture probabilities among individual tigers.

Estimates of capture probability, tiger population size and density

The tiger capture histories (Table 1) were used to generate parameter estimates under model M_h using the jackknife estimator (Burnham & Overton, 1978; Otis *et al.*, 1978) implemented in *CAPTURE*, which performed well in earlier photographic capture studies of tigers (Karanth & Nichols, 1998; Karanth *et al.*, 2004c). The estimated average capture probability per sampling occasion (\hat{p}) was 0.42. The total population size estimate (\hat{N}) was 19 tigers with a standard error ($\hat{SE}[\hat{N}]$) of 3.9 tigers. Based on the sampled area $\hat{A}(W)(\hat{SE}[\hat{A}(W)]) = 477.2$ (58.24) km², the estimated density of tigers in the area was $\hat{D}(\hat{SE}[\hat{D}]) = 3.98$ (0.51) tigers per 100 km². These estimates exclude cubs <12 months in age, which generally comprise 20-25% of wild tiger populations (Smith, 1993; Kenny *et al.*, 1995).

Discussion

We have demonstrated in this study that non-invasive photographic sampling is a potentially useful method for estimating densities of tigers in the tropical forests of the Western Forest Complex in Thailand and therefore probably for other similar areas in South-east Asia. Ecological factors, such as climate, topography and present tiger density levels permit the application of this method. The overall probability of capturing a tiger present in the sampled area during the entire survey ($M_{t+1}/\hat{N} = 0.79$) was <1. Therefore, it is critical to use the capture-recapture sampling-based approach (Williams *et al.*, 2002) to deal with the fact that not all tigers present in the study area are likely to be detected.

Based on comparisons of this ad hoc study with earlier surveys in India that employed more rigorous field protocols (Karanth et al., 2002; Nichols & Karanth, 2002), we recommend the following modifications to future camera trap studies of tigers in the area: (1) The number of camera traps employed in this study was small (10-15). To improve robustness of the statistical inferences of tiger abundance we recommend deployment of at least 40-50 traps, so that the sampled area, the potential number of tiger-exposed traps, and recapture rates can all be increased. (2) The camera trap survey duration should be shorter, preferably <6 weeks, to avoid potential violation of population closure assumptions. Furthermore, a pre-designed field survey protocol (Nichols & Karanth, 2002), which can generate data amenable to straightforward construction of capture histories, should be employed. A larger number of traps would make it easier to implement such a survey design. (3) It would be useful to sample this tiger population photographically on an annual basis to estimate its size and density, as well as other parameters such as longer term rates of survival, recruitment, and permanent and temporary emigration. Robust Design and other recent refinements in capture-recapture analyses (Pollock et al., 1990; Lebreton et al., 1992; Kendall et al., 1997; Williams et al., 2002) facilitate such analyses (Karanth et al., 2006). Reliable monitoring of the responses of tiger population dynamics to threats and conservation interventions can be an effective component of long-term adaptive management.

The observed mean density of *c*. 4 tigers per 100 km² in this study was comparable to the density of 3.3-7.3 tigers per 100 km² measured in ecologically similar disturbed semi-deciduous forests such as Tadoba, Bhadra, Melghat, Pench and Panna reserves in India (Karanth *et al.*, 2004c). However, better protected Indian reserves that are ecologically comparable to Huai Kha Khaeng, such as Kanha, Bandipur and Nagarahole, support tiger densities that are thrice as high (*c*. 12 tigers per 100 km²). The Huai Kha Khaeng landscape lacks an abundant, social cervid such as the chital *Axis axis* that accounts for 13-95% of prey numbers recorded in Indian reserves. However, Eld's deer *Cervus eldi*, which was extirpated from Huai Kha Khaeng in historical times, is such a species.

Our study area of 477 km² around Khao Nang Rum research station forms 17% of the area of Huai Kha Khaeng Wildlife Sanctuary and 2.7% of the Western Forest Complex. Prima facie, this area appears to support low densities of ungulate prey (Srikosamatara, 1993), and consequently a relatively low density of c. 4 tigers per 100 km². If the entire landscape surrounding Khao Nang Rum research station supports comparable tiger densities, Huai Kha Khaeng Sanctuary could hold

113 tigers, and the entire Western Forest Complex *c*. 720 tigers.

Given the similarity of vegetation types, climate and prey composition between semi-deciduous forests of India and Thailand, their ecological productivities should be comparable. Furthermore, given the similarity in composition of their ungulate prey assemblages, potential maximum prey densities and hence tiger densities should also be similar. Based on tiger density data from well protected Indian reserves (Karanth et al., 2004c), we speculate that Huai Kha Khaeng Sanctuary could potentially hold 338 tigers, and the entire Western Forest Complex >2,000 tigers, highlighting the importance of this area for global tiger conservation. Major new conservation initiatives followed on from this study, in particular improved law enforcement under the joint initiatives of the Thailand government and the Wildlife Conservation Society, and we have also implemented an improved camera-trap monitoring system that employs standard closed model photographic capture-recapture sampling of <60 days duration (Karanth et al., 2002) using 136 trap sites to sample effectively an area of 1,260 km².

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